Nonlinear Functional Analysis and Applications
Vol. 22, No. 5 (2017), pp. 983-999
ISSN: 1229-1595(print), 2466-0973(online)
http://nfaa.kyungnam.ac.kr/journal-nfaa
Copyright © 2017 Kyungnam University Press

# ON A $M$-ORDER NONLINEAR INTEGRODIFFERENTIAL EQUATION ON TWO VARIABLES 

Huynh Thi Hoang Dung ${ }^{1}$, Pham Hong Danh ${ }^{2}$, Le Thi Phuong Ngoc ${ }^{3}$ and Nguyen Thanh Long ${ }^{4}$<br>${ }^{1}$ Department of Mathematics<br>University of Architecture of Ho Chi Minh City<br>196 Pasteur Str., Dist. 3, Ho Chi Minh City, Vietnam<br>Department of Mathematics and Computer Science<br>VNUHCM - University of Science<br>227 Nguyen Van Cu Str., Dist. 5, HoChiMinh City, Vietnam<br>e-mail: dunghth1980@gmail.com<br>${ }^{2}$ Department of Mathematics University of Economics of Ho Chi Minh City 59C Nguyen Dinh Chieu Str., Dist. 3, Ho Chi Minh City, Vietnam<br>Department of Mathematics and Computer Science VNUHCM - University of Science<br>227 Nguyen Van Cu Str., Dist. 5, HoChiMinh City, Vietnam<br>e-mail: hongdanh282@gmail.com<br>${ }^{3}$ University of Khanh Hoa<br>01 Nguyen Chanh Str., Nha Trang City, Vietnam<br>e-mail: ngoc1966@gmail.com<br>${ }^{4}$ Department of Mathematics and Computer Science<br>VNUHCM - University of Science<br>227 Nguyen Van Cu Str., Dist. 5, Ho Chi Minh City, Vietnam<br>e-mail: longnt2@gmail.com

Dedicated to Professor Jong Kyu Kim on the occasion of his retirement


#### Abstract

In this paper, we study the existence and the compactness of the set of solutions for m-order nonlinear integrodifferential equation on two variables. The main tools are the


[^0]fixed point theorems together with the definition of a suitable Banach space and appropriate conditions for subsets to be relatively compact in this space. Two illustrative examples are given.

## 1. Introduction

In this paper, we consider the following m-order nonlinear integrodifferential equation in two variables

$$
\begin{equation*}
u(x, y)=g(x, y)+\iint_{\Omega} K\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right) d s d t \tag{1.1}
\end{equation*}
$$

where $(x, y) \in \Omega=[0,1] \times[0,1]$ and $g: \Omega \rightarrow \mathbb{R}, K: \Omega \times \Omega \times \mathbb{R}^{m+1} \rightarrow \mathbb{R}$ are given functions. Denote by $D_{1}^{i} u=\frac{\partial^{i} u}{\partial x^{i}}$, the partial derivative of order $i=1, \ldots, m$ of a function $u$ defined on $\Omega$, with respect to the first variable.

It is well known that integral and integrodifferential equations have attracted the interest of scientists not only because of their major role in the fields of functional analysis but also because of their important role in numerous applications, for example, mechanics, physics, population dynamics, economics and other fields of science, see Corduneanu [8], Deimling [9].

There are many different methods to solve the integral and integrodifferential equations (see, for example, see [1]-[23] and the references given therein). In [3], his homotopy perturbation method was applied to solve linear and nonlinear systems of integro-differential equations. In [20], based on the applications of the well-known Banach fixed point theorem coupled with Bielecki type norm and a certain integral inequality with explicit estimate, Pachpatte proved uniqueness and other properties of solutions of the following Fredholm type integrodifferential equation

$$
x(t)=g(t)+\int_{a}^{b} f\left(t, s, x(s), x^{\prime}(s), \ldots, x^{(n-1)}(s)\right) d s, t \in[a, b],
$$

where $x, g, f$ are real valued functions and $n \geq 2$ is an integer. With the same methods, Pachpatte studied the existence, uniqueness and some basic properties of solutions of the Fredholm type integral equation in two variables as follows (see [21]):

$$
u(x, y)=f(x, y)+\int_{0}^{a} \int_{0}^{b} g\left(x, y, s, t, u(s, t), D_{1} u(s, t), D_{2} u(s, t)\right) d t d s
$$

Abdou et al. also considered the existence of integrable solution of nonlinear integral equation, of type Hammerstein-Volterra of the second kind, by using the technique of measure of weak noncompactness and Schauder fixed point theorem (see [2]).

Recently, in [10]-[12], [15]-[19], using tools of functional analysis and a fixed point theorem of Krasnosel'skii type, we have investigated solvability and asymptotically stable of nonlinear functional integral equations on one variable or two variables, or $N$ variables.

In the base of the above works, we consider (1.1). This paper is organized as follows. In section 2, we present some preliminaries. It consists of the definition of a suitable Banach space and a sufficient condition for relatively compact subsets. In section 3, by applying the Banach theorem and the Schauder theorem, we prove two existence theorems. Furthermore, the compactness of solutions set is also proved. In order to illustrate the results obtained here, two examples are given.

## 2. Preliminaries

First, we construct an appropriate Banach space for (1.1) as follows. By $X=C(\Omega ; \mathbb{R})$, we denote the space of all continuous functions from $\Omega$ into $\mathbb{R}$ equipped with the following norm

$$
\begin{equation*}
\|u\|_{X}=\sup _{(x, y) \in \Omega}|u(x, y)|, u \in X \tag{2.1}
\end{equation*}
$$

Put

$$
\begin{equation*}
X_{m}=\left\{u \in X=C(\Omega ; \mathbb{R}): D_{1}^{i} u \in X, i=1,2, \ldots, m\right\} \tag{2.2}
\end{equation*}
$$

We remark that

$$
C^{1}(\Omega ; \mathbb{R}) \backslash X_{m} \neq \phi, \quad X_{m} \backslash C^{1}(\Omega ; \mathbb{R}) \neq \phi, \quad X_{m} \cap C^{1}(\Omega ; \mathbb{R}) \neq \phi
$$

for all $m=2,3, \ldots$
Indeed,
(i) We have $u=u(x, y)=\left|x-\frac{1}{2}\right|\left(x-\frac{1}{2}\right)\left|y-\frac{1}{3}\right|\left(y-\frac{1}{3}\right) \in C^{1}(\Omega ; \mathbb{R})$, but $u \notin X_{m}$.
(ii) We also have $v=v(x, y)=x^{m+1}\left|y-\frac{1}{3}\right| \in X_{m}$, but $v \notin C^{1}(\Omega ; \mathbb{R})$.
(iii) With $w(x, y)=e^{x+y}$, we have $w \in X_{m} \cap C^{1}(\Omega ; \mathbb{R})$, so

$$
X_{m} \cap C^{1}(\Omega ; \mathbb{R}) \neq \phi
$$

We shall need the following lemma, the proof of which can be found in $[10$, p.266-267].

