

## LIGHTLIKE HYPERSURFACES OF AN INDEFINITE KAEHLER MANIFOLD WITH A SEMI-SYMMETRIC METRIC CONNECTION

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**Abstract.** We study lightlike hypersurfaces  $M$  of an indefinite Kaehler manifold  $\bar{M}$  with a semi-symmetric metric connection subject such that the characteristic vector field  $\zeta$  of  $\bar{M}$  belongs to our screen distribution  $S(TM)$ . First, we provide several new results on such a lightlike hypersurface. Next, we investigate lightlike hypersurfaces of an indefinite complex space form  $\bar{M}(c)$  with a semi-symmetric metric connection such that  $\zeta$  belongs to  $S(TM)$ .

### 1. INTRODUCTION

In 1924, Friedmann-Schouten [3] introduced the idea of a semi-symmetric connection: A linear connection  $\bar{\nabla}$  on a semi-Riemannian manifold  $(\bar{M}, \bar{g})$  is called a *semi-symmetric connection* if its torsion tensor  $\bar{T}$  satisfies

$$\bar{T}(\bar{X}, \bar{Y}) = \theta(\bar{Y})\bar{X} - \theta(\bar{X})\bar{Y}, \quad (1.1)$$

where  $\theta$  is a 1-form associated with a smooth unit spacelike vector field  $\zeta$ , which is called the *characteristic vector field* of  $\bar{M}$ , by  $\theta(\bar{X}) = \bar{g}(\bar{X}, \zeta)$ . Moreover, if this connection is a metric one, *i.e.*, it satisfies  $\bar{\nabla}\bar{g} = 0$ , then  $\bar{\nabla}$  is called a *semi-symmetric metric connection* on  $\bar{M}$ . The notion of a semi-symmetric metric connection was introduced by Yano [8] and studied by this author [4, 6]. In the followings, denote by  $\bar{X}$ ,  $\bar{Y}$  and  $\bar{Z}$  the smooth vector fields on  $\bar{M}$ .

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**Remark 1.1.** Denote  $\tilde{\nabla}$  by the Levi-Civita connection of a semi-Riemannian manifold  $(\bar{M}, \bar{g})$  with respect to  $\bar{g}$ . It is well known that a linear connection  $\bar{\nabla}$  on  $\bar{M}$  is a semi-symmetric metric connection if and only if it satisfies

$$\bar{\nabla}_{\bar{X}}\bar{Y} = \tilde{\nabla}_{\bar{X}}\bar{Y} + \theta(\bar{Y})\bar{X} - \bar{g}(\bar{X}, \bar{Y})\zeta. \tag{1.2}$$

The object of this paper is to study lightlike hypersurfaces  $M$  of an indefinite Kaehler manifold  $\bar{M}$  with a semi-symmetric metric connection  $\bar{\nabla}$  subject such that the characteristic vector field  $\zeta$  of  $\bar{M}$  belongs to our screen distribution  $S(TM)$  of  $M$ . In Section 3, we provide several new results on such a lightlike hypersurface. In Section 4, we characterize lightlike hypersurfaces of an indefinite complex space form  $\bar{M}(c)$  with a semi-symmetric metric connection subject to the condition that  $\zeta$  belongs to  $S(TM)$ .

## 2. STRUCTURE EQUATIONS

Let  $(\bar{M}, \bar{g}, J)$  be an indefinite Kaehler manifold, where  $\bar{g}$  is a semi-Riemannian metric and  $J$  is an indefinite almost complex structure ([7]) such that

$$J^2 = -I, \quad \bar{g}(J\bar{X}, J\bar{Y}) = \bar{g}(\bar{X}, \bar{Y}), \quad (\tilde{\nabla}_{\bar{X}}J)\bar{Y} = 0. \tag{2.1}$$

Replacing the Levi-Civita connection  $\tilde{\nabla}$  by the semi-symmetric metric connection  $\bar{\nabla}$ , the third equation of three equations in (2.1) is reduced to

$$(\bar{\nabla}_{\bar{X}}J)\bar{Y} = \theta(J\bar{Y})\bar{X} - \theta(\bar{Y})J\bar{X} - \bar{g}(\bar{X}, J\bar{Y})\zeta + \bar{g}(\bar{X}, \bar{Y})J\zeta. \tag{2.2}$$

