Nonlinear Functional Analysis and Applications Vol. 17, No. 1 (2012), pp. 71-87

http://nfaa.kyungnam.ac.kr/jour-nfaa.htm Copyright \bigodot 2012 Kyungnam University Press

REGULARIZATION FOR A SYSTEM OF INVERSE-STRONGLY MONOTONE OPERATOR EQUATIONS

Nguyen thi Thu Thuy

College of Sciences, Thainguyen University Quyetthang, Thainguyen, Vietnam e-mail: thuychip04@yahoo.com

Abstract. In this paper, we introduce a regularization process of finding a common element of a system of operator equations for inverse-strongly monotone operators in real Banach spaces, and then give a convergence theorem. The convergence rates of regularized solutions are estimated by using a regularization parameter-choice that is based upon the generalized discrepancy principle. Further, we consider an iterative regularization method of zero order for solving system of inverse-strongly monotone operator equations in real Hilbert spaces.

1. INTRODUCTION

Let X be a real reflexive Banach space having property E-S (i.e. weak and norm convergences of any sequence in X imply its strong convergences). Let X and its dual space be strictly convex. For the sake of simplicity, the norms of X and X^{*} are denoted by the same symbol $\|.\|$. We write $\langle x^*, x \rangle$ instead of $x^*(x)$ for $x^* \in X^*$ and $x \in X$.

Let $A_j: X \to X^*$ be a family of hemicontinuous monotone operators defined on $X, f_j \in X^*, j = 1, ..., N$. Set $S_j = \{\bar{x} \in X : A_j(\bar{x}) = f_j\}$. It is easy to see that S_j is closed convex subset in X (see [10]). Assume that $S = \bigcap_{j=1}^N S_j \neq \emptyset$. We consider the following problem

finding an element
$$x^0 \in S$$
. (1.1)

⁰Received February 8, 2011. Revised March 3, 2012.

⁰2000 Mathematics Subject Classification: 47J06, 47A52, 65F22, 47H05.

⁰Keywords: System of operator equations for inverse-strongly monotone operators, regularized solution, regularization parameter-choice, iterative regularization.

Nguyen Thi Thu Thuy

Without additional conditions on A_j such as the strongly or uniformly monotone property, each equation $A_j(x) = f_j$ is an ill-posed problem. By this, we mean that the solution set S_j does not depend continuously on the data (A_j, f_j) . Therefore, to find a solution of this equation, we have to use stable methods. One of these methods is the Tikhonov regularization in the form (see [1])

$$A_{j}^{h}(x) + \alpha U^{s}(x - x_{*}) = f_{j}^{\delta}, \qquad (1.2)$$

where $\alpha > 0$ is a regularization parameter, U^s is the generalized duality mapping of X, A_j^h is a monotone bounded hemicontinuous operator on X, (A_j^h, f_j^δ) are approximation of (A_j, f_j) in the sense that

$$||A_{j}^{h}(x) - A_{j}(x)|| \le hg(||x||), \quad ||f_{j}^{\delta} - f_{j}|| \le \delta$$
(1.3)

with levels $(h, \delta) \to 0$, g(t) is a non-negative bounded function for $t \ge 0$ and x_* is in X which plays the role of a criterion of selection.

Let $\tau = (h, \delta)$. For each j, equation (1.2) has a unique solution $x_j^{\alpha, \tau}$ and if $h/\alpha, \, \delta/\alpha, \, \alpha \to 0$ then $x_j^{\alpha, \tau} \to x_j \in S_j$ with x_* -minimal norm (see [1]), i.e.

$$||x_j - x_*|| = \min_{x \in S_j} ||x - x_*||, \quad j = 1, ..., N.$$

In this paper, we consider the more general problem, that is to find a common element x_{α}^{τ} of the solution sets of equations involving inverse-strongly monotone operators such that $x_{\alpha}^{\tau} \to x^0 \in S$ as $h, \delta, \alpha \to 0$ and estimate the value of $||x_{\alpha}^{\tau} - x^0||$ based on regularization parameter choice by the generalized discrepancy principle. Moreover, we propose an iterative regularization method of zero order that is a parallel algorithm. This algorithm generates a sequence $\{z_n\}$ from an arbitrary initial $z_0 \in H$, where H is a real Hilbert space. The sequence $\{z_n\}$ is shown to converge to $x^0 \in S$.

We now recall some definitions (see [5, 13]).

Definition 1.1. An operator $A: D(A) \equiv X \to X^*$ is called inverse-strongly monotone if

$$\langle A(x) - A(y), x - y \rangle \ge m_A ||A(x) - A(y)||^2, \ \forall x, y \in X, \ m_A > 0,$$
 (1.4)

where m_A is a positive constant.

Definition 1.2. An operator $U^s : X \to X^*$ is called the generalized duality mapping of X if

$$U^{s}(x) = \{x^{*} \in X^{*} : \langle x^{*}, x \rangle = \|x^{*}\|^{s-1}\|x\| = \|x\|^{s}\}, \ s \ge 2.$$

Assume that the generalized duality mapping U^s satisfies the following condition

$$\langle U^{s}(x) - U^{s}(y), x - y \rangle \ge m_{U} ||x - y||^{s}, \ \forall x, y \in X,$$
 (1.5)

where m_U is a positive constant. It is well-known that when X is a Hilbert space then $U^s = I$, s = 2 and $m_s = 1$, where I denotes the identity operator in the setting space (see [2]).

2. Main result

For approximations to a solution of (1.1), we introduce the following regularized problem of finding an $x_{\alpha}^{\tau} \in X$ such that (see Nguyen Buong [9])

$$\sum_{j=1}^{N} \alpha^{\lambda_j} (A_j^h(x_{\alpha}^{\tau}) - f_j^{\delta}) + \alpha U^s(x_{\alpha}^{\tau} - x_*) = \theta,$$

$$\lambda_1 = 0 < \lambda_j < \lambda_{j+1} < 1, \quad j = 2, ..., N - 1.$$
(2.1)

We have the following result.

Lemma 2.1. Let X be an E-S space with strictly convex dual space X^* , $A_j^h: X \to X^*$ be a monotone bounded hemicontinuous operator for all h > 0, $U^s: X \to X^*$ be a generalized duality mapping and $f_j^{\delta} \in X^*$ for all $\delta > 0$. Then Problem (2.1) has an unique solution x_{α}^{τ} for all $\alpha > 0$.