Lemma 2.1. ([10]) $X_{m}$ is a Banach space with the norm defined by

$$
\begin{equation*}
\|u\|_{X_{m}}=\|u\|_{X}+\sum_{i=1}^{m}\left\|D_{1}^{i} u\right\|_{X}, u \in X_{m} \tag{2.3}
\end{equation*}
$$

Next, we give a sufficient condition for relatively compact subsets of $X_{m}$.

Lemma 2.2. Let $\mathcal{F} \subset X_{m}$. Then $\mathcal{F}$ is relatively compact in $X_{m}$ if and only if the following conditions are satisfied
(i) $\exists M>0:\|u\|_{X_{m}} \leq M, \forall u \in \mathcal{F}$;
(ii) $\forall \varepsilon>0, \exists \delta>0: \forall(x, y),(\bar{x}, \bar{y}) \in \Omega$,

$$
\begin{equation*}
|x-\bar{x}|+|y-\bar{y}|<\delta \quad \Longrightarrow \quad \sup _{u \in \mathcal{F}}[u(x, y)-u(\bar{x}, \bar{y})]_{*}<\varepsilon \tag{2.4}
\end{equation*}
$$

where we denote $[u(x, y)]_{*}=|u(x, y)|+\sum_{i=1}^{m}\left|D_{1}^{i} u(x, y)\right|$.
Proof. Let $\mathcal{F}$ be relatively compact in $X_{m}$. Then $\mathcal{F}$ is bounded, so (2.4) (i) is true. Now, we show that (2.4) (ii) is also true.

For every $\varepsilon>0$, considering a collection of open balls in $X_{m}$, with center at $u \in \mathcal{F}$ and radius $\frac{\varepsilon}{3}$, as follows

$$
B\left(u, \frac{\varepsilon}{3}\right)=\left\{\bar{u} \in X_{m}:\|u-\bar{u}\|_{X_{m}}<\frac{\varepsilon}{3}\right\}, u \in \mathcal{F} .
$$

It is clear that $\overline{\mathcal{F}} \subset \bigcup_{u \in \mathcal{F}} B\left(u, \frac{\varepsilon}{3}\right)$. Because $\overline{\mathcal{F}}$ compact in $X_{m}$, the open cover $\bigcup_{u \in \mathcal{F}} B\left(u, \frac{\varepsilon}{3}\right)$ of $\overline{\mathcal{F}}$ contains a finite subcover, so there are $u_{1}, \ldots, u_{q} \in \mathcal{F}$ such that

$$
\overline{\mathcal{F}} \subset \bigcup_{j=1}^{q} B\left(u_{j}, \frac{\varepsilon}{3}\right) .
$$

By the functions $u_{j}, D_{1}^{i} u_{j}, i=1, \ldots, m, j=1, \ldots, q$ are uniformly continuous on $\Omega$, there exists $\delta>0$ such that, for all $(x, y),(\bar{x}, \bar{y}) \in \Omega,|x-\bar{x}|+|y-\bar{y}|<\delta$, we have

$$
\left[u_{j}(x, y)-u_{j}(\bar{x}, \bar{y})\right]_{*}<\frac{\varepsilon}{3}, \forall j=1, \ldots, q .
$$

For all $u \in \mathcal{F}, u \in B\left(u_{j}, \frac{\varepsilon}{3}\right)$ for some $j=1, \ldots, q$. Thus, for all $(x, y),(\bar{x}, \bar{y}) \in \Omega$, if $|x-\bar{x}|+|y-\bar{y}|<\delta$ then we obtain

$$
\begin{aligned}
{[u(x, y)-u(\bar{x}, \bar{y})]_{*} \leq } & {\left[u(x, y)-u_{j}(x, y)\right]_{*}+\left[u_{j}(x, y)-u_{j}(\bar{x}, \bar{y})\right]_{*} } \\
& +\left[u_{j}(\bar{x}, \bar{y})-u(\bar{x}, \bar{y})\right]_{*} \\
\leq & 2\left\|u-u_{j}\right\|_{X_{m}}+\left[u_{j}(x, y)-u_{j}(\bar{x}, \bar{y})\right]_{*} \\
< & \frac{2 \varepsilon}{3}+\frac{\varepsilon}{3}=\varepsilon .
\end{aligned}
$$

It implies that (2.4) (ii) is true.
Conversely, suppose that the conditions (i), (ii) hold. To prove that $\mathcal{F}$ is relatively compact in $X_{m}$, let $\left\{u_{p}\right\}$ be a sequence in $\mathcal{F}$, we show that $\left\{u_{p}\right\}$ contains a convergent subsequence. By (2.4), $\mathcal{F}_{1}=\left\{u_{p}: p \in \mathbb{N}\right\}$ and $\mathcal{F}_{2}^{i}=$ $\left\{D_{1}^{i} u_{p}: p \in \mathbb{N}\right\}$ are uniformly bounded and equicontinuous in $X$. Applying
the Ascoli-Arzela theorem to $\mathcal{F}_{1}$, it is relatively compact in $X$, so there exists a subsequence $\left\{u_{p_{k}}\right\}$ of $\left\{u_{p}\right\}$ and $u \in X$ such that

$$
\left\|u_{p_{k}}-u\right\|_{X} \rightarrow 0, \text { as } k \rightarrow \infty .
$$

Note that $\left\{D_{1}^{i} u_{p_{k}}: k \in \mathbb{N}\right\} \subset \mathcal{F}_{2}^{i}$ is also uniformly bounded and equicontinuous in $X$, so it is also relatively compact in $X$. We obtain the existence of a subsequence of $\left\{D_{1}^{i} u_{p_{k}}\right\}$, denoted by the same symbol, and $w^{(i)} \in X$, such that

$$
\left\|D_{1}^{i} u_{p_{k}}-w^{(i)}\right\|_{X} \rightarrow 0, \text { as } k \rightarrow \infty
$$

Since

$$
u_{p_{k}}(x, y)-u_{p_{k}}(0, y)=\int_{0}^{x} D_{1} u_{p_{k}}(s, y) d s, \forall(x, y) \in \Omega
$$

furthermore $\left\|u_{p_{k}}-u\right\|_{X} \rightarrow 0$ and $\left\|D_{1} u_{p_{k}}-w^{(1)}\right\|_{X} \rightarrow 0$, we obtain

$$
u(x, y)-u(0, y)=\int_{0}^{x} w^{(1)}(s, y) d s, \forall(x, y) \in \Omega
$$

It gives $D_{1} u=w^{(1)} \in X$. Let $D_{1}^{i} u=w^{(i)}, i=1,2, \ldots, r<m$. We have

$$
\begin{equation*}
D_{1}^{r} u_{p}(x, y)-D_{1}^{r} u_{p}(0, y)=\int_{0}^{x} D_{1}^{r+1} u_{p}(s, y) d s, \forall(x, y) \in \Omega \tag{2.5}
\end{equation*}
$$

Since $\left\|D_{1}^{r} u_{p}-D_{1}^{r} u\right\|_{X} \rightarrow 0$ and $\left\|D_{1}^{r+1} u_{p}-w^{(r+1)}\right\|_{X} \rightarrow 0$, (2.5) leads to

$$
\begin{equation*}
D_{1}^{r} u(x, y)-D_{1}^{r} u(0, y)=\int_{0}^{x} w^{(r+1)}(s, y) d s, \forall(x, y) \in \Omega \tag{2.6}
\end{equation*}
$$

Then $D_{1}^{r+1} u=w^{(r+1)} \in X$. By induction, we deduce that $D_{1}^{i} u=w^{(i)}, i=$ $1,2, \ldots, m$. Therefore $u \in X_{m}$ and $u_{p_{k}} \rightarrow u$ in $X_{m}$. This completes the proof.