Let  $(M, g)$  be a lightlike hypersurface of an indefinite Kaehler manifold  $\bar{M} = (\bar{M}, \bar{g}, J)$ . Then the normal bundle  $TM^\perp$  of  $M$  is a subbundle of the tangent bundle  $TM$ . A complementary vector bundle  $S(TM)$  of  $TM^\perp$  in  $TM$  is non-degenerate and called a *screen distribution* of  $M$  such that

$$TM = TM^\perp \oplus_{orth} S(TM),$$

where  $\oplus_{orth}$  denotes the orthogonal direct sum. Denote by  $F(M)$  the algebra of smooth functions on  $M$  and by  $\Gamma(E)$  the  $F(M)$  module of smooth sections of any vector bundle  $E$  over  $M$ . Also denote by  $(2.1)_i$  the  $i$ -th equation of (2.1). We use same notations for any others. For any null section  $\xi$  of  $TM^\perp$  on a coordinate neighborhood  $\mathcal{U} \subset M$ , there exists a unique null section  $N$  of a unique lightlike vector bundle  $tr(TM)$  in  $S(TM)^\perp$  satisfying

$$\bar{g}(\xi, N) = 1, \quad \bar{g}(N, N) = \bar{g}(N, X) = 0, \quad \forall X \in \Gamma(S(TM)).$$

We call  $tr(TM)$  and  $N$  the *transversal vector bundle* and the *null transversal vector field* of  $M$  with respect to the screen distribution  $S(TM)$ , respectively [1, Section 4.1]. Then the tangent bundle  $T\bar{M}$  of  $\bar{M}$  is decomposed as

$$T\bar{M} = TM \oplus tr(TM) = \{TM^\perp \oplus tr(TM)\} \oplus_{orth} S(TM).$$

Denote by  $X, Y$  and  $Z$  the vector fields on  $M$ , unless otherwise specified. Let  $P$  be the projection morphism of  $TM$  on  $S(TM)$ . Then the local Gauss and Weingarten formulae of  $M$  and  $S(TM)$  are given respectively by

$$\bar{\nabla}_X Y = \nabla_X Y + B(X, Y)N, \tag{2.3}$$

$$\bar{\nabla}_X N = -A_N X + \tau(X)N; \tag{2.4}$$

$$\nabla_X PY = \nabla_X^* PY + C(X, PY)\xi, \tag{2.5}$$

$$\nabla_X \xi = -A_\xi^* X - \tau(X)\xi, \tag{2.6}$$

where  $\nabla$  and  $\nabla^*$  are the induced linear connections on  $TM$  and  $S(TM)$ ,  $B$  and  $C$  are the local second fundamental forms on  $TM$  and  $S(TM)$ , respectively,  $A_N$  and  $A_\xi^*$  are the shape operators and  $\tau$  is a 1-form on  $TM$ .

The connection  $\nabla$  is a semi-symmetric non-metric connection and satisfy

$$(\nabla_X g)(Y, Z) = B(X, Y)\eta(Z) + B(X, Z)\eta(Y). \tag{2.7}$$

$$T(X, Y) = \theta(Y)X - \theta(X)Y, \tag{2.8}$$

and we see that  $B$  is symmetric on  $TM$ , where  $T$  is the torsion tensor with respect to the induced connection  $\nabla$  and  $\eta$  is a 1-form on  $TM$  such that

$$\eta(X) = \bar{g}(X, N).$$

From the fact that  $B(X, Y) = \bar{g}(\bar{\nabla}_X Y, \xi)$ , we know that  $B$  is independent of the choice of the screen distribution  $S(TM)$  and satisfies

$$B(X, \xi) = 0. \tag{2.9}$$

The above two local second fundamental forms  $B$  and  $C$  for  $TM$  and  $S(TM)$  respectively are related to their shape operators by

$$B(X, Y) = g(A_\xi^* X, Y), \quad \bar{g}(A_\xi^* X, N) = 0, \tag{2.10}$$

$$C(X, PY) = g(A_N X, PY), \quad \bar{g}(A_N X, N) = 0. \tag{2.11}$$

From (2.10),  $A_\xi^*$  is  $S(TM)$ -valued real self-adjoint operator and satisfies

$$A_\xi^* \xi = 0, \tag{2.12}$$

### 3. SOME RESULTS

For a lightlike hypersurface  $M$  of an indefinite Kaehler manifold  $\bar{M}$ , it is known ([1, Section 6.2], [4]) that  $J(TM^\perp)$  and  $J(tr(TM))$  are subbundles of  $S(TM)$  such that  $TM^\perp \cap J(TM^\perp) = \{0\}$  and  $TM^\perp \cap J(tr(TM)) = \{0\}$ . Therefore  $J(TM^\perp) \oplus J(tr(TM))$  is a vector subbundle of  $S(TM)$ , of rank 2. Thus there exist two non-degenerate almost complex distributions  $D_o$  and  $D$

on  $M$  with respect to  $J$ , i.e.,  $J(D_o) \subset D_o$  and  $J(D) \subset D$ , such that

$$S(TM) = J(TM^\perp) \oplus J(\text{tr}(TM)) \oplus_{\text{orth}} D_o,$$

$$D = \{TM^\perp \oplus_{\text{orth}} J(TM^\perp)\} \oplus_{\text{orth}} D_o.$$

In this case, the decomposition form of  $TM$  is reduced to

$$TM = D \oplus J(\text{tr}(TM)). \tag{3.1}$$

Consider two local lightlike vector fields  $U$  and  $V$  on  $S(TM)$  such that

