

## FIXED POINT THEOREMS FOR CONDENSING MULTIMAPS ON ABSTRACT CONVEX UNIFORM SPACES

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**Abstract.** In this paper we present fixed point theory for condensing multimap on abstract convex uniform spaces. Also we obtain a nonlinear alternative of Leray-Schauder type for Mönch type maps. Our main results unify and improve some well-know results in the literature.

### 1. INTRODUCTION

Throughout the paper,  $\langle X \rangle$  denotes the family of all nonempty finite subsets of nonempty set  $X$ . Let  $X$  and  $Y$  be topological spaces with  $A \subseteq X$  and  $B \subseteq Y$ . Let  $F : X \multimap Y$  be a multimap with nonempty values. The image of  $A$  under  $F$  is the set  $F(A) = \bigcup_{x \in A} F(x)$ ; and the inverse image of  $B$  under  $F$  is  $F^{-}(B) = \{x \in X : F(x) \cap B \neq \emptyset\}$ .  $F$  is said to be:

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- (i) closed if its graph,  $Gr(F) = \{(x, y) \in X \times Y : y \in F(x)\}$  is a closed set in the product space  $X \times Y$ ,
- (ii) upper semicontinuous, if for each closed set  $B \subseteq Y$ ,  $F^-(B) = \{x \in X : F(x) \cap B \neq \emptyset\}$  is closed in  $X$ ,
- (iii) compact if  $\overline{F(X)}$  is compact subset of  $Y$ .

It is well-known that if  $Y$  is compact Hausdorff and  $F(x)$  is closed for each  $x \in X$ , then  $F$  is upper semicontinuous if and only if  $F$  is closed. For the remainder of this paper we assume all topological spaces are Hausdorff.

**Definition 1.1.** An *abstract convex space*  $(E, D; \Gamma)$  consists of a nonempty set  $E$ , a nonempty set  $D$ , and a multimap  $\Gamma : \langle D \rangle \multimap E$  with nonempty values. When  $D \subseteq E$ , the space is denoted by  $(E \supseteq D; \Gamma)$ . In such a case, a subset  $X$  of  $E$  is said to be  $\Gamma$ -convex if, for any  $A \in \langle X \cap D \rangle$ , we have  $\Gamma(A) \subseteq X$ . For a nonempty subset  $Q$  of  $E$ , the  $\Gamma$ -convex hull of  $Q$ , denoted by  $co_\Gamma(Q)$ , is defined by

$$co_\Gamma(Q) = \bigcap \{C : Q \subseteq C \subseteq E, C \text{ is } \Gamma\text{-convex}\},$$

and the closed  $\Gamma$ -convex hull of  $Q$ , denoted by  $\overline{co}_\Gamma(Q)$ , is defined by  $\overline{co}_\Gamma(Q) = \overline{co_\Gamma(Q)}$ . In the case  $E = D$ , let  $(E; \Gamma) := (E, E; \Gamma)$ .

An abstract convex space with any topology is called an *abstract convex topological space*.

**Examples 1.2.** A convexity space  $(E, \mathcal{C})$  in the classical sense [3],  $G$ -convex spaces,  $C$ -spaces, convex spaces and almost convex spaces [4] are the main examples of abstract convex spaces.

**Definition 1.3.** Let  $(E, D; \Gamma)$  be an abstract convex space and  $Z$  a set. For a multimap  $F : E \multimap Z$  with nonempty values, if a multimap  $G : D \multimap Z$  satisfies

$$F(\Gamma(A)) \subseteq G(A), \text{ for all } A \in \langle X \rangle,$$

then  $G$  is called a *KKM map* with respect to  $F$ . A *KKM map*  $G : D \multimap Z$  is a *KKM map* with respect to the identity map  $1_E$ . A multimap  $F : E \multimap Z$  is said to have the *KKM property* if, for a *KKM map*  $G : D \multimap Z$  with respect to  $F$ , the family  $\{\overline{G(x)}\}_{x \in X}$  has the finite intersection property. We denote

$$\text{KKM}(E, Z) := \{F : E \multimap Z : F \text{ has the KKM property}\}.$$

**Definition 1.4.** For an abstract convex space  $(E \supseteq D; \Gamma)$ , let  $X$  be a  $\Gamma$ -convex subset of  $E$ , and  $D'$  a nonempty subset of  $X \cap D$ . Let  $\Gamma' : \langle D' \rangle \multimap X$  be a map defined by

$$\Gamma'(A) = \Gamma(A) \subseteq X \text{ for } A \in D'.$$

Then  $(X \supseteq D'; \Gamma')$  itself is an abstract convex space called a subspace.