Proof. Since A_j^h is a monotone bounded hemicontinuous operator so it is a maximal monotone (see [5]). This implies that $\sum_{j=1}^{N} \alpha^{\lambda_j} A_j^h + \alpha U^s$ is also maximal monotone and coercitive (see [5, 6]). Then Theorem 1.7.4 in [3] guaranties the solvability of equation (2.1) in the sense of inclusion. Let x_{α}^{τ} be a solution of (2.1). It is unique because the operator $\sum_{j=1}^{N} \alpha^{\lambda_j} A_j^h + \alpha U^s$ is strictly monotone.

The solution x_{α}^{τ} satisfying (2.1) will be view as the regularized solution of problem (1.1).

Theorem 2.1. Let X and X^* be strictly convex spaces, A_j be a inversestrongly monotone, A_j^h be a monotone bounded hemicontinuous operator, and $U^s: X \to X^*$ a generalized duality mapping. Assume that (1.3) and (1.5) hold. If

$$\frac{h+\delta}{\alpha} \to 0 \ as \ \alpha \to 0, \tag{2.2}$$

then the sequence $\{x_{\alpha}^{\tau}\}$ of solutions of the equation (2.1) converges strongly in X to $x^{0} \in S$ with x_{*} -minimal norm. *Proof.* For $x \in S$, it follows from (1.1) and (2.1) that

$$\sum_{j=1}^{N} \alpha^{\lambda_j} \langle A_j^h(x_\alpha^\tau) - f_j^\delta - A_j(x) + f_j, x_\alpha^\tau - x \rangle + \alpha \langle U^s(x_\alpha^\tau - x_*) - U^s(x - x_*), x_\alpha^\tau - x \rangle = \alpha \langle U^s(x - x_*), x - x_\alpha^\tau \rangle.$$

Using (1.5) we obtain

$$\alpha m_U \|x_{\alpha}^{\tau} - x\|^s \le \sum_{j=1}^N \alpha^{\lambda_j} \langle A_j^h(x_{\alpha}^{\tau}) - A_j^h(x) + A_j^h(x) - A_j(x) + f_j - f_j^{\delta}, x - x_{\alpha}^{\tau} \rangle + \alpha \langle U^s(x - x_*), x - x_{\alpha}^{\tau} \rangle.$$

It follows from (1.3) and the monotonicity of ${\cal A}^h_j$ that

$$m_U \|x_{\alpha}^{\tau} - x\|^s \le \frac{1}{\alpha} N(hg(\|x\|) + \delta) \|x - x_{\alpha}^{\tau}\| + \langle U^s(x - x_*), x - x_{\alpha}^{\tau} \rangle.$$
(2.3)

Now from (2.2) and (2.3) we conclude that the sequence $\{x_{\alpha}^{\tau}\}$ is bounded. So there exists a subsequence $\{x_{\beta}^{\nu}\}$, where $\beta \subseteq \alpha$ and $\nu = (h', \delta') \subseteq \tau$, which weakly converges to some element $\hat{x} \in X$. We also have

$$\frac{h'+\delta'}{\beta} \to 0 \text{ as } \alpha \to 0.$$

First, we prove that $\hat{x} \in S_1$. Indeed, for an arbitrary $x \in X$, by virtue of the monotonicity of A_j^h and the property of U^s and (2.1) we have

$$\begin{split} \langle A_1^{h'}(x) - f_1^{\delta'}, x - x_{\beta}^{\nu} \rangle &\geq \langle A_1^{h'}(x_{\beta}^{\nu}) - f_1^{\delta'}, x - x_{\beta}^{\nu} \rangle \\ &= \sum_{j=2}^N \beta^{\lambda_j} \langle A_j^{h'}(x_{\beta}^{\nu}) - f_j^{\delta'}, x_{\beta}^{\nu} - x \rangle \\ &\quad + \beta \langle U^s(x_{\beta}^{\nu} - x_*), x_{\beta}^{\nu} - x \rangle \\ &\geq \sum_{j=2}^N \beta^{\lambda_j} \langle A_j^{h'}(x) - f_j^{\delta'}, x_{\beta}^{\nu} - x \rangle + \beta \langle U^s(x - x_*), x_{\beta}^{\nu} - x \rangle \end{split}$$

Letting $\alpha \to 0$, and so $\beta \to 0$ and $\nu \to 0$, we obtain from the last inequality and (1.3) the limit inequality

$$\langle A_1(x) - f_1, x - \hat{x} \rangle \ge 0, \quad \forall x \in X.$$

Consequently, by Minty's lemma $\hat{x} \in S_1$ (see [14]). Now, we shall prove that $\hat{x} \in S_j, j = 2..., N$. Indeed, by (2.1) and making use of the monotonicity of

 $A_j^{h'}$, it follows that

$$\langle A_{2}^{h'}(x_{\beta}^{\nu}) - f_{2}^{\delta'}, x_{\beta}^{\nu} - x \rangle + \sum_{j=3}^{N} \beta^{\lambda_{j} - \lambda_{2}} \langle A_{j}^{h'}(x_{\beta}^{\nu}) - f_{j}^{\delta'}, x_{\beta}^{\nu} - x \rangle + \beta^{1 - \lambda_{2}} \langle U^{s}(x_{\beta}^{\nu} - x_{*}), x_{\beta}^{\nu} - x \rangle = \frac{1}{\beta^{\lambda_{2}}} \langle A_{1}^{h'}(x_{\beta}^{\nu}) - A_{1}^{h'}(x) + A_{1}^{h'}(x) - A_{1}(x) + f_{1} - f_{1}^{\delta'}, x - x_{\beta}^{\nu} \rangle \leq \frac{\beta^{1 - \lambda_{2}}}{\beta} (h'g(||x||) + \delta') ||x - x_{\beta}^{\nu}||, \quad \forall x \in S_{1}.$$

After letting $\alpha \to 0$ we obtain

$$\langle A_2(\hat{x}) - f_2, \hat{x} - x \rangle \le 0, \quad \forall x \in S_1.$$
 (2.4)

Let \tilde{x} be an element in $S_1 \cap S_2$. It follows from (2.4) that

$$0 = \langle A_2(\tilde{x}) - f_2, \tilde{x} - \hat{x} \rangle \ge \langle A_2(\hat{x}) - f_2, \tilde{x} - \hat{x} \rangle \ge 0.$$

Hence,

$$\langle A_2(\hat{x}) - f_2, \tilde{x} - \hat{x} \rangle = 0 = \langle A_2(\tilde{x}) - f_2, \tilde{x} - \hat{x} \rangle.$$

Consequently $\langle A_2(\tilde{x}) - A_2(\hat{x}), \tilde{x} - \hat{x} \rangle = 0$. Using the inverse-strongly monotonicity of A_2 we have

$$0 = \langle A_2(\tilde{x}) - A_2(\hat{x}), \tilde{x} - \hat{x} \rangle \ge m_{A_2} \|A_2(\tilde{x}) - A_2(\hat{x})\|^2 \ge 0.$$

Therefore,

$$A_2(\hat{x}) - f_2 = A_2(\tilde{x}) - f_2 = 0.$$

So, $\hat{x} \in S_2$.