$$U = -JN, \quad V = -J\xi. \tag{3.2}$$

Denote by  $S$  the projection morphism of  $TM$  on  $D$  with respect to the decomposition (3.1). Then any vector field  $X$  on  $M$  is expressed as follows:

$$X = SX + u(X)U,$$

where  $u$  and  $v$  are 1-forms locally defined on  $TM$  by

$$u(X) = g(X, V), \quad v(X) = g(X, U). \tag{3.3}$$

Using (3.2), the action  $JX$  of any  $X \in \Gamma(TM)$  by  $J$  is expressed as follows:

$$JX = FX + u(X)N, \tag{3.4}$$

where  $F$  is a tensor field of type  $(1, 1)$  globally defined on  $M$  by  $F = J \circ S$ . Applying  $J$  to (3.4) and using (2.1) and (3.2), we have

$$F^2X = -X + u(X)U. \tag{3.5}$$

As  $u(U) = 1$  and  $FU = 0$ , the set  $(F, u, U)$  defines an indefinite almost contact structure on  $M$ . Then  $F$  is called the *structure tensor field* of  $M$ .

In the sequel, we shall assume that  $\zeta$  belongs to  $S(TM)$ . Applying  $\bar{\nabla}_X$  to (3.2) and (3.4) and using (2.2)~(2.6), (2.9)~(2.11), and (3.4), we have

$$B(X, U) = C(X, V) - \theta(V)\eta(X), \tag{3.6}$$

$$\nabla_X U = F(A_N X) + \tau(X)U + \theta(U)X - v(X)\zeta - \eta(X)F\zeta. \tag{3.7}$$

$$\nabla_X V = F(A_\xi^* X) - \tau(X)V + \theta(V)X - u(X)\zeta, \tag{3.8}$$

$$(\nabla_X F)Y = u(Y)A_N X - B(X, Y)U + \theta(FY)X - \theta(Y)FX - \bar{g}(X, JY)\zeta + g(X, Y)F\zeta. \tag{3.9}$$

**Theorem 3.1.** *There exist no lightlike hypersurfaces of an indefinite Kaehler manifold  $\bar{M}$  with a semi-symmetric metric connection such that  $\zeta$  belongs to  $S(TM)$  and  $V$  is parallel with respect to the connection  $\nabla$  on  $M$ .*

*Proof.* Assume that  $V$  is parallel with respect to the connection  $\nabla$ . Taking the scalar product with  $N$  to (3.8) and using (2.10) and (3.4), we obtain

$$B(X, U) + \theta(V)\eta(X) = 0.$$

Replacing  $X$  by  $\xi$  to this equation and using (2.9), we have  $\theta(V) = 0$ . Thus

$$B(X, U) = 0.$$

Taking the scalar product with  $\zeta$  to (3.8) and using  $\theta(V) = 0$ , we obtain

$$B(X, F\zeta) = -u(X).$$

From the last two equations, we have the following impossible result:

$$-1 = -u(U) = B(U, F\zeta) = B(F\zeta, U) = 0.$$

Thus we have our theorem. □

**Theorem 3.2.** *There exist no lightlike hypersurfaces of an indefinite Kaehler manifold  $\bar{M}$  with a semi-symmetric metric connection such that  $\zeta$  belongs to  $S(TM)$  and  $F$  is parallel with respect to the connection  $\nabla$  on  $M$ .*

*Proof.* Assume that  $F$  is parallel with respect to  $\nabla$ . Replacing  $Y$  by  $\xi$  to (3.9) and using (2.9) and the fact that  $F\xi = -V$ , we get

$$\theta(V)X = u(X)\zeta.$$

Taking the scalar product with  $N$  to this, we have  $\theta(V)\eta(X) = 0$ . It follows that  $\theta(V) = 0$ . Taking  $X = U$  to the last equation:  $u(X)\zeta = 0$ , we get  $\zeta = 0$ . It is a contradiction to  $\zeta \neq 0$ . □

**Definition 3.3.** ([5]) The structure tensor field  $F$  of  $M$  is said to be *recurrent* if there exists a 1-form  $\varpi$  on  $TM$  such that

$$(\nabla_X F)Y = \varpi(X)FY.$$

**Theorem 3.4.** *There exist no lightlike hypersurfaces of an indefinite Kaehler manifold  $\bar{M}$  with a semi-symmetric metric connection such that  $\zeta$  belongs to  $S(TM)$  and the structure tensor field  $F$  of  $M$  is recurrent.*

*Proof.* From the above definition and (3.9), we obtain

$$\begin{aligned} \varpi(X)FY &= u(Y)A_N X - B(X, Y)U + \theta(FY)X - \theta(Y)FX \\ &\quad - \bar{g}(X, JY)\zeta + g(X, Y)F\zeta. \end{aligned}$$