## 3. The existence theorems

We make the following assumptions.
$\left(A_{1}\right) g \in X_{m}$,
$\left(A_{2}\right) K \in C\left(\Omega \times \Omega \times \mathbb{R}^{m+1} ; \mathbb{R}\right)$, such that

$$
\frac{\partial K}{\partial x}, \frac{\partial^{2} K}{\partial x^{2}}, \ldots, \frac{\partial^{m} K}{\partial x^{m}} \in C\left(\Omega \times \Omega \times \mathbb{R}^{m+1} ; \mathbb{R}\right)
$$

and there exist nonnegative functions $k_{0}, k_{1}, \ldots, k_{m}: \Omega \times \Omega \rightarrow \mathbb{R}$ satisfying
(i) $\beta=\sum_{i=0}^{m} \sup _{(x, y) \in \Omega} \iint_{\Omega} k_{i}(x, y, s, t) d s d t<1$,
(ii) $\forall(x, y, s, t) \in \Omega \times \Omega, \forall\left(u_{0}, u_{1}, \ldots, u_{m}\right),\left(\bar{u}_{0}, \bar{u}_{1}, \ldots, \bar{u}_{m}\right) \in \mathbb{R}^{m+1}$, $\left|K\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)-K\left(x, y, s, t ; \bar{u}_{0}, \bar{u}_{1}, \ldots, \bar{u}_{m}\right)\right|$ $\leq k_{0}(x, y, s, t) \sum_{j=0}^{m}\left|u_{j}-\bar{u}_{j}\right|$,
(iii) $\forall(x, y, s, t) \in \Omega \times \Omega, \forall\left(u_{0}, u_{1}, \ldots, u_{m}\right),\left(\bar{u}_{0}, \bar{u}_{1}, \ldots, \bar{u}_{m}\right) \in \mathbb{R}^{m+1}$,

$$
\begin{aligned}
\left\lvert\, \frac{\partial^{i} K}{\partial x^{i}}\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)-\right. & \left.\frac{\partial^{i} K}{\partial x^{i}}\left(x, y, s, t ; \bar{u}_{0}, \bar{u}_{1}, \ldots, \bar{u}_{m}\right) \right\rvert\, \\
& \leq k_{i}(x, y, s, t) \sum_{j=0}^{m}\left|u_{j}-\bar{u}_{j}\right|
\end{aligned}
$$

Theorem 3.1. Let the functions $g, K$ in (1.1) satisfy the assumptions $\left(A_{1}\right)$, $\left(A_{2}\right)$. Then the equation (1.1) has a unique solution in $X_{m}$.

Proof. For every $u \in X_{m}$, we put

$$
\begin{align*}
(A u)(x, y)= & g(x, y)  \tag{3.1}\\
& +\iint_{\Omega} K\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right) d s d t,(x, y) \in \Omega .
\end{align*}
$$

It is obvious that $A u \in X_{m}$. We shall show that $A: X_{m} \rightarrow X_{m}$ is a contraction map, by proving

$$
\begin{equation*}
\|A u-A \bar{u}\|_{X_{m}} \leq \beta\|u-\bar{u}\|_{X_{m}}, \forall u, \bar{u} \in X_{m} . \tag{3.2}
\end{equation*}
$$

For any $u, \bar{u} \in X_{m}$, and $(x, y) \in \Omega$, from ( $A_{2}$ )-(ii), (3.1) leads to

$$
\begin{aligned}
& |(A u)(x, y)-(A \bar{u})(x, y)| \\
& \leq \iint_{\Omega} \mid K\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right) \\
& \quad-K\left(x, y, s, t ; \bar{u}(s, t), D_{1} \bar{u}(s, t), \ldots, D_{1}^{m} \bar{u}(s, t)\right) \mid d s d t \\
& \leq \iint_{\Omega} k_{0}(x, y, s, t) \sum_{j=0}^{m}\left|D_{1}^{j} u(s, t)-D_{1}^{j} \bar{u}(s, t)\right| d s d t \\
& \leq\left(\sup _{(x, y) \in \Omega} \iint_{\Omega} k_{0}(x, y, s, t) d s d t\right)\|u-\bar{u}\|_{X_{m}} .
\end{aligned}
$$

Hence we have

$$
\begin{equation*}
\|A u-A \bar{u}\|_{X} \leq\left(\sup _{(x, y) \in \Omega} \iint_{\Omega} k_{0}(x, y, s, t) d s d t\right)\|u-\bar{u}\|_{X_{m}} \tag{3.3}
\end{equation*}
$$

Similarly, by

$$
\begin{aligned}
D_{1}^{i}(A u)(x, y)= & D_{1}^{i} g(x, y) \\
& +\iint_{\Omega} \frac{\partial^{i} K}{\partial x^{i}}\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right) d s d t
\end{aligned}
$$

and $\left(A_{2}\right)$-(ii) we obtain

$$
\begin{aligned}
& \left|D_{1}^{i}(A u)(x, y)-D_{1}^{i}(A \bar{u})(x, y)\right| \\
& \leq \iint_{\Omega} \frac{\partial^{i} K}{\partial x^{i}}\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right) \\
& \left.\quad-\frac{\partial^{i} K}{\partial x^{i}}\left(x, y, s, t ; \bar{u}(s, t), D_{1} \bar{u}(s, t), \ldots, D_{1}^{m} \bar{u}(s, t)\right) \right\rvert\, d s d t \\
& \leq \iint_{\Omega} k_{i}(x, y, s, t) \sum_{j=0}^{m}\left|D_{1}^{j} u(s, t)-D_{1}^{j} \bar{u}(s, t)\right| d s d t \\
& \leq\left(\sup _{(x, y) \in \Omega} \iint_{\Omega} k_{i}(x, y, s, t) d s d t\right)\|u-\bar{u}\|_{X_{m}} .
\end{aligned}
$$

Hence we have

$$
\begin{equation*}
\left\|D_{1}^{i}(A u)-D_{1}^{i}(A \bar{u})\right\|_{X} \leq\left(\sup _{(x, y) \in \Omega} \iint_{\Omega} k_{i}(x, y, s, t) d s d t\right)\|u-\bar{u}\|_{X_{m}} \tag{3.4}
\end{equation*}
$$

From (3.3) and (3.4), we have (3.2). Applying the Banach fixed point theorem, Theorem 3.1 is proved.