So, $x \in S_2$. Set $\tilde{S}_i = \bigcap_{k=1}^i S_k$. Then, \tilde{S}_i is also closed convex, and $\tilde{S}_i \neq \emptyset$. Now, suppose that $\hat{x} \in \tilde{S}_i$, and we need to show that \hat{x} belongs to S_{i+1} . Again, by virtue of (2.1) for $x \in \tilde{S}_i$, we can write

$$\begin{split} \langle A_{i+1}^{h'}(x_{\beta}^{\nu}) - f_{i+1}^{\delta'}, x_{\beta}^{\nu} - x \rangle &+ \sum_{j=i+2}^{N} \beta^{\lambda_{j} - \lambda_{i+1}} \langle A_{j}^{h'}(x_{\beta}^{\nu}) - f_{j}^{\delta'}, x_{\beta}^{\nu} - x \rangle \\ &+ \beta^{1 - \lambda_{i+1}} \langle U^{s}(x_{\beta}^{\nu} - x_{*}), x_{\beta}^{\nu} - x \rangle \\ &= \sum_{k=1}^{i} \beta^{\lambda_{k} - \lambda_{i+1}} \langle A_{k}^{h'}(x_{\beta}^{\nu}) - f_{k}^{\delta'}, x - x_{\beta}^{\nu} \rangle \\ &\leq \frac{1}{\beta} \sum_{k=1}^{i} \beta^{\lambda_{k} + 1 - \lambda_{i+1}} \langle A_{k}^{h'}(x) - A_{k}(x) + f_{k} - f_{k}^{\delta'}, x - x_{\beta}^{\nu} \rangle \\ &\leq \frac{1}{\beta} N \big(h'g(\|x\|) + \delta' \big) \|x - x_{\beta}^{\nu} \|. \end{split}$$

Therefore, by letting $\alpha \to 0$ we have

$$\langle A_{i+1}(\hat{x}) - f_{i+1}, \hat{x} - x \rangle \le 0, \quad \forall x \in S_i.$$

By an argument analogous to the previous one, we get $\hat{x} \in S_{i+1}$, which means that $\hat{x} \in S$.

On the other hand, it follows from (2.3) that

$$\langle U^s(x-x_*), x-\hat{x} \rangle \ge 0, \quad \forall x \in S.$$

 S_j is closed convex, so is S. Replacing x by $t\hat{x} + (1-t)x$, $t \in (0,1)$ in the last inequality, dividing by (1-t) and letting t to 1, we obtain

$$\langle U^s(\hat{x} - x_*), x - \hat{x} \rangle \ge 0, \quad \forall x \in S.$$

Hence $\|\hat{x} - x_*\| \leq \|x - x_*\|$, $\forall x \in S$. Because of the convexity and the closedness of S, and the strictly convexity of X we deduce that $\hat{x} = x^0$. So, all sequence $\{x_{\alpha}^{\tau}\}$ converges weakly to x^0 . It follows from (2.3) that the sequence $\{x_{\alpha}^{\tau}\}$ converges strongly to x^0 . This completes the proof.

Now, we consider the problem of choosing $\tilde{\alpha} = \alpha(h, \delta)$ such that

$$\lim_{h,\delta\to 0} \alpha(h,\delta) = 0 \text{ and } \lim_{h,\delta\to 0} \frac{h+\delta}{\alpha(h,\delta)} = 0.$$

To solve this problem, we use the function for selecting $\tilde{\alpha} = \alpha(h, \delta)$ by generalized discrepancy principle, i.e. the relation $\tilde{\alpha} = \alpha(h, \delta)$ is constructed on the basis of the following equation

$$\rho(\tilde{\alpha}) = (h+\delta)^p \tilde{\alpha}^{-q}, \quad p,q > 0, \tag{2.5}$$

with $\rho(\tilde{\alpha}) = \tilde{\alpha}(c + ||x_{\tilde{\alpha}}^{\tau} - x_*||^{s-1})$, where $x_{\tilde{\alpha}}^{\tau}$ is the solution of (2.1) with $\alpha = \tilde{\alpha}$, c is some positive constant. Note that the generalized discrepancy principle was presented in [11] for linear ill-posed problems and then it was developed for nonlinear ones in [7]. We have the following results.

Lemma 2.2. Let X be an E-S space with a strictly convex dual space X^* , $A_j^h: X \to X^*$ be a monotone bounded hemicontinuous operator and $U^s: X \to X^*$ with condition (1.5) holds. Then the function $\rho(\alpha) = \alpha(c + ||x_{\alpha}^{\tau} - x_*||)$ is single-valued and continuous for $\alpha \ge \alpha_0 > 0$, where x_{α}^{τ} is the solution of (2.1).

Proof. Single-valued solvability of the equation (2.1) implies the continuity property of the function $\rho(\alpha)$. Let $\alpha_1, \alpha_2 \ge \alpha_0$ be arbitrary $(\alpha_0 > 0)$. It

follows from (2.1) that

$$\begin{split} &\sum_{j=1}^{N} \alpha_{1}^{\lambda_{j}} \langle A_{j}^{h}(x_{\alpha_{1}}^{\tau}) - f_{j}^{\delta}, x_{\alpha_{1}}^{\tau} - x_{\alpha_{2}}^{\tau} \rangle + \alpha_{1} \langle U^{s}(x_{\alpha_{1}}^{\tau} - x_{*}), x_{\alpha_{1}}^{\tau} - x_{\alpha_{2}}^{\tau} \rangle \\ &+ \sum_{j=1}^{N} \alpha_{2}^{\lambda_{j}} \langle A_{j}^{h}(x_{\alpha_{2}}^{\tau}) - f_{j}^{\delta}, x_{\alpha_{2}}^{\tau} - x_{\alpha_{1}}^{\tau} \rangle + \alpha_{2} \langle U^{s}(x_{\alpha_{2}}^{\tau} - x_{*}), x_{\alpha_{2}}^{\tau} - x_{\alpha_{1}}^{\tau} \rangle \\ &+ \sum_{j=1}^{N} \alpha_{2}^{\lambda_{j}} \langle A_{j}^{h}(x_{\alpha_{1}}^{\tau}) - f_{j}^{\delta}, x_{\alpha_{2}}^{\tau} - x_{\alpha_{1}}^{\tau} \rangle + \sum_{j=1}^{N} \alpha_{2}^{\lambda_{j}} \langle A_{j}^{h}(x_{\alpha_{1}}^{\tau}) - f_{j}^{\delta}, x_{\alpha_{1}}^{\tau} - x_{\alpha_{2}}^{\tau} \rangle = 0, \end{split}$$