Replacing  $Y$  by  $\xi$  and using (2.9) and the fact that  $F\xi = -V$ , we get

$$\varpi(X)V = \theta(V)X - u(X)\zeta.$$

Taking the scalar product with  $N$ ,  $\zeta$  and  $U$  to this by turns, we have

$$\theta(V) = 0, \quad u(X) = 0, \quad \varpi(X) = 0.$$

As  $\varpi(X) = 0$ , the structure tensor  $F$  is parallel with respect to the induced connection  $\nabla$  on  $M$ . Thus we have our theorem by Theorem 3.2. □

**Definition 3.5.** ([5]) The structure tensor field  $F$  of  $M$  is said to be *Lie recurrent* if there exists a 1-form  $\vartheta$  on  $M$  such that

$$(\mathcal{L}_X F)Y = \vartheta(X)FY,$$

where  $\mathcal{L}_X$  denotes the Lie derivative on  $M$  with respect to  $X$ , that is,

$$(\mathcal{L}_X F)Y = [X, FY] - F[X, Y].$$

The structure tensor field  $F$  is called *Lie parallel* if  $\mathcal{L}_X F = 0$ . A lightlike hypersurface  $M$  of an indefinite Kaehler manifold  $\bar{M}$  is called *Lie recurrent* if it admits a Lie recurrent structure tensor field  $F$ .

**Theorem 3.6.** *Let  $M$  be a Lie recurrent lightlike hypersurface of an indefinite Kaehler manifold  $\bar{M}$  with a semi-symmetric metric connection such that the characteristic vector field  $\zeta$  of  $\bar{M}$  belongs to  $S(TM)$ . Then*

- (1)  $F$  is Lie parallel,
- (2) the 1-form  $\tau$  satisfies  $\tau = 0$ , and
- (3) the shape operator  $A_\xi^*$  satisfies  $A_\xi^*U = A_\xi^*V = 0$ .

*Proof.* (1) Using the above definition, (2.8), (3.4) and (3.9), we obtain

$$\begin{aligned} \vartheta(X)FY &= -\nabla_{FY}X + F\nabla_YX + u(Y)A_NX - B(X, Y)U \\ &\quad - \bar{g}(X, JY)\zeta + g(X, Y)F\zeta. \end{aligned} \quad (3.10)$$

Taking  $Y = \xi$  to (3.10) and using (2.9) and the fact that  $F\xi = -V$ , we have

$$-\vartheta(X)V = \nabla_VX + F\nabla_\xi X + u(X)\zeta. \quad (3.11)$$

Taking the scalar product with  $V$  to (3.11), we have

$$u(\nabla_VX) = -\theta(V)u(X). \quad (3.12)$$

Replacing  $Y$  by  $V$  to (3.10) and using the fact that  $FV = \xi$ , we have

$$\vartheta(X)\xi = -\nabla_\xi X + F\nabla_VX - B(X, V)U + u(X)F\zeta.$$

Applying  $F$  to this equation and using (3.5) and (3.12), we obtain

$$\vartheta(X)V = \nabla_VX + F\nabla_\xi X + u(X)\zeta.$$

Comparing this equation with (3.11), we get  $\vartheta = 0$ . Thus  $F$  is Lie parallel.

(2) Taking the scalar product with  $N$  to (3.10) and using (2.11)<sub>2</sub>, we get

$$-\bar{g}(\nabla_{FY}X, N) + g(\nabla_YX, U) + \theta(U)g(X, Y) = 0. \quad (3.13)$$

Replacing  $X$  by  $V$  to (3.13) and using (2.10) and (3.8), we have

$$B(FY, U) + \tau(Y) = 0.$$

Taking  $Y = U$  to this equation and using the fact that  $FU = 0$ , we obtain

$$\tau(U) = 0. \quad (3.14)$$

Replacing  $X$  by  $\xi$  to (3.13) and using (2.6) and (2.10), we have

$$B(X, U) = \tau(FX). \tag{3.15}$$

From this equation and (3.6), we see that

$$u(A_N X) = \tau(FX) + \theta(V)\eta(X). \tag{3.16}$$

Replacing  $X$  by  $U$  to (3.10) and using (2.11), (3.6) and (3.7), we obtain

$$u(Y)A_N U - F(A_N FY) - A_N Y - \tau(FY)U + \eta(Y)\zeta + v(Y)F\zeta = 0.$$

Taking the scalar product with  $V$  to this and using (3.16), we get  $\tau(FY) = 0$ .