Next, we also obtain the existence of solutions of (1.1) in $X_{m}$ via the Schauder fixed point theorem, by making the following assumptions.
$\left(A_{1}\right) g \in X_{m}$,
$\left(\bar{A}_{2}\right) K \in C\left(\Omega \times \Omega \times \mathbb{R}^{m+1} ; \mathbb{R}\right)$, such that

$$
\frac{\partial K}{\partial x}, \frac{\partial^{2} K}{\partial x^{2}}, \ldots, \frac{\partial^{m} K}{\partial x^{m}} \in C\left(\Omega \times \Omega \times \mathbb{R}^{m+1} ; \mathbb{R}\right)
$$

and there exist nonnegative functions $\bar{k}_{0}, \bar{k}_{1}, \ldots, \bar{k}_{m}: \Omega \times \Omega \rightarrow \mathbb{R}$ satisfying
(i) $\bar{\beta}=\sum_{i=0}^{m} \sup _{(x, y) \in \Omega} \iint_{\Omega} \bar{k}_{i}(x, y, s, t) d s d t<1$,
(ii) $\left|K\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)\right| \leq \bar{k}_{0}(x, y, s, t)\left(1+\sum_{j=0}^{m}\left|u_{j}\right|\right)$,

$$
\forall(x, y, s, t) \in \Omega \times \Omega, \quad \forall\left(u_{0}, u_{1}, \ldots, u_{m}\right) \in \mathbb{R}^{m+1}
$$

$$
\begin{aligned}
& \text { (iii) }\left|\frac{\partial^{i} K}{\partial x^{i}}\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)\right| \leq \bar{k}_{i}(x, y, s, t)\left(1+\sum_{j=0}^{m}\left|u_{j}\right|\right) \text {, } \\
& \forall(x, y, s, t) \in \Omega \times \Omega, \forall\left(u_{0}, u_{1}, \ldots, u_{m}\right) \in \mathbb{R}^{m+1}, i=1,2, \ldots, m .
\end{aligned}
$$

Theorem 3.2. Let the functions $g$, $K$ in (1.1) satisfy the assumptions $\left(A_{1}\right)$, $\left(\bar{A}_{2}\right)$. Then the equation (1.1) has a solution in $X_{m}$. Furthermore, the set of solutions is compact.

Proof. With the operator $A$ as in (3.1), it is clear that $A: X_{m} \rightarrow X_{m}$. For $M>0$, we define a closed ball in $X_{m}$ as follows:

$$
B_{M}=\left\{u \in X_{m}:\|u\|_{X_{m}} \leq M\right\} .
$$

We shall show that there exists $M>0$ such that $A: B_{M} \rightarrow B_{M}$. For every $u \in B_{M}$ and $(x, y) \in \Omega$, we have

$$
\begin{aligned}
|(A u)(x, y)| & \leq|g(x, y)|+\iint_{\Omega}\left|K\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right)\right| d s d t \\
& \leq\|g\|_{X}+\iint_{\Omega} \bar{k}_{0}(x, y, s, t)\left(1+\sum_{i=0}^{m}\left|D_{1}^{i} u(s, t)\right|\right) d s d t \\
& \leq\|g\|_{X}+\iint_{\Omega} \bar{k}_{0}(x, y, s, t)\left(1+\|u\|_{X_{m}}\right) d y \\
& \leq\|g\|_{X}+(1+M)\left(\sup _{(x, y) \in \Omega} \iint_{\Omega} \bar{k}_{0}(x, y, s, t) d s d t\right)
\end{aligned}
$$

It implies that

$$
\begin{equation*}
\|A u\|_{X} \leq\|g\|_{X}+(1+M)\left(\sup _{(x, y) \in \Omega} \iint_{\Omega} \bar{k}_{0}(x, y, s, t) d s d t\right) . \tag{3.5}
\end{equation*}
$$

Similarly,

$$
\begin{aligned}
\left|D_{1}^{i}(A u)(x, y)\right| \leq & \left|D_{1}^{i} g(x, y)\right| \\
& +\iint_{\Omega}\left|\frac{\partial^{i} K}{\partial x^{i}}\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right)\right| d s d t \\
\leq & \left\|D_{1}^{i} g\right\|_{X}+(1+M)\left(\sup _{(x, y) \in \Omega} \iint_{\Omega} \bar{k}_{i}(x, y, s, t) d s d t\right),
\end{aligned}
$$

so we have

$$
\begin{equation*}
\left\|D_{1}^{i}(A u)\right\|_{X} \leq\left\|D_{1}^{i} g\right\|_{X}+(1+M)\left(\sup _{(x, y) \in \Omega} \iint_{\Omega} \bar{k}_{i}(x, y, s, t) d s d t\right) \tag{3.6}
\end{equation*}
$$

Therefore, we have

$$
\begin{aligned}
\|A u\|_{X_{m}} & \leq\|g\|_{X_{m}}+(1+M) \sum_{i=0}^{m} \sup _{(x, y) \in \Omega} \iint_{\Omega} \bar{k}_{i}(x, y, s, t) d s d t \\
& \leq\|g\|_{X_{m}}+(1+M) \bar{\beta} .
\end{aligned}
$$

Choosing $M \geq\|g\|_{X_{m}}+(1+M) \bar{\beta}$, i.e. $M \geq \frac{\|g\|_{X_{m}}+\bar{\beta}}{1-\beta}$, then $A: B_{M} \rightarrow B_{M}$.
Now we show that two conditions as below are satisfied.
(i) $A: B_{M} \rightarrow B_{M}$ is continuous.
(ii) $\mathcal{F}=A\left(B_{M}\right)$ is relatively compact in $X_{m}$.

To prove (i), let $\left\{u_{p}\right\} \subset B_{M},\left\|u_{p}-u\right\|_{X_{m}} \rightarrow 0$, as $m \rightarrow \infty$, we need to show that

$$
\begin{equation*}
\left\|A u_{p}-A u\right\|_{X} \rightarrow 0 \text { and } \sum_{i=1}^{m}\left\|D_{1}^{i}\left(A u_{p}\right)-D_{1}^{i}(A u)\right\|_{X} \rightarrow 0, \text { as } p \rightarrow \infty \tag{3.8}
\end{equation*}
$$

Note that

$$
\begin{align*}
& \left|\left(A u_{p}\right)(x, y)-(A u)(x, y)\right|  \tag{3.9}\\
& \leq \iint_{\Omega} \mid K\left(x, y, s, t ; u_{p}(s, t), D_{1} u_{p}(s, t), \ldots, D_{1}^{m} u_{p}(s, t)\right) \\
& \quad-K\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right) \mid d s d t
\end{align*}
$$

Since $K$ is uniformly continuous on $\Omega \times \Omega \times[-M, M]^{m+1}$, for $\varepsilon>0$, there exists $\delta>0$ such that, for all $\left(u_{0}, u_{1}, \ldots, u_{m}\right),\left(\bar{u}_{0}, \bar{u}_{1}, \ldots, \bar{u}_{m}\right) \in[-M, M]^{m+1}$ and $(x, y, s, t) \in \Omega \times \Omega$,

$$
\begin{aligned}
& \sum_{i=0}^{m}\left|u_{i}-\bar{u}_{i}\right|<\delta \\
& \Longrightarrow\left|K\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)-K\left(x, y, s, t ; \bar{u}_{0}, \bar{u}_{1}, \ldots, \bar{u}_{m}\right)\right|<\varepsilon
\end{aligned}
$$