where $x_{\alpha_1}^{\tau}$ and $x_{\alpha_2}^{\tau}$ are solutions of (2.1) with $\alpha = \alpha_1$ and $\alpha = \alpha_2$. Using the monotonicity of A_j^h we have

$$\begin{aligned} \alpha_1 \langle U^s(x_{\alpha_1}^{\tau} - x_*) - U^s(x_{\alpha_2}^{\tau} - x_*), x_{\alpha_1}^{\tau} - x_{\alpha_2}^{\tau} \rangle \\ &\leq (\alpha_2 - \alpha_1) \langle U^s(x_{\alpha_2}^{\tau} - x_*), x_{\alpha_1}^{\tau} - x_{\alpha_2}^{\tau} \rangle \\ &+ \sum_{j=1}^N (\alpha_2^{\lambda_j} - \alpha_1^{\lambda_j}) \langle A_j^h(x_{\alpha_1}^{\tau}) - f_j^{\delta}, x_{\alpha_1}^{\tau} - x_{\alpha_2}^{\tau} \rangle. \end{aligned}$$

It follows from (1.5) and the last inequality that

$$m_U \|x_{\alpha_1}^{\tau} - x_{\alpha_2}^{\tau}\|^{s-1} \le \frac{|\alpha_2 - \alpha_1|}{\alpha_0} \|x_{\alpha_2}^{\tau} - x_*\|^{s-1} + \sum_{j=1}^N \frac{|\alpha_2^{\lambda_j} - \alpha_1^{\lambda_j}|}{\alpha_0} \|A_j^h(x_{\alpha_1}^{\tau}) - f_j^{\delta}\|.$$

Obviously, $x_{\alpha_1}^{\tau} \to x_{\alpha_2}^{\tau}$ as $\alpha_1 \to \alpha_2$. It means that the function $||x_{\alpha}^{\tau} - x_*||$ is continuous on $[\alpha_0; +\infty)$. Therefore, $\rho(\alpha)$ is also continuous on $[\alpha_0; +\infty)$. \Box

Theorem 2.2. Let X and X^* be strictly convex spaces, A_j^h be a monotone bounded hemicontinuous operator, $U^s : X \to X^*$ be a duality mapping. Assume that (1.3) and (1.5) hold. Then

(i) There exists at least a solution $\tilde{\alpha}$ of the equation (2.5);

(ii) Let $\tau \to 0$. Then

(1) $\tilde{\alpha} \to 0;$

(2) If $0 then <math>\frac{h+\delta}{\tilde{\alpha}} \to 0$, $x_{\tilde{\alpha}}^{\tau} \to x^{0} \in S$ with x_{*} -minimal norm and there exits constants $C_{1}, C_{2}^{\tau} > 0$ such that for sufficiently small $h, \delta > 0$ the relation

$$C_1 \le (h+\delta)^p \alpha^{-1-q}(h,\delta) \le C_2$$

holds.

Proof. (i) For $0 < \alpha < 1$, it follows from (2.1) that

$$\sum_{j=1}^{N} \alpha^{\lambda_j} \langle A_j^h(x_\alpha^\tau) - f_j^\delta, x_\alpha^\tau - x_* \rangle + \alpha \langle U^s(x_\alpha^\tau - x_*), x_\alpha^\tau - x_* \rangle = 0.$$

Hence,

$$\begin{aligned} &\alpha \langle U^s(x_\alpha^\tau - x_*), x_\alpha^\tau - x_* \rangle \\ &\leq \sum_{j=1}^N \alpha^{\lambda_j} \langle A_j^h(x_*) - f_j^\delta, x_* - x_\alpha^\tau \rangle \\ &= \sum_{j=1}^N \alpha^{\lambda_j} \langle A_j^h(x_*) - A_j(x_*) + A_j(x_*) - f_j + f_j - f_j^\delta, x_* - x_\alpha^\tau \rangle. \end{aligned}$$

We invoke (1.3), (1.5) and the last inequality to deduce that

$$\alpha \|x_{\alpha}^{\tau} - x_{*}\|^{s-1} \le N \big(hg(\|x_{*}\|) + \|A_{j}(x_{*}) - f_{j}\| + \delta \big).$$
(2.6)

It follows from (2.6) and the form of $\rho(\alpha)$ that

$$\begin{aligned} \alpha^{q} \rho(\alpha) &= \alpha^{1+q} (c + \|x_{\alpha}^{\tau} - x_{*}\|^{s-1}) \\ &= c \alpha^{1+q} + \alpha^{q} \alpha \|x_{\alpha}^{\tau} - x_{*}\|^{s-1} \\ &\leq c \alpha^{1+q} + \alpha^{q} N \big(hg(\|x_{*}\|) + \|A_{j}(x_{*}) - f_{j}\| + \delta \big). \end{aligned}$$

Therefore, $\lim_{\alpha \to +0} \alpha^q \rho(\alpha) = 0.$ On the other hand,

$$\lim_{\alpha \to +\infty} \alpha^q \rho(\alpha) \ge c \lim_{\alpha \to +\infty} \alpha^{1+q} = +\infty.$$

Since $\rho(\alpha)$ is continuous, there exists at least one $\tilde{\alpha}$ which satisfies (2.5).

ii) It follows from (2.5) and the form of $\rho(\tilde{\alpha})$ that

$$\tilde{\alpha} \le c^{-1/(1+q)} (h+\delta)^{p/(1+q)}.$$

Therefore, $\tilde{\alpha} \to 0$ as $\tau \to 0$.