Taking  $Y = FX$  to  $\tau(FY) = 0$  and using (3.5) and (3.14), we have

$$\tau(X) = 0, \quad \forall X \in \Gamma(TM).$$

(3) As  $\tau = 0$ , using (2.10) and (3.15), we have  $g(A_\xi^* U, X) = 0$ , As  $S(TM)$  is non-degenerate, we get  $A_\xi^* U = 0$ . Replacing  $X$  by  $\xi$  to (3.11) and using (2.12) and the fact that  $\tau = 0$ , we obtain  $A_\xi^* V = 0$ .  $\square$

#### 4. HYPERSURFACES OF AN INDEFINITE COMPLEX SPACE FORM

Denote by  $\bar{R}$ ,  $R$  and  $R^*$  the curvature tensors of the semi-symmetric metric connection  $\bar{\nabla}$  on  $\bar{M}$ , and the induced linear connections  $\nabla$  and  $\nabla^*$  on  $M$  and  $S(TM)$ , respectively. Using the Gauss-Weingarten formulae, we obtain Gauss equations for  $M$  and  $S(TM)$ , respectively, such that

$$\begin{aligned} \bar{R}(X, Y)Z &= R(X, Y)Z + B(X, Z)A_N Y - B(Y, Z)A_N X \\ &+ \{(\nabla_X B)(Y, Z) - (\nabla_Y B)(X, Z) \\ &+ [\tau(X) - \theta(X)]B(Y, Z) - [\tau(Y) - \theta(Y)]B(X, Z)\}N, \end{aligned} \tag{4.1}$$

$$\begin{aligned} R(X, Y)PZ &= R^*(X, Y)PZ + C(X, PZ)A_\xi^* Y - C(Y, PZ)A_\xi^* X \\ &+ \{(\nabla_X C)(Y, PZ) - (\nabla_Y C)(X, PZ) \\ &- [\tau(X) + \theta(X)]C(Y, PZ) + [\tau(Y) + \theta(Y)]C(X, PZ)\}\xi. \end{aligned} \tag{4.2}$$

**Definition 4.1.** An indefinite complex space form  $\bar{M}(c)$  is a connected indefinite Kaehler manifold of constant holomorphic sectional curvature  $c$ ;

$$\begin{aligned} \tilde{R}(\bar{X}, \bar{Y})\bar{Z} &= \frac{c}{4}\{\bar{g}(\bar{Y}, \bar{Z})\bar{X} - \bar{g}(\bar{X}, \bar{Z})\bar{Y} \\ &+ \bar{g}(J\bar{Y}, \bar{Z})J\bar{X} - \bar{g}(J\bar{X}, \bar{Z})J\bar{Y} + 2\bar{g}(\bar{X}, J\bar{Y})J\bar{Z}\}, \end{aligned} \tag{4.3}$$

where  $\tilde{R}$  is the curvature tensor of the Levi-Civita connection  $\tilde{\nabla}$  on  $\bar{M}$ .

By directed calculations from (1.1) and (1.2), we see that

$$\begin{aligned} \bar{R}(\bar{X}, \bar{Y})\bar{Z} &= \tilde{R}(\bar{X}, \bar{Y})\bar{Z} + \bar{g}(\bar{X}, \bar{Z})\bar{\nabla}_{\bar{Y}}\zeta - \bar{g}(\bar{Y}, \bar{Z})\bar{\nabla}_{\bar{X}}\zeta \\ &+ \{(\bar{\nabla}_{\bar{X}}\theta)(\bar{Z}) - \bar{g}(\bar{X}, \bar{Z})\}\bar{Y} - \{(\bar{\nabla}_{\bar{Y}}\theta)(\bar{Z}) - \bar{g}(\bar{Y}, \bar{Z})\}\bar{X}. \end{aligned} \tag{4.4}$$

Taking the scalar product with  $\xi$  and  $N$  to (4.4) by turns and then, substituting (4.1) and (4.3) into the resulting equation and using (2.11)<sub>2</sub>, (3.4) and the fact that  $\bar{\nabla}$  is a metric connection, we obtain

$$\begin{aligned} & (\nabla_X B)(Y, Z) - (\nabla_Y B)(X, Z) \\ & + \{\tau(X) - \theta(X)\}B(Y, Z) - \{\tau(Y) - \theta(Y)\}B(X, Z) \\ & - g(X, Z)B(Y, \zeta) + g(Y, Z)B(X, \zeta) \\ & = \frac{c}{4}\{u(X)g(FY, Z) - u(Y)g(FX, Z) + 2u(Z)\bar{g}(X, JY)\}, \end{aligned} \quad (4.5)$$

$$\begin{aligned} & (\nabla_X C)(Y, PZ) - (\nabla_Y C)(X, PZ) \\ & - \{\tau(X) + \theta(X)\}C(Y, PZ) + \{\tau(Y) + \theta(Y)\}C(X, PZ) \\ & - g(X, PZ)C(Y, \zeta) + g(Y, PZ)C(X, \zeta) \\ & - (\bar{\nabla}_X \theta)(PZ)\eta(Y) + (\bar{\nabla}_Y \theta)(PZ)\eta(X) \\ & = \left(\frac{c}{4} + 1\right)\{\eta(X)g(Y, PZ) - \eta(Y)g(X, PZ)\} \\ & + \frac{c}{4}\{v(X)g(FY, PZ) - v(Y)g(FX, PZ) + 2v(PZ)\bar{g}(X, JY)\}. \end{aligned} \quad (4.6)$$

**Definition 4.2.** ([5]) The structure vector field  $U$  is called *principal* (with respect to  $A_\xi^*$ ) if there exists a smooth function  $\alpha$  on  $\mathcal{U}$  such that

$$A_\xi^* U = \alpha U. \quad (4.7)$$

A lightlike hypersurface  $M$  of an indefinite Kaehler manifold is called a *Hopf lightlike hypersurface* [5] if it admits a principal structure vector field  $U$ .