Since $\left\|u_{p}-u\right\|_{X} \rightarrow 0$ and $\sum_{i=1}^{m}\left\|D_{1}^{i} u_{p}-D_{1}^{i} u\right\|_{X} \rightarrow 0$, there is $p_{0} \in \mathbb{N}$ such that for all $p \in \mathbb{N}$ with $p \geq p_{0}$,

$$
\left\|u_{p}-u\right\|_{X}+\sum_{i=1}^{m}\left\|D_{1}^{i} u_{p}-D_{1}^{i} u\right\|_{X}<\delta
$$

It implies that for all $p \in \mathbb{N}$ with $p \geq p_{0}$ and $(x, y, s, t) \in \Omega \times \Omega$,

$$
\begin{aligned}
& \mid K\left(x, y, s, t ; u_{p}(s, t), D_{1} u_{p}(s, t), \ldots, D_{1}^{m} u_{p}(s, t)\right) \\
& -K\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right) \mid<\varepsilon .
\end{aligned}
$$

Hence we have

$$
\left|\left(A u_{p}\right)(x, y)-(A u)(x, y)\right|<\varepsilon, \forall(x, y) \in \Omega, \forall p \geq p_{0}
$$

It means that

$$
\begin{equation*}
\left\|A u_{p}-A u\right\|_{X}<\varepsilon, \forall p \geq p_{0} \tag{3.10}
\end{equation*}
$$

i.e., $\left\|A u_{p}-A u\right\|_{X} \rightarrow 0$, as $p \rightarrow \infty$. By the same argument, we obtain that

$$
\left\|D_{1}^{i}\left(A u_{p}\right)-D_{1}^{i}(A u)\right\|_{X} \rightarrow 0
$$

as $p \rightarrow \infty$, for each $i=1, \ldots, m$.
To prove (ii), we use Lemma 2.2. Condition (2.4) (i) holds because of $\mathcal{F}=$ $A\left(B_{M}\right) \subset B_{M}$. It remains to show (2.4) (ii). We note that

$$
\begin{align*}
& (A u)(x, y)-(A u)(\bar{x}, \bar{y})  \tag{3.11}\\
& =g(x, y)-g(\bar{x}, \bar{y}) \\
& \quad+\iint_{\Omega}\left[K\left(x, y, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right)\right. \\
& \left.\quad-K\left(\bar{x}, \bar{y}, s, t ; u(s, t), D_{1} u(s, t), \ldots, D_{1}^{m} u(s, t)\right)\right] d s d t,
\end{align*}
$$

for all $(x, y),(\bar{x}, \bar{y}) \in \Omega, u \in B_{M}$. Let $\varepsilon>0$. By the fact that $K$ is uniformly continuous on $\Omega \times \Omega \times[-M, M]^{m+1}$, there exists $\delta_{1}>0$ such that for all ( $x, y$ ), $(\bar{x}, \bar{y}) \in \Omega$,

$$
\begin{aligned}
& |x-\bar{x}|+|y-\bar{y}|<\delta_{1} \\
& \Longrightarrow\left|K\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)-K\left(\bar{x}, \bar{y}, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)\right|<\frac{\varepsilon}{4},
\end{aligned}
$$

for all $\left(s, t ; u_{0}, u_{1}, \ldots, u_{m}\right) \in \Omega \times[-M, M]^{m+1}$. Then, for all $(x, y),(\bar{x}, \bar{y}) \in \Omega$,

$$
\begin{aligned}
|x-\bar{x}|+|y-\bar{y}|<\delta_{1} \Longrightarrow & \mid K\left(x, y, s, t ; u(y), D_{1} u(y), \ldots, D_{1}^{m} u(y)\right) \\
& -K\left(\bar{x}, \bar{y}, s, t ; u(y), D_{1} u(y), \ldots, D_{1}^{m} u(y)\right) \left\lvert\,<\frac{\varepsilon}{4}\right.,
\end{aligned}
$$

for all $(s, t, u) \in \Omega \times B_{M}$. Hence, for all $(x, y),(\bar{x}, \bar{y}) \in \Omega$,

$$
\begin{aligned}
& |x-\bar{x}|+|y-\bar{y}|<\delta_{1} \\
& \Longrightarrow \iint_{\Omega} \mid K\left(x, y, s, t ; u(y), D_{1} u(y), \ldots, D_{1}^{m} u(y)\right) \\
& \quad-K\left(\bar{x}, \bar{y}, s, t ; u(y), D_{1} u(y), \ldots, D_{1}^{m} u(y)\right) \left\lvert\, d s d t<\frac{\varepsilon}{4}\right., \forall u \in B_{M} .
\end{aligned}
$$

Since $g$ is also uniformly continuous on $\Omega$, there is $\delta_{2}>0$ such that

$$
\forall(x, y), \quad(\bar{x}, \bar{y}) \in \Omega, \quad|x-\bar{x}|+|y-\bar{y}|<\delta_{2} \Longrightarrow|g(x, y)-g(\bar{x}, \bar{y})|<\frac{\varepsilon}{4} .
$$

Choose $\bar{\delta}_{1}=\min \left\{\delta_{1}, \delta_{2}\right\}$, it gives for all $(x, y),(\bar{x}, \bar{y}) \in \Omega$,

$$
\begin{equation*}
|x-\bar{x}|+|y-\bar{y}|<\bar{\delta}_{1} \Longrightarrow|(A u)(x, y)-(A u)(\bar{x}, \bar{y})|<\frac{\varepsilon}{2}, \forall u \in B_{M} . \tag{3.12}
\end{equation*}
$$

It is similar to $\frac{\partial^{i} K}{\partial x^{i}}, D_{1}^{i} g$, so there is $\bar{\delta}_{2}>0$ such that for all $(x, y),(\bar{x}, \bar{y}) \in \Omega$,

$$
\begin{align*}
& |x-\bar{x}|+|y-\bar{y}|<\bar{\delta}_{2}  \tag{3.13}\\
& \Longrightarrow\left|D_{1}^{i}(A u)(x, y)-D_{1}^{i}(A u)(\bar{x}, \bar{y})\right|<\frac{\varepsilon}{2 m}, \forall u \in B_{M}
\end{align*}
$$

It follows that, by choosing $\delta=\min \left\{\bar{\delta}_{1}, \bar{\delta}_{2}\right\}$, we have, for all $(x, y),(\bar{x}, \bar{y}) \in \Omega$,

$$
\begin{align*}
|x-\bar{x}|+|y-\bar{y}|<\delta \Longrightarrow & {[(A u)(x, y)-(A u)(\bar{x}, \bar{y})]_{*} }  \tag{3.14}\\
& =|(A u)(x, y)-(A u)(\bar{x}, \bar{y})| \\
& +\sum_{i=1}^{m}\left|D_{1}^{i}(A u)(x, y)-D_{1}^{i}(A u)(\bar{x}, \bar{y})\right| \\
& <\frac{\varepsilon}{2}+m \frac{\varepsilon}{2 m}=\varepsilon, \forall u \in B_{M} .
\end{align*}
$$

Using Lemma $2.2, \mathcal{F}=A\left(B_{M}\right)$ is relatively compact in $X_{m}$. And applying the Schauder fixed point theorem, the existence of a solution is proved.