If 0 , it follows from (2.5) and (2.6) that

$$\left[\frac{h+\delta}{\tilde{\alpha}}\right]^{p} = \left[(h+\delta)^{p}\tilde{\alpha}^{-q}\right]\tilde{\alpha}^{q-p}$$
$$= \left[\tilde{\alpha}c + \tilde{\alpha}\|x_{\tilde{\alpha}}^{\tau} - x_{*}\|^{s-1}\right]\tilde{\alpha}^{q-p}$$
$$\leq c\tilde{\alpha}^{1+q-p} + \tilde{\alpha}^{q-p}N\left(hg(\|x_{*}\|) + \|A_{j}(x_{*}) - f_{j}\| + \delta\right).$$

 So

$$\lim_{h,\delta\to 0} \left[\frac{h+\delta}{\tilde{\alpha}}\right]^p = 0.$$

By Theorem 2.1 the sequence $x_{\tilde{\alpha}}^{\tau}$ converges to $x^0 \in S$ with x_* -minimal norm as $h, \delta \to 0$.

Clearly,

$$(h+\delta)^{p}\tilde{\alpha}^{-1-q} = \tilde{\alpha}^{-1}\rho(\tilde{\alpha}) = (c+\|x_{\tilde{\alpha}}^{\tau}-x_{*}\|^{s-1}),$$

therefore there exists a positive constant C_2 in the theorem. On the other hand, because c > 0 there exists a positive constant C_1 in the theorem. This completes the proof.

To estimate the convergence rates for the sequence $\{x_{\tilde{\alpha}}^{\tau}\}$, we assume that there exists a positive constant $\tilde{\tau}$ such that

$$||A_1(y) - A_1(x) - A_1'(x)(y - x)|| \le \tilde{\tau} ||A_1(y) - A_1(x)||, \quad \forall x \in S,$$
(2.7)

and y belongs to some neighbourhood of S.

Note that, Hanke, Neubauer and Scherzer [12] gave a first convergence analysis of the Landweber iteration method for a class of nonlinear operators with (2.7) when $\tilde{\tau} < 1/2$. The use of this assumption to estimate the convergence rates of the regularized solutions of ill-posed inverse-strongly monotone variational inequalities in Banach space was considered in [8].

Theorem 2.3. Let X and X^* be strictly convex spaces, A_j^h be a monotone bounded hemicontinuous operator, $U^s : X \to X^*$ be a duality mapping. Assume that (1.3) and (1.5) hold and,

(i) A_1 is Fréchet continuously differentiable with (2.7) for $x = x^0$;

(ii) there exists $z \in X$ such that $A'_1(x^0)^* z = U^s(x^0 - x_*);$

(iii) the parameter $\tilde{\alpha} = \alpha(h, \delta)$ is chosen by (2.5) with 0 . Then,

$$\|x_{\tilde{\alpha}}^{\tau} - x^{0}\| = O\left((h+\delta)^{\mu_{1}}\right), \quad \mu_{1} = \min\left\{\frac{1+q-p}{s(1+q)}, \frac{\lambda_{2}p}{s(1+q)}\right\}.$$

Proof. Replacing x by x^0 in (2.3) we obtain

$$m_U \|x_{\tilde{\alpha}}^{\tau} - x^0\|^s \leq \frac{1}{\tilde{\alpha}} N \left(hg(\|x^0\|) + \delta \right) \|x^0 - x_{\tilde{\alpha}}^{\tau}\| + \langle U^s(x^0 - x_*), x^0 - x_{\tilde{\alpha}}^{\tau} \rangle.$$
(2.8)
Using conditions (i), (ii) we can write

$$\langle U^{s}(x^{0} - x_{*}), x^{0} - x_{\tilde{\alpha}}^{\tau} \rangle = \langle z, A_{1}'(x^{0})(x^{0} - x_{\tilde{\alpha}}^{\tau}) \rangle$$

$$\leq \|z\|(\tilde{\tau}+1)\|A_{1}(x_{\tilde{\alpha}}^{\tau}) - A_{1}(x^{0})\|$$

$$\leq \|z\|(\tilde{\tau}+1)\left(hg(\|x_{\tilde{\alpha}}^{\tau}\|) + \|A_{1}^{h}(x_{\tilde{\alpha}}^{\tau}) - f_{1}^{\delta}\| + \delta\right)$$

$$\leq \|z\|(\tilde{\tau}+1)\left[\sum_{j=2}^{N} \tilde{\alpha}^{\lambda_{j}}\|A_{j}^{h}(x_{\tilde{\alpha}}^{\tau}) - f_{j}^{\delta}\|$$

$$+ \tilde{\alpha}\|x_{\tilde{\alpha}}^{\tau} - x_{*}\|^{s-1} + hg(\|x_{\tilde{\alpha}}^{\tau}\|) + \delta\right].$$

$$(2.9)$$

Combining with (2.8), the inequality (2.9) becomes

$$m_{U} \|x_{\tilde{\alpha}}^{\tau} - x^{0}\|^{s} \leq \frac{1}{\tilde{\alpha}} N \left(hg(\|x^{0}\|) + \delta \right) \|x^{0} - x_{\tilde{\alpha}}^{\tau}\| + \|z\|(\tilde{\tau}+1) \left[\sum_{j=2}^{N} \tilde{\alpha}^{\lambda_{j}} \|A_{j}^{h}(x_{\tilde{\alpha}}^{\tau}) - f_{j}^{\delta}\| + \tilde{\alpha} \|x_{\tilde{\alpha}}^{\tau} - x_{*}\|^{s-1} + hg(\|x_{\tilde{\alpha}}^{\tau}\|) + \delta \right].$$
(2.10)

Now, it follows from Theorem 2.2 that

$$\tilde{\alpha} \le C_1^{-1/(1+q)} (h+\delta)^{p/(1+q)},$$

and

$$\frac{h+\delta}{\tilde{\alpha}} \le C_2(h+\delta)^{1-p}\tilde{\alpha}^q$$
$$\le C_2C_1^{-q/(1+q)}(h+\delta)^{1-p/(1+q)}.$$

Therefore,

$$m_U \|x_{\tilde{\alpha}}^{\tau} - x^0\|^s \le \overline{C_1}(h+\delta)^{1-p/(1+q)} \|x^0 - x_{\tilde{\alpha}}^{\tau}\| + \overline{C_2}(h+\delta)^{\lambda_2 p/(1+q)},$$

where $\overline{C_i}, i=1,2$ are the positive constants. Using the implication

$$a, b, c \ge 0, \ s > t, \ a^s \le ba^t + c \Longrightarrow a^s = O(b^{s/(s-t)} + c),$$

we obtain

$$\|x_{\tilde{\alpha}}^{\tau} - x^{0}\| = O\big((h+\delta)^{\mu_{1}}\big).$$

Remark 2.1. If α is chosen a priory such that $\alpha \sim (h + \delta)^{\eta}$, $0 < \eta < 1$, it follows from (2.10) that

$$\|x_{\alpha}^{\tau} - x^{0}\| = O((h+\delta)^{\mu_{2}}), \ \mu_{2} = \min\left\{\frac{1-\eta}{s-1}, \frac{\lambda_{2}\eta}{s}\right\}.$$

And now, we consider the following iterative regularization method of zero order, where z_{n+1} is defined by

$$z_{n+1} = z_n - \beta_n \left[\sum_{j=1}^N \alpha_n^{\lambda_j} (A_j(z_n) - f_j) + \alpha_n(z_n - x_*) \right], \ z_0 \in H,$$
(2.11)

where H is a real Hilbert space, $\{\alpha_n\}$ and $\{\beta_n\}$ are sequences of positive numbers.