**Definition 4.3.** ([2]) A lightlike hypersurface  $M$  is said to be *screen conformal* if there exists a non-vanishing smooth function  $\varphi$  on  $\mathcal{U}$  such that

$$C(X, PY) = \varphi B(X, Y). \quad (4.8)$$

**Theorem 4.4.** Let  $M$  be a lightlike hypersurface of an indefinite complex space form  $\bar{M}(c)$  with a semi-symmetric non-metric connection subject such that  $\zeta$  belongs to  $S(TM)$ . If one of the following conditions is satisfied;

- (1)  $M$  is Lie recurrent,
- (2)  $M$  is Hopf lightlike hypersurface, and
- (3)  $M$  is screen conformal,

then  $c = 0$ , i.e.,  $\bar{M}(c)$  is flat.

*Proof.* (1) In case  $M$  is Lie recurrent. As  $\tau = 0$ , from (3.15) we obtain

$$B(Y, U) = 0. \quad (4.9)$$

Applying  $\nabla_X$  to this equation and using (3.7) and (4.9), we have

$$\begin{aligned} (\nabla_X B)(Y, U) & = -B(Y, F(A_N X)) - \theta(U)B(X, Y) \\ & + v(X)B(Y, \zeta) + \eta(X)B(Y, F\zeta). \end{aligned}$$



Substituting the last two equations into (4.5), we have

$$\begin{aligned} & B(X, F(A_N Y)) - B(Y, F(A_N X)) \\ & + \eta(X)B(Y, F\zeta) - \eta(Y)B(X, F\zeta) \\ & = \frac{c}{4}\{u(Y)\eta(X) - u(X)\eta(Y) + 2\bar{g}(X, JY)\}. \end{aligned}$$

Taking  $X = \xi$  and  $Y = U$  to this and using (2.9) and (4.9), we get  $c = 0$ .

(2) Taking the scalar product with  $X$  to (4.7) and using (2.10), we get

$$B(X, U) = \alpha v(X), \quad C(X, V) = \alpha v(X) + \theta(V)\eta(X), \quad (4.10)$$

due to (3.6). Applying  $\nabla_X$  to  $v(Y) = g(X, U)$  and using (2.7), (2.11)<sub>2</sub>, (3.4), (3.6), (3.7) and (4.10)<sub>1</sub>, we obtain

$$\begin{aligned} (\nabla_X v)Y &= v(Y)\tau(X) - \theta(Y)v(X) - g(A_N X, FY) \\ &+ \theta(U)g(X, Y) + \theta(FY)\eta(X). \end{aligned} \quad (4.11)$$

Applying  $\nabla_X$  to  $B(Y, U) = \alpha v(Y)$  and using (3.7) and (4.11), we have

$$\begin{aligned} (\nabla_X B)(Y, U) &= (X\alpha)v(Y) - B(Y, F(A_N X)) - \theta(U)B(X, Y) \\ &+ v(X)B(Y, \zeta) + \eta(X)B(Y, F\zeta) \\ &- \alpha\{\theta(Y)v(X) + g(A_N X, FY) \\ &- \theta(U)g(X, Y) - \theta(FY)\eta(X)\}. \end{aligned}$$

Substituting this equation and (4.10)<sub>1</sub> into (4.5) such that  $Z = U$ , we have

$$\begin{aligned} & \{X\alpha + \alpha\tau(X)\}v(Y) - \{Y\alpha + \alpha\tau(Y)\}v(X) \\ & + \{B(Y, F\zeta) + \alpha\theta(FY)\}\eta(X) - \{B(X, F\zeta) + \alpha\theta(FX)\}\eta(Y) \\ & + g(A_N X, F(A_\xi^* Y) - \alpha FY) - g(A_N Y, F(A_\xi^* X) - \alpha FX) \\ & = \frac{c}{4}\{u(Y)\eta(X) - u(X)\eta(Y) + 2\bar{g}(X, JY)\}. \end{aligned}$$

Taking  $X = \xi$  and  $Y = U$  and using (2.9), (2.12), (3.4), (4.7), (4.10)<sub>1,2</sub> and the facts that  $B(U, F\zeta) = 0$ ,  $C(U, V) = 0$ ,  $FU = 0$ ,  $F\xi = -V$ , we get  $c = 0$ .