Next, we show that the set of solutions, $S=\left\{u \in B_{M}: u=A u\right\}$, is compact in $X_{m}$. By the compactness of the operator $A: B_{M} \rightarrow B_{M}$ and $S=A(S)$, we only prove that $S$ is closed. Let $\left\{u_{p}\right\} \subset S,\left\|u_{p}-u\right\|_{X_{m}} \rightarrow 0$. The continuity of $A$ leads to

$$
\begin{aligned}
\|u-A u\|_{X_{m}} & \leq\left\|u-u_{p}\right\|_{X_{m}}+\left\|u_{p}-A u\right\|_{X_{m}} \\
& =\left\|u-u_{p}\right\|_{X_{m}}+\left\|A u_{p}-A u\right\|_{X_{m}} \rightarrow 0
\end{aligned}
$$

so $u=A u \in S$. Theorem 3.2 is proved.
To the end, we illustrate the results obtained here by two examples.
Example 3.3. We consider (1.1), with the functions $g, K$ as follows

$$
\left\{\begin{array}{l}
K\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)  \tag{3.15}\\
=k(x, y)\left[(s t)^{\alpha_{0}} \sin \left(\frac{\pi u_{0}}{2 w_{0}(s, t)}\right)+\sum_{i=1}^{m}(s t)^{\alpha_{i}} \cos \left(\frac{2 \pi u_{i}}{D_{1}^{i} w_{0}(s, t)}\right)\right], \\
g(x, y)=w_{0}(x, y)-\sum_{j=0}^{m} \frac{1}{\left(1+\alpha_{j}\right)^{2}} k(x, y),
\end{array}\right.
$$

where

$$
\begin{equation*}
w_{0}(x, y)=e^{x}+x^{\gamma_{1}}|y-\alpha|^{\gamma_{2}}, k(x, y)=x^{\tilde{\gamma}_{1}}|y-\tilde{\alpha}|^{\tilde{\gamma}_{2}}, \tag{3.16}
\end{equation*}
$$

and $\alpha, \gamma_{1}, \gamma_{2}, \tilde{\alpha}, \tilde{\gamma}_{1}, \tilde{\gamma}_{2}, \alpha_{0}, \alpha_{1}, \ldots, \alpha_{m}$ are positive constants satisfying

$$
\left\{\begin{array}{l}
0<\alpha<1,0<\gamma_{2} \leq 1, \gamma_{1}>m  \tag{3.17}\\
0<\tilde{\alpha}<1,0<\tilde{\gamma}_{2} \leq 1, \tilde{\gamma}_{1}>m \\
\alpha_{0}, \alpha_{1}, \ldots, \alpha_{m}>0 \\
2 \pi \sum_{j=0}^{m} \frac{1}{\left(1+\alpha_{j}\right)^{2}}\left(1+\sum_{i=1}^{m} \tilde{\gamma}_{1}\left(\tilde{\gamma}_{1}-1\right) \ldots\left(\tilde{\gamma}_{1}-i+1\right)\right) \max \left\{\tilde{\alpha} \tilde{\gamma}_{2},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}<1 .
\end{array}\right.
$$

We have

$$
\begin{aligned}
w_{0}(x, y) & =e^{x}+x^{\gamma_{1}}|y-\alpha|^{\gamma_{2}} \\
D_{1}^{i} w_{0}(x, y) & =e^{x}+\gamma_{1}\left(\gamma_{1}-1\right) \ldots\left(\gamma_{1}-i+1\right) x^{\gamma_{1}-i}|y-\alpha|^{\gamma_{2}},
\end{aligned}
$$

so $w_{0}, D_{1}^{i} w_{0} \in X$ and $w_{0}(x, y) \geq 1, D_{1}^{i} w_{0}(x, y) \geq 1$. Hence $K \in C(\Omega \times \Omega \times$ $\left.\mathbb{R}^{m+1} ; \mathbb{R}\right)$. We now prove that $\left(A_{1}\right),\left(A_{2}\right)$ hold. It is obviously that $\left(A_{1}\right)$ holds, by $w_{0}, k \in X_{m}$.

Assumption $\left(A_{2}\right)$ holds, by the fact that
First, $D_{1}^{i} k \in X$,

$$
\frac{\partial^{i} K}{\partial x^{i}}=D_{1}^{i} k(x, y)\left[(s t)^{\alpha_{0}} \sin \left(\frac{\pi u_{0}}{2 w_{0}(s, t)}\right)+\sum_{i=1}^{m}(s t)^{\alpha_{i}} \cos \left(\frac{2 \pi u_{i}}{D_{1}^{i} w_{0}(s, t)}\right)\right]
$$

so $\frac{\partial^{i} K}{\partial x^{i}} \in C\left(\Omega \times \Omega \times \mathbb{R}^{m+1} ; \mathbb{R}\right)$;

$$
\begin{align*}
& \left|K\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)-K\left(x, y, s, t ; \bar{u}_{0}, \bar{u}_{1}, \ldots, \bar{u}_{m}\right)\right|  \tag{3.18}\\
& \leq k(x, y)\left((s t)^{\alpha_{0}} \frac{\pi\left|u_{0}-\bar{u}_{0}\right|}{2 w_{0}(s, t)}+\sum_{i=1}^{m}(s t)^{\alpha_{i}} \frac{2 \pi\left|u_{i}-\bar{u}_{i}\right|}{D_{1}^{i} w_{0}(s, t)}\right) \\
& \leq 2 \pi k(x, y) \sum_{i=0}^{m}(s t)^{\alpha_{i}} \sum_{j=0}^{m}\left|u_{j}-\bar{u}_{j}\right| \\
& \equiv k_{0}(x, y, s, t) \sum_{j=0}^{m}\left|u_{j}-\bar{u}_{j}\right|
\end{align*}
$$

in which

$$
\begin{equation*}
k_{0}(x, y, s, t)=2 \pi k(x, y) \sum_{j=0}^{m}(s t)^{\alpha_{j}} ; \tag{3.19}
\end{equation*}
$$

$$
\begin{align*}
& \left|\frac{\partial^{i} K}{\partial x^{i}}\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)-\frac{\partial^{i} K}{\partial x^{i}}\left(x, y, s, t ; \bar{u}_{0}, \bar{u}_{1}, \ldots, \bar{u}_{m}\right)\right|  \tag{3.20}\\
& \leq k_{i}(x, y, s, t) \sum_{j=0}^{m}\left|u_{j}-\bar{u}_{j}\right|
\end{align*}
$$

where

$$
\begin{equation*}
k_{i}(x, y, s, t)=2 \pi\left|D_{1}^{i} k(x, y)\right| \sum_{j=0}^{m}(s t)^{\alpha_{j}} . \tag{3.21}
\end{equation*}
$$

We have

$$
\begin{align*}
\iint_{\Omega} k_{i}(x, y, s, t) d s d t & =2 \pi\left|D_{1}^{i} k(x, y)\right| \sum_{j=0}^{m} \iint_{\Omega}(s t)^{\alpha_{j}} d s d t  \tag{3.22}\\
& =2 \pi \sum_{j=0}^{m} \frac{1}{\left(1+\alpha_{j}\right)^{2}}\left|D_{1}^{i} k(x, y)\right| \\
& \leq 2 \pi \sum_{j=0}^{m} \frac{1}{\left(1+\alpha_{j}\right)^{2}} \sup _{(x, y) \in \Omega}\left|D_{1}^{i} k(x, y)\right| .
\end{align*}
$$