We consider the operator equation

$$\sum_{j=1}^{N} \alpha_n^{\lambda_j} (A_j(x) - f_j) + \alpha_n (x - x_*) = \theta.$$
 (2.12)

Theorem 2.4. Let X and X^* be strictly convex spaces, $A_j : X \to X^*$ be a monotone bounded hemicontinuous operator and inverse-strongly monotone. Assume that (1.3) holds. Then

(i) For each $\alpha_n > 0$, Problem (2.12) has a unique solution x_n ;

(ii) If $0 < \alpha_n \le 1$, $\alpha_n \to 0$ as $n \to +\infty$, then $\lim_{n \to +\infty} x_n = x^0 \in S$ with x_* -minimal norm and

$$||x_{n+1} - x_n|| = O\left(\frac{|\alpha_{n+1} - \alpha_n|}{\alpha_n}\right),$$

where x_{n+1} is a solution of (2.12) when α_n is replaced by α_{n+1} .

Proof. (i) By an argument analogous to that used in the proof of the equation (2.1), we deduce that the equation (2.12) has a unique solution denoted by x_n .

(ii) The proof of the first part is anologue to Theorem 2.1.

Let x_{n+1} be a solution of (2.12) when α_n is replaced by α_{n+1} . It follows from (2.12) that

$$\sum_{j=1}^{N} \alpha_{n}^{\lambda_{j}} \langle A_{j}(x_{n}) - f_{j}, x_{n} - x_{n+1} \rangle + \alpha_{n} \langle x_{n} - x_{*}, x_{n} - x_{n+1} \rangle$$
$$+ \sum_{j=1}^{N} \alpha_{n+1}^{\lambda_{j}} \langle A_{j}(x_{n+1}) - f_{j}, x_{n+1} - x_{n} \rangle + \alpha_{n+1} \langle x_{n+1} - x_{*}, x_{n+1} - x_{n} \rangle$$
$$+ \sum_{j=1}^{N} \alpha_{n+1}^{\lambda_{j}} \langle A_{j}(x_{n}) - f_{j}, x_{n+1} - x_{n} \rangle + \sum_{j=1}^{N} \alpha_{n+1}^{\lambda_{j}} \langle A_{j}(x_{n}) - f_{j}, x_{n} - x_{n+1} \rangle = 0.$$

Because of the monotonicity of A_j and the last inequality, we obtain

$$\sum_{j=1}^{N} (\alpha_n^{\lambda_j} - \alpha_{n+1}^{\lambda_j}) \langle A_j(x_n) - f_j, x_n - x_{n+1} \rangle + \alpha_n \langle x_n - x_*, x_n - x_{n+1} \rangle + \alpha_{n+1} \langle x_{n+1} - x_*, x_{n+1} - x_n \rangle \le 0.$$

Hence,

$$\begin{aligned} \alpha_n \langle x_n - x_{n+1}, x_n - x_{n+1} \rangle &\leq (\alpha_n - \alpha_{n+1}) \langle x_{n+1} - x_*, x_{n+1} - x_n \rangle \\ &+ \sum_{j=2}^N (\alpha_n^{\lambda_j} - \alpha_{n+1}^{\lambda_j}) \langle A_j(x_n) - f_j, x_{n+1} - x_n \rangle. \end{aligned}$$

 So

$$\|x_n - x_{n+1}\| \le \frac{|\alpha_n - \alpha_{n+1}|}{\alpha_n} \|x_{n+1} - x_*\| + \frac{K}{\alpha_n} \sum_{j=2}^N |\alpha_n^{\lambda_j} - \alpha_{n+1}^{\lambda_j}|, \qquad (2.13)$$

where K is a positive constant such that $K = \max_{2 \le j \le N} ||A_j(x_n) - f_j||$. On the other hand, it follows from (2.12) that

$$\sum_{j=1}^{N} \alpha_{n+1}^{\lambda_j} \langle A_j(x_{n+1}) - f_j, x_{n+1} - x \rangle + \alpha_{n+1} \langle x_{n+1} - x_*, x_{n+1} - x \rangle$$
$$= \sum_{j=1}^{N} \alpha_{n+1}^{\lambda_j} \langle A_j(x_{n+1}) - A_j(x) + f_j - f_j, x_{n+1} - x \rangle$$
$$+ \alpha_{n+1} \langle x_{n+1} - x_*, x_{n+1} - x \rangle = 0, \ \forall x \in S.$$

Using the monotone property of A_j the last equality have the form

$$\alpha_{n+1}\langle x_{n+1} - x_*, x_{n+1} - x \rangle = \sum_{j=1}^N \alpha_{n+1}^{\lambda_j} \langle A_j(x_{n+1}) - A_j(x), x - x_{n+1} \rangle$$

$$\leq 0, \ \forall x \in S.$$

Therefore,

$$||x_{n+1} - x_*|| \le ||x - x_*||, \ \forall x \in S.$$
(2.14)

Combining (2.13), (2.14) and the Lagrange's mean-value theorem for the differentiable function $\varphi(\nu) = \nu^{\gamma}$, $0 < \gamma < 1$, $\nu \in [1; +\infty)$ on $[\alpha_n; \alpha_{n+1}]$ we get $\|x_{n+1} - x_n\| \leq M \frac{|\alpha_{n+1} - \alpha_n|}{\alpha_n}$,

$$M = \|x^0 - x_*\| + K(N - 1).$$

The proof is complete.

We need the following result (see [4]).

Lemma 2.3. Let $\{u_k\}, \{a_k\}, \{b_k\}$ be the sequences of positive numbers satisfying the following conditions:

(i)
$$u_{k+1} \le (1-a_k)u_k + b_k, \quad 0 \le a_k \le 1,$$

Regularization for a system of inverse-strongly monotone operator equations 83

(*ii*)
$$\sum_{k=1}^{\infty} a_k = +\infty$$
, $\lim_{k \to +\infty} \frac{b_k}{a_k} = 0$.
Then, $\lim_{k \to +\infty} u_k = 0$.