(3) If  $M$  is screen conformal, then, using (3.6) and (4.8), we have

$$B(X, U - \varphi V) = -\theta(V)\eta(X).$$

Replacing  $X$  by  $\xi$  to this equation and using (2.9), we obtain

$$\theta(V) = 0, \quad B(X, U - \varphi V) = 0. \quad (4.12)$$

Applying  $\bar{\nabla}_X$  to  $\theta(V) = 0$  and using (2.10), (3.4), (3.8) and (4.12)<sub>1</sub>, we get

$$(\bar{\nabla}_X \theta)(V) = B(X, F\zeta) + u(X). \quad (4.13)$$

Applying  $\nabla_X$  to  $C(Y, PZ) = \varphi B(Y, PZ)$ , we have

$$(\nabla_X C)(Y, PZ) = (X\varphi)B(Y, PZ) + \varphi(\nabla_X B)(Y, PZ).$$

Substituting this equation into (4.6) and using (4.5), we have

$$\begin{aligned} & \{X\varphi - 2\varphi\tau(X)\}B(Y, PZ) - \{Y\varphi - 2\varphi\tau(Y)\}B(X, PZ) \\ & - (\bar{\nabla}_X\theta)(PZ)\eta(Y) + (\bar{\nabla}_Y\theta)(PZ)\eta(X) \\ = & \left(\frac{c}{4} + 1\right)\{\eta(X)g(Y, PZ) - \eta(Y)g(X, PZ)\} \\ & + \frac{c}{4}\{[v(X) - \varphi u(X)]g(FY, PZ) - [v(Y) - \varphi u(Y)]g(FX, PZ) \\ & + 2[v(PZ) - \varphi u(PZ)]\bar{g}(X, JY)\}. \end{aligned}$$

Taking  $Y = \xi$  and  $PZ = V$  to this and using (2.9) and (4.13), we have

$$\{\xi\varphi - 2\varphi\tau(\xi)\}B(X, V) + B(X, F\zeta) = \frac{3}{4}cu(X).$$

Taking  $X = U - \varphi V$  to this equation and using (4.12)<sub>2</sub>, we obtain  $c = 0$ .  $\square$

**Definition 4.5.** ([1]) A screen distribution  $S(TM)$  is called *totally umbilical* if there exists a smooth function  $\gamma$  on a neighborhood  $\mathcal{U}$  such that

$$C(X, PY) = \gamma g(X, PY). \quad (4.14)$$

**Theorem 4.6.** *Let  $M$  be a lightlike hypersurface of an indefinite complex space form  $\bar{M}(c)$  with a semi-symmetric non-metric connection subject such that  $\zeta$  belongs to  $S(TM)$ . If  $S(TM)$  is totally umbilical, then  $c = 0$ , i.e.,  $\bar{M}(c)$  is flat, and  $\gamma = 0$ , i.e.,  $S(TM)$  is totally geodesic*

*Proof.* From (2.11), (3.6) and (4.14), we see that  $A_N X = \gamma PX$  and

$$B(X, U) = \gamma u(X) - \theta(V)\eta(X).$$

Replacing  $X$  by  $\xi$ ,  $V$ ,  $U$  and  $\zeta$  to this by turns and using (2.9), we obtain

$$\theta(V) = 0, \quad B(V, U) = 0, \quad B(U, U) = \gamma, \quad B(U, \zeta) = 0, \quad (4.15)$$

$$B(X, U) = \gamma u(X). \quad (4.16)$$

Applying  $\bar{\nabla}_X$  to  $\theta(V) = 0$  and using (2.10), (3.4), (3.8) and (4.15)<sub>1</sub>, we get

$$(\bar{\nabla}_X\theta)(V) = B(X, F\zeta) + u(X).$$

Taking  $Y = F\zeta$  to (4.16), we get  $B(U, F\zeta) = 0$ . Replacing  $X$  by  $U$  to the last equation and using the fact that  $B(U, F\zeta) = 0$ , we obtain

$$(\bar{\nabla}_U\theta)(V) = 1. \quad (4.17)$$

Applying  $\nabla_X$  to  $C(Y, PZ) = \gamma g(Y, PZ)$  and using (2.7), we obtain

$$(\nabla_X C)(Y, PZ) = (X\gamma)g(Y, PZ) + \gamma B(X, PZ)\eta(Y).$$

Substituting this equation and (4.14) into (4.6), we have

$$\begin{aligned} & \{X\gamma - \gamma\tau(X) - [\frac{c}{4} + 1]\eta(X)\}g(Y, PZ) \\ & - \{Y\gamma - \gamma\tau(Y) - [\frac{c}{4} + 1]\eta(Y)\}g(X, PZ) \\ & + \gamma\{B(X, PZ)\eta(Y) - B(Y, PZ)\eta(X)\} \\ & - (\bar{\nabla}_X\theta)(PZ)\eta(Y) + (\bar{\nabla}_Y\theta)(PZ)\eta(X) \\ & = \frac{c}{4}\{v(X)g(FY, PZ) - v(Y)g(FX, PZ) + 2v(PZ)\bar{g}(X, JY)\}. \end{aligned}$$