We also have the following lemma, it is clear, so we omit its proof.
Lemma 3.4. Let positive constants $\alpha, \gamma_{2}, \gamma_{1}$ satisfy $0<\alpha<1,0<\gamma_{2} \leq 1<$ $\gamma_{1}$. Then

$$
\begin{aligned}
& 0 \leq x^{\gamma_{1}}|y-\alpha|^{\gamma_{2}} \leq \max \left\{\alpha^{\gamma_{2}},(1-\alpha)^{\gamma_{2}}\right\}, \forall x, y \in[0,1], \\
& 0 \leq x^{\gamma_{1}-1}|y-\alpha|^{\gamma_{2}} \leq \max \left\{\alpha^{\gamma_{2}},(1-\alpha)^{\gamma_{2}}\right\}, \forall x, y \in[0,1] .
\end{aligned}
$$

Using Lemma 3.4, we get

$$
\begin{align*}
& 0 \leq k(x, y)=x^{\tilde{\gamma}_{1}}|y-\tilde{\alpha}|^{\tilde{\gamma}_{2}} \leq \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\} ; \\
& 0 \leq D_{1} k(x, y)= \\
& \quad \begin{aligned}
0 & \tilde{\gamma}_{1} x^{\tilde{\gamma}_{1}-1}|y-\tilde{\alpha}|^{\tilde{\gamma}_{2}} \leq \tilde{\gamma}_{1} \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\} \\
& \vdots \\
& \leq \tilde{\gamma}_{1}\left(\tilde{\gamma}_{1}-1\right) \ldots\left(\tilde{\gamma}_{1}-i+1\right) \ldots\left(\tilde{\gamma}_{1}-i+1\right) \max \left\{x^{\tilde{\gamma}_{1}-i}|y-\alpha|^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}, i=1, \ldots, m,
\end{aligned}
\end{align*}
$$

SO

$$
\begin{align*}
& \sum_{i=0}^{m} \sup _{(x, y) \in \Omega} \iint_{\Omega} k_{i}(x, y, s, t) d s d t  \tag{3.24}\\
& \leq 2 \pi \sum_{j=0}^{m} \frac{1}{\left(1+\alpha_{j}\right)^{2}}\left(1+\sum_{i=1}^{m} \tilde{\gamma}_{1}\left(\tilde{\gamma}_{1}-1\right) \ldots\left(\tilde{\gamma}_{1}-i+1\right)\right) \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}
\end{align*}
$$

consequently

$$
\begin{equation*}
\beta=\sum_{i=0}^{m} \sup _{(x, y) \in \Omega} \iint_{\Omega} k_{i}(x, y, s, t) d s d t<1 \tag{3.25}
\end{equation*}
$$

Then, Theorem 3.1 is fulfilled. Morever, $w_{0} \in X_{m}$ is also a unique solution of (1.1).

Example 3.5. We consider (1.1) with the functions $K, g$ defined by

$$
\left\{\begin{array}{l}
K\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)=k(x, y) K_{1}\left(s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)  \tag{3.26}\\
g(x, y)=w_{0}(x, y)-2 \sum_{j=0}^{m} \frac{1}{\left(1+\alpha_{j}\right)^{2}} k(x, y)
\end{array}\right.
$$

where

$$
\left\{\begin{array}{l}
K_{1}\left(s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)  \tag{3.27}\\
=(s t)^{\alpha_{0}}\left(\frac{\left|u_{0}\right|}{w_{0}(s, t)}+\left|\frac{u_{0}}{w_{0}(s, t)}\right|^{1 / 4}\right)+\sum_{i=1}^{m}(s t)^{\alpha_{i}}\left(\frac{\left|u_{i}\right|}{D_{1}^{i} w_{0}(s, t)}+\left(\frac{u_{i}}{D_{1}^{i} w_{0}(s, t)}\right)^{1 / 3}\right) \\
w_{0}(x, y)=e^{x}+x^{\gamma_{1}}|y-\alpha|^{\gamma_{2}}, \quad k(x, y)=x^{\tilde{\gamma}_{1}}|y-\tilde{\alpha}|^{\tilde{\gamma}_{2}}
\end{array}\right.
$$

and $\alpha, \gamma_{1}, \gamma_{2}, \tilde{\alpha}, \tilde{\gamma}_{1}, \tilde{\gamma}_{2}, \alpha_{0}, \alpha_{1}, \ldots, \alpha_{m}$ are positive constants satisfying

$$
\left\{\begin{array}{l}
0<\alpha<1,0<\gamma_{2} \leq 1, \gamma_{1}>m  \tag{3.28}\\
0<\tilde{\alpha}<1,0<\tilde{\gamma}_{2} \leq 1, \tilde{\gamma}_{1}>m \\
\alpha_{0}, \alpha_{1}, \ldots, \alpha_{m}>0 \\
2 \sum_{j=0}^{m} \frac{1}{\left(1+\alpha_{j}\right)^{2}}\left(1+\sum_{i=1}^{m} \tilde{\gamma}_{1}\left(\tilde{\gamma}_{1}-1\right) \ldots\left(\tilde{\gamma}_{1}-i+1\right)\right) \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}<1 .
\end{array}\right.
$$

We can prove that $\left(A_{1}\right),\left(\bar{A}_{2}\right)$ hold, by the following.
First, $w_{0}, D_{1}^{i} w_{0} \in X$ and $w_{0}(x, y) \geq 1, D_{1}^{i} w_{0}(x, y) \geq 1$. Then $K \in C(\Omega \times$ $\left.\Omega \times \mathbb{R}^{m+1} ; \mathbb{R}\right)$.

By $D_{1}^{i} k \in X, \frac{\partial^{i} K}{\partial x^{i}}=D_{1}^{i} k(x, y) K_{1}\left(s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)$, so $\frac{\partial^{i} K}{\partial x^{i}} \in C(\Omega \times \Omega \times$ $\left.\mathbb{R}^{m+1} ; \mathbb{R}\right)$. Applying the inequality

$$
a \leq 1+a^{q}, \forall a \geq 0, \forall q \geq 1
$$

we obtain

$$
\begin{align*}
\left|K_{1}\left(s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)\right| \leq & (s t)^{\alpha_{0}}\left(1+\frac{2\left|u_{0}\right|}{w_{0}(s, t)}\right)  \tag{3.29}\\
& +\sum_{i=1}^{m}(s t)^{\alpha_{i}}\left(1+\frac{2\left|u_{i}\right|}{D_{1}^{i} w_{0}(s, t)}\right) \\
\leq & 2 \sum_{i=0}^{m}(s t)^{\alpha_{i}}\left(1+\sum_{j=0}^{m}\left|u_{j}\right|\right),
\end{align*}
$$

it leads to

$$
\begin{align*}
\left|K\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)\right| & =k(x, y)\left|K_{1}\left(s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)\right|  \tag{3.30}\\
& \leq \bar{k}_{0}(x, y, s, t)\left(1+\sum_{j=0}^{m}\left|u_{j}\right|\right),
\end{align*}
$$

in which

$$
\begin{equation*}
\bar{k}_{0}(x, y, s, t)=2 k(x, y) \sum_{j=0}^{m}(s t)^{\alpha_{j}} . \tag{3.31}
\end{equation*}
$$