Theorem 2.5. Assume that $\{\alpha_n\}$ and $\{\beta_n\}$ in the problem (2.11) satisfy the following conditions:

(i)
$$1 \ge \alpha_n \searrow 0, \ \beta_n \to 0 \text{ as } n \to +\infty ;$$

(ii) $\lim_{n \to +\infty} \frac{|\alpha_{n+1} - \alpha_n|}{\beta_n \alpha_n^2} = 0, \ \lim_{n \to +\infty} \frac{\beta_n}{\alpha_n} = 0;$
(iii) $\sum_{n=1}^{\infty} \alpha_n \beta_n = +\infty.$

Then $\{z_n\}$ generated from (2.11) converges in H to $x^0 \in S$ as $n \to +\infty$.

Proof. First, we have $||z_n - x^0|| \le ||z_n - x_n|| + ||x_n - x^0||$. The second term in right-hand side of this estimate tends to zero as $n \to \infty$, by Theorem 2.3. So we only have to proof that z_n approximates x_n as $n \to \infty$. Let $\Delta_n = ||z_n - x_n||$. Obviuously,

$$\begin{aligned} \Delta_{n+1} &= \|z_{n+1} - x_{n+1}\| \\ &= \|z_n - x_n - \beta_n \bigg[\sum_{j=1}^N \alpha_n^{\lambda_j} (A_j(z_n) - f_j) + \alpha_n (z_n - x_*) \bigg] \\ &- (x_{n+1} - x_n) \|, \end{aligned}$$

$$\leq \bigg\| z_n - x_n - \beta_n \bigg[\sum_{j=1}^N \alpha_n^{\lambda_j} (A_j(z_n) - f_j) + \alpha_n (z_n - x_*) \bigg] \bigg\| \\ &+ \|x_{n+1} - x_n\|, \end{aligned}$$
(2.15)

where

$$\left\| z_n - x_n - \beta_n \left[\sum_{j=1}^N \alpha_n^{\lambda_j} (A_j(z_n) - f_j) + \alpha_n(z_n - x_*) \right] \right\|^2$$

= $\| z_n - x_n \|^2 + \beta_n^2 \left\| \sum_{j=1}^N \alpha_n^{\lambda_j} (A_j(z_n) - f_j) + \alpha_n(z_n - x_*) \right\|^2$
 $- 2\beta_n \left\langle z_n - x_n, \sum_{j=1}^N \alpha_n^{\lambda_j} (A_j(z_n) - f_j) + \alpha_n(z_n - x_*) \right.$
 $- \left[\sum_{j=1}^N \alpha_n^{\lambda_j} (A_j(x_n) - f_j) + \alpha_n(x_n - x_*) \right] \right\rangle$

Nguyen Thi Thu Thuy

$$\leq (1 - 2\beta_n \alpha_n) \|z_n - x_n\|^2 + \beta_n^2 \left\| \sum_{j=1}^N \alpha_n^{\lambda_j} (A_j(z_n) - f_j) + \alpha_n (z_n - x_*) \right\|^2.$$
(2.16)

Since A_j is inverse-strongly monotone, A_j is Lipschitz continuous, and

$$\begin{split} & \left\|\sum_{j=1}^{N} \alpha_{n}^{\lambda_{j}} (A_{j}(z_{n}) - f_{j}) + \alpha_{n}(z_{n} - x_{*})\right\|^{2} \\ &= \left\|\sum_{j=1}^{N} \alpha_{n}^{\lambda_{j}} (A_{j}(z_{n}) - f_{j}) + \alpha_{n}(z_{n} - x_{*}) - \sum_{j=1}^{N} \alpha_{n}^{\lambda_{j}} (A_{j}(x_{n}) - f_{j}) - \alpha_{n}(x_{n} - x_{*})\right\|^{2} \\ &\leq \left(\sum_{j=1}^{N} \alpha_{n}^{\lambda_{j}} \frac{1}{m_{A_{j}}} \|z_{n} - x_{n}\|\right)^{2} + \alpha_{n}^{2} \|z_{n} - x_{n}\|^{2} + 2\alpha_{n} \sum_{j=1}^{N} \alpha_{n}^{\lambda_{j}} \frac{1}{m_{A_{j}}} \|z_{n} - x_{n}\|^{2} \\ &\leq c \|z_{n} - x_{n}\|^{2}, \end{split}$$

where c is positive constant. Combining (2.15), (2.16), the last inequality and the Theorem 2.3 yields that

$$\Delta_{n+1} \le \left(\Delta_n^2 (1 - 2\beta_n \alpha_n + c\beta_n^2)\right)^{1/2} + M \frac{|\alpha_{n+1} - \alpha_n|}{\alpha_n}.$$

By taking the squares of the both sides of the last inequality and then applying the elementary estimate (see [4])

$$(a+b)^2 \le (1+\alpha_n\beta_n)a^2 + (1+\frac{1}{\alpha_n\beta_n})b^2$$

we obtain that

$$\Delta_{n+1}^2 \leq \Delta_n^2 (1 - \beta_n \alpha_n + c\beta_n^2 - 2\alpha_n^2 \beta_n^2 + c\alpha_n \beta_n^3) + \left(1 + \frac{1}{\beta_n \alpha_n}\right) M^2 \frac{|\alpha_{n+1} - \alpha_n|^2}{\alpha_n^2}.$$
(2.17)

The conditions of Lemma 2.3 for the numerical sequence $\{\Delta_n\}$ are true because of (2.17) and conditions (i) - (iii) with

$$a_n = \alpha_n \beta_n - c\beta_n^2 + 2\alpha_n^2 \beta_n^2 - c\alpha_n \beta_n^3$$
$$b_n = \left(1 + \frac{1}{\beta_n \alpha_n}\right) M^2 \frac{|\alpha_{n+1} - \alpha_n|^2}{\alpha_n^2}.$$
te.

The proof is complete.

Remark 2.2. The sequences $\beta_n = (1+n)^{-1/2}$ and $\alpha_n = (1+n)^{-p}$, 0 < 2p < 1/N satisfy all conditions in Theorem 2.5.

3. Numerical example

We now apply the obtained results of the previous sections to solve the convex optimization problem: find an element $x^0 \in H$ such that

$$\varphi_j(x^0) = \min_{x \in H} \varphi_j(x) \quad j = 1, ..., N,$$
(3.1)

where φ_j is weakly lower semi-continuous proper convex function on a real Hilbert space H.