Replacing  $Y$  by  $\xi$  to this equation and using (2.9), (3.2) and (3.3), we have

$$\begin{aligned} \gamma B(X, PZ) &= \{\xi\gamma - \gamma\tau(\xi) - \frac{c}{4} - 1\}g(X, PZ) \tag{4.18} \\ &+ (\bar{\nabla}_X\theta)(PZ) - (\bar{\nabla}_\xi\theta)(PZ)\eta(X) \\ &- \frac{c}{4}\{v(X)u(PZ) + 2u(X)v(PZ)\}. \end{aligned}$$

Taking  $X = U$  and  $PZ = V$  to (4.18) and using (4.15)<sub>2</sub> and (4.17), we have

$$\xi\gamma - \gamma\tau(\xi) = \frac{3}{4}c. \tag{4.19}$$

Applying  $\bar{\nabla}_X$  to  $g(\zeta, \zeta) = 1$  and using the fact that  $\bar{\nabla}$  is metric, we obtain

$$(\bar{\nabla}_X\theta)(\zeta) = 0. \tag{4.20}$$

Taking  $X = U$  and  $PZ = \zeta$  to (4.18) and using (4.15)<sub>1,4</sub>, (4.19) and (4.20), we get  $\theta(U) = 0$ . As  $\bar{g}(J\zeta, \zeta) = 0$ , we see that  $g(F\zeta, \zeta) = 0$ . Thus

$$\theta(U) = 0, \quad g(F\zeta, \zeta) = 0. \tag{4.21}$$

Applying  $\bar{\nabla}_X$  to  $\theta(U) = 0$  and using (3.7), (4.14) and (4.21), we obtain

$$(\bar{\nabla}_X\theta)(U) = \gamma g(X, F\zeta) + v(X).$$

Taking  $X = V$  and  $X = U$  to this equation by turns, we obtain

$$(\bar{\nabla}_V\theta)(U) = 1, \quad (\bar{\nabla}_U\theta)(U) = 0. \tag{4.22}$$

Taking  $X = V$  and  $PZ = U$  to (4.18) and using (4.15)<sub>2</sub>, (4.19) and (4.22)<sub>1</sub>, we have  $c = 0$ . As  $c = 0$ , the equation (4.18) reduces

$$\gamma B(X, PY) = -g(X, PZ) + (\bar{\nabla}_X\theta)(PZ) - (\bar{\nabla}_\xi\theta)(PZ)\eta(X).$$

Taking  $X = Z = U$  to this equation and using (4.15)<sub>3</sub> and (4.22)<sub>2</sub>, we have  $\gamma = 0$ . Thus  $S(TM)$  is totally geodesic. □

**Theorem 4.7.** *Let  $M$  be a lightlike hypersurface of an indefinite Kaehler manifold  $\bar{M}$  with a semi-symmetric non-metric connection  $\nabla$  such that  $\tau = 0$  and  $\zeta$  belongs to  $S(TM)$ . If  $U$  is parallel with respect to  $\nabla$ , then  $c = 0$ .*

*Proof.* Taking the scalar product with  $V$  to (3.7) and using  $\tau = 0$ , we get

$$\theta(U)u(X) - \theta(V)v(X) = 0.$$

Taking  $X = U$  and  $X = V$  to this equation by turns, we have

$$\theta(U) = 0, \quad \theta(V) = 0. \quad (4.23)$$

Taking the scalar product with  $\zeta$ ,  $F\zeta$  and  $N$  to (3.7) by turns and using (4.23) and the fact that  $\tau = 0$ , we obtain

$$g(F(A_N X), \zeta) = v(X), \quad g(A_N X, \zeta) = \eta(X), \quad C(X, U) = 0. \quad (4.24)$$

Applying  $\bar{\nabla}_X$  to  $\theta(U) = 0$  and using (3.7) and (4.24)<sub>1</sub>, we have

$$(\bar{\nabla}_X \theta)(U) = 0. \quad (4.25)$$

Applying  $\nabla_Y$  to (4.24)<sub>3</sub> and using the fact that  $\nabla_Y U = 0$ , we have

$$(\nabla_X C)(Y, U) = 0.$$

Substituting this equation and (4.24)<sub>3</sub> into (4.6) with  $PZ = U$  and using (4.24)<sub>2</sub> and (4.25), we have

$$\frac{c}{2} \{v(Y)\eta(X) - v(X)\eta(Y)\} = 0.$$

Taking  $X = \xi$  and  $Y = V$  to this equation, we obtain  $c = 0$ . □

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