Similarly,

$$
\begin{equation*}
\left|\frac{\partial^{i} K}{\partial x_{1}^{i}}\left(x, y, s, t ; u_{0}, u_{1}, \ldots, u_{m}\right)\right| \leq \bar{k}_{i}(x, y, s, t)\left(1+\sum_{j=0}^{m}\left|u_{j}\right|\right), \tag{3.32}
\end{equation*}
$$

in which

$$
\begin{equation*}
\bar{k}_{i}(x, y, s, t)=2\left|D_{1}^{i} k(x, y)\right| \sum_{j=0}^{m}(s t)^{\alpha_{j}} . \tag{3.33}
\end{equation*}
$$

Next,

$$
\begin{aligned}
& \sum_{i=0}^{m} \sup _{(x, y) \in \Omega} \iint_{\Omega} \bar{k}_{i}(x, y, s, t) d s d t \\
& =2 \sum_{i=0}^{m} \sup _{(x, y) \in \Omega}\left|D_{1}^{i} k(x, y)\right| \sum_{j=0}^{m} \iint_{\Omega}(s t)^{\alpha_{j}} d s d t \\
& \leq 2 \sum_{j=0}^{m} \frac{1}{\left(1+\alpha_{j}\right)^{2}}\left(1+\sum_{i=1}^{m} \tilde{\gamma}_{1}\left(\tilde{\gamma}_{1}-1\right) \ldots\left(\tilde{\gamma}_{1}-i+1\right)\right) \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\},
\end{aligned}
$$

so

$$
\begin{equation*}
\bar{\beta}=\sum_{i=0}^{m} \sup _{(x, y) \in \Omega} \iint_{\Omega} \bar{k}_{i}(x, y, s, t) d s d t<1 \tag{3.34}
\end{equation*}
$$

Theorem 3.2 is true. Furthermore, $w_{0} \in X_{m}$ is also a solution of (1.1).

Acknowledgments: The authors wish to express their sincere thanks to the referees and the Editor for their valuable comments. This research is funded by Vietnam National University HoChiMinh City (VNU-HCM) under Grant no. B2017-18-04.

## References

[1] M. A. Abdou, W. G. El-Sayed, E. I. Deebs, A solution of a nonlinear integral equation, Applied Math. and Compu., 160 (2005), 1-14.
[2] M. A. Abdou, A. A. Badr, M. M. El-Kojok, On the solution of a mixed nonlinear integral equation, Applied Math. and Compu., 217(12) (2011), 5466-5475.
[3] J. Biazar, H. Ghazvini, M. Eslami, He's homotopy perturbation method for systems of integro-differential equations, Chaos, Solitons and Fractals, 39(3) (2009), 1253-1258.
[4] Jafar Biazar, M. Eslami, Modified HPM for solving systems of Volterra integral equations of the second kind, Jour. of King Saud University -Science, 23(1) (2011), 35-39.
[5] J. Biazar, M. Eslami, M. R. Islam, Differential transform method for special systems of integral equations, Jour. of King Saud University -Science, 24(3) (2012), 211-214.
[6] J. Biazar, M. Eslami, H. Aminikhah, Application of homotopy perturbation method for systems of Volterra integral equations of the first kind, Chaos, Solitons and Fractals, 42(5) (2009), 3020-3026.
[7] M. M. El-Borai, M. A. Abdou, M. M. El-Kojok, On a discussion of nonlinear integral equation of type Volterra - Hammerstein, J. Korea Soc. Math. Educ., Ser. B, Pure Appl. Math. 15(1) (2008), 1-17.
[8] C. Corduneanu, Integral equations and applications, Cambridge University Press, New York, 1991.
[9] K. Deimling, Nonlinear Functional Analysis, Springer, NewYork, 1985.
[10] P. H. Danh, H. T. H. Dung, N. T. Long, L. T. P. Ngoc, On nonlinear integrodifferential equations in two variables, Results in Math., 71(1) (2017), 251-281.
[11] H. T. H. Dung, L. T. P. Ngoc, Note on a Volterra-Fredholm type integrodifferential equation in two variables, Nonlinear Funct. Anal. and Appl., 22(1) (2017), 121-135.
[12] H. T. H. Dung, L. T. P. Ngoc, N. T. Long, On a $(m+n)$-order nonlinear integrodifferential equation in two variables, Jour. of Abstract Diff. Equ. and Appl.,(JADEA). 8(1) (2017), 71-83.
[13] M. Eslami, New homotopy perturbation method for a special kind of Volterra integral equations in two-dimensional space, Compu. Math. and Model., 25(1) (2014), 135-148.
[14] Monica Lauran, Existence results for some nonlinear integral equations, Miskolc Mathematical Notes, 13(1) (2012), 67-74.
[15] L. T. P. Ngoc, N. T. Long, Applying a fixed point theorem of Krasnosel'skii type to the existence of asymptotically stable solutions for a Volterra -Hammerstein integral equation, Nonlinear Anal. TMA. 74(11) (2011), 3769-3774.
[16] L. T. P. Ngoc, N. T. Long, On a nonlinear Volterra - Hammerstein integral equation in two variables, Acta Math. Scientia, 33B(2) (2013), 484-494.
[17] L. T. P. Ngoc, N. T. Long, Existence of asymptotically stable solutions for a mixed functional nonlinear integral equation in $N$ variables, Mathematische Nachrichten, 288(5-6) (2015), 633-647.
[18] L. T. P. Ngoc, N. T. Long, A continuum of solutions in a Fréchet space of a nonlinear functional integral equation in $N$ variables, Mathematische Nachrichten, 289(13) (2016), 1665-1679.
[19] L. T. P. Ngoc, H. T. H. Dung, N. T. Long, Applying a fixed point theorem of Krasnosel'skii to a nonlinear integrodifferential equations in $N$ variables, Fixed Point Theory (accepted for publication).
[20] B. G. Pachpatte, On Fredholm type integrodifferential equation, Tamkang J. of Math., 39(1) (2008), 85-94.
[21] B. G. Pachpatte, On Fredholm type integral equation in two variables, Diff. Equations \& Applications, 1 (1) (2009), 27-39.
[22] B. G. Pachpatte, Volterra integral and integrodifferential equations in two variables, J. Inequal. Pure and Appl. Math., 10(4) (2009), Art. 108, 10 pp.
[23] I. K. Purnaras, A note on the existence of solutions to some nonlinear functional integral equations, Electronic J. Qualitative Theory of Diff. Equat., 2016(17) (2006), 1-24.


[^0]:    ${ }^{0}$ Received June 24, 2017. Revised November 29, 2017.
    ${ }^{0} 2010$ Mathematics Subject classification: 45G10, 47H10, 47N20, 65J15.
    ${ }^{0}$ Keywords: m-order nonlinear integrodifferential equation, Banach fixed point theorem, Schauder fixed point theorem.