We consider the case, when the function $\varphi_j : L^2[0,1] \to \mathbb{R} \cup \{+\infty\}$ is defined by $\varphi_j(x) = f(\frac{1}{2} \langle B_j x, x \rangle), \ j = 1, 2$, where $f : \mathbb{R} \to \mathbb{R}$ is chosen as follows

$$f(t) = \begin{cases} 0 & , t \leq b_0, \\ \frac{(t-b_0)^2}{2\nu} & , b_0 < t \leq b_0 + \nu, \\ t-b_0 - \frac{\nu}{2} & , t > b_0 + \nu, \end{cases}$$

with $\nu > 0$ is sufficiently small, and $B_j : L^2[0,1] \to L^2[0,1]$ are difined by $B_j x(t) = \int_0^1 k_j(t,s) x(s) ds$,

$$k_1(t,s) = \begin{cases} t(1-s) &, & \text{if } t \le s, \\ s(1-t) &, & \text{if } s < t, \end{cases}$$

and

$$k_{2}(t,s) = \begin{cases} \frac{(1-s)^{2}st^{2}}{2} - \frac{(1-s)^{2}t^{3}(1+2s)}{6} \\ +\frac{(t-s)^{3}}{6}, & \text{if } t \geq s, \end{cases}$$

$$\frac{s^{2}(1-s)(1-t)^{2}}{2} + \frac{s^{2}(1-t)^{3}(2s-3)}{6} \\ +\frac{(s-t)^{3}}{6}, & \text{if } t < s. \end{cases}$$

Then x^0 is a solution to the problem (3.1) if and only if $x^0 \in S$ with $A_j(x) = f'(\frac{1}{2}\langle B_j x, x \rangle)B_j(x)$.

 $\tilde{\mathrm{W}}\mathrm{e}$ apply the iterative regularization method (2.11) as follow

$$z_{m+1} = z_m - \beta_m \big[\tilde{A}_1 z_m + \alpha_m \tilde{A}_2 z_m + \alpha_m^2 z_m \big], \quad z_0 \in \mathbb{R}^M, \tag{3.2}$$

where $\tilde{A}_j(x) = f'(\frac{1}{2} \langle \tilde{B}_j \tilde{x}, \tilde{x} \rangle) \tilde{B}_j(\tilde{x})$ with

$$\begin{split} \tilde{B}_{j} &= (\ell k_{j}(t_{k},t_{l}))_{k,l=1}^{M} \\ \tilde{x} &= (\tilde{x}_{1},...,\tilde{x}_{M})^{T} \\ \tilde{x}_{k} &\sim x(t_{k}), \ k = 1,...,M, \ \ell = \frac{1}{M} \end{split}$$

By choosing $\alpha_m = (1+m)^{-p}$, $0 , <math>\beta_m = (1+m)^{-1/2}$, $z_0 = (5, 5, ..., 5)^T \in \mathbb{R}^M$ and $b_0 = \frac{10^{-3}}{2}$, $\nu = 10^{-2}$ we obtain the results.

| ana | $3, \nu = 3$ | io we obtain |
|--------------------------------------|-------------------------|-------------------------|
| m | err | $ x^0 - z_m $ |
| 32 | 0.00067782 | 0.0077909 |
| 64 | 5.3403×10^{-5} | 0.0010353 |
| 128 | 2.7676×10^{-6} | 8.9792×10^{-5} |
| 256 | 8.6222×10^{-8} | 4.6575×10^{-6} |
| Table 2.1: $M = 50, p = \frac{1}{9}$ | | |

| m | err | $ x^0 - z_m $ |
|---------------------------------------|--------------------------|-------------------------|
| 32 | 0.00013731 | 0.001026 |
| 64 | 3.7047×10^{-6} | 4.379×10^{-5} |
| 128 | 3.9267×10^{-8} | 7.2603×10^{-7} |
| 256 | 1.2199×10^{-10} | 3.501×10^{-9} |
| Table 2.2: $M = 50, p = \frac{1}{18}$ | | |

In these tables, $err = \max_{1 \le k \le M} |z_k^{(m-1)} - z_k^{(m)}|$ is error.

References

- Ya. I. Alber, On solving nonlinear equations involving monotone operators in Banach spaces, Sibirian Mathematics Journal, 26 (1975), 3-11.
- [2] Ya. I. Alber and A. I. Notik, Geometric properties of Banach spaces and approximate methods for solving nonlinear operator equations, Soviet Math. Dokl., 29 (1984), 611-615.
- [3] Ya. I. Alber and I. P. Ryazantseva, Nonlinear ill-posed problems of monotne type, Springer Verlag, New York, 2006.
- [4] A. Bakushinsky and A. Goncharsky, *Ill-posed problem: Theory and Applications*, Kluwer Acad. Publ, 1994.
- [5] V. Barbu, Nonlinear semigroups and differential equations in Banach spaces, Noordhoff International Publishing, Leyden The Netherlands, 1976.
- [6] H. Brezis, Operateurs maximaux monotones et semi-groupes de contractions dans les espaces de Hilbert, Amsterdam - London - New York: Noth-Holland Publ. Company and American Elsevier Publ. Company, 1973.

Regularization for a system of inverse-strongly monotone operator equations

- [7] Ng. Buong, Generalized discrepancy principle and ill-posed equation involving accretive operators, Nonlinear Funct. Anal. and Appl., 9 (2004), 73-78.
- [8] Ng. Buong, Convergence rates in regularization for ill-posed variational inequalities, CUBO, Mathematical Journal, 21, No. 3 (2005), 87-94.
- [9] Ng. Buong, Regularization for unconstrained vector optimization of convex functionals in Banach spaces, Zh. Vycisl. Mat. i Mat. Fiziki, 46, No.3 (2006), 372-378.
- [10] I. Ekeland and R. Temam, Convex analysis and Variational problems, Amstedam: North Holland, 1976.
- [11] H. W. Engl, Discrepancy principle for Tikhonov regularization of ill-posed problems leading to optimal convergence rates, J. Optim. Theory and Appl., 52 (1987), 209-215.
- [12] M. Hanke, A. Neubauer and O. Scherzer, A convergence analysis of the Landweber iteration for nonlinear ill-posed problems, Numerische Mathematik, 72 (1995), 21-37.
- [13] F. Liu and M. Z. Nashed, Regularization of nonlinear ill-posed variational inequalities and convergence rates, Set-Valued Analysis, 6 (1998) 313-344.
- [14] M. M. Vainberg, Variational Method and Method of Monotone Operators in the Theory of Nonlinear Equations, New York, John Wiley, 1973.