**Lemma 1.5.** (Park [6]) *Let  $(E \supseteq D; \Gamma)$  be an abstract convex space,  $(X \supseteq D'; \Gamma')$  a subspace,  $Z$  a set. If  $F \in \text{KKM}(E, Z)$ , then  $F|_X \in \text{KKM}(X, Z)$ .*

**Definition 1.6.** For a given abstract convex space  $(E, D; \Gamma)$  and a topological space  $X$ , a map  $H : X \dashrightarrow E$  is called a  $\Phi$ -map if there exists a map  $G : X \dashrightarrow D$  such that

- (i) for each  $x \in X$ ,  $A \in \langle G(x) \rangle$  implies  $\Gamma(A) \subseteq H(x)$ ; and
- (ii)  $X = \bigcup \{ \text{Int } G^{-1}(y) : y \in D \}$ .

If  $(E, \mathcal{U})$  is a uniform space, then its topology is induced by the uniformity  $\mathcal{U}$  is the family of all subsets  $G$  of  $E$  such that for each in  $x \in G$ , there is  $U \in \mathcal{U}$  such that  $U[x] \subseteq G$ , where  $U[x] = \{y \in X : (x, y) \in U\}$ . If  $K \subseteq E$  and  $U \in \mathcal{U}$ , then  $U[K] = \bigcup_{x \in K} U[x]$ . A subset  $S$  of a uniform space  $E$  is said to be precompact if, for any entourage  $V$ , there is a finite subset  $N$  of  $E$  such that  $S \subseteq V[N]$ .

**Definition 1.7.** An *abstract convex uniform space*  $(E, D; \Gamma; \mathcal{U})$  is an abstract convex space so that its topology is induced by the uniformity  $\mathcal{U}$ . In section 2, we shall assume that the convex structure  $\Gamma$  and the base  $\mathcal{B}$  of  $\mathcal{U}$  satisfy the following conditions:

$$V[K] \text{ is } \Gamma\text{-convex whenever } K \text{ is a } \Gamma\text{-convex subset of } E \text{ and } V \in \mathcal{B}; \quad (1.1)$$

$$c_{\Gamma}(A) \text{ is precompact whenever } A \text{ is precompact.} \quad (1.2)$$

In  $(E, D; \Gamma; \mathcal{U})$ , a subset  $Z$  of  $E$  is called a  $\Phi$ -set if, for any entourage  $U \in \mathcal{U}$ , there exists a  $\Phi$ -map  $H : Z \dashrightarrow E$  such that  $Gr(T) \subseteq U$ . If  $E$  itself is a  $\Phi$ -set, then it is called a  $\Phi$ -space.

Note part (i) of the following lemma was proved in [5], in the setting of locally  $G$ -convex spaces.

**Lemma 1.8.** *Let  $(E, \Gamma; \mathcal{U})$  be an abstract convex space. Then the following statements hold:*

- (i) if  $K$  is a  $\Gamma$ -convex subset  $E$ , then its closure  $\overline{K}$  is also  $\Gamma$ -convex,
- (ii)  $\overline{c_{\Gamma}}(Q) = \bigcap \{ C : Q \subseteq C \subseteq E, C \text{ is closed and } \Gamma\text{-convex} \}$ ,
- (iii) if  $X \subseteq E$  be a  $\Phi$ -set and  $Y \subseteq X$  then  $Y$  is also a  $\Phi$ -set.

*Proof.* (i) Let  $\mathcal{B}$  be a base of  $\mathcal{U}$  as described above,  $V \in \mathcal{B}$ , and  $A = \{a_1, \dots, a_n\} \subseteq \langle \overline{K} \rangle$ . Choose  $\{x_1, \dots, x_n\} \subseteq \langle K \rangle$  with  $x_i \in V[a_i] \cap K$  for any  $i = 1, \dots, n$ . Since  $V[K]$  is  $\Gamma$ -convex and  $a_i \in V[x_i] \subseteq V[K]$  for any  $i = 1, \dots, n$ , we infer that  $\Gamma(A) \subseteq V[K]$  for all  $V \in \mathcal{B}$ , and hence  $\Gamma(A) \subseteq \bigcap_{V \in \mathcal{B}} V[K] = \overline{K}$ . This shows that  $\overline{K}$  is  $\Gamma$ -convex.

(ii) By (i),  $\overline{c_{\Gamma}}(Q)$  is a closed,  $\Gamma$ -convex set which contains  $Q$ , so

$$\bigcap \{ C : Q \subseteq C \subseteq E, C \text{ is closed and } \Gamma\text{-convex} \} \subseteq \overline{c_{\Gamma}}(Q).$$

On the other hand, we have

$$\begin{aligned} & \bigcap \{C : Q \subseteq C \subseteq E, C \text{ is closed and } \Gamma\text{-convex}\} \\ &= \overline{\bigcap \{C : Q \subseteq C \subseteq E, C \text{ is closed and } \Gamma\text{-convex}\}} \\ & \supseteq \overline{\bigcap \{C : Q \subseteq C \subseteq E, C \text{ is } \Gamma\text{-convex}\}} \\ &= \overline{co_\Gamma(Q)} = \overline{co_\Gamma(Q)}. \end{aligned}$$

(iii) Since  $X$  is a  $\Phi$ -set, for any entourage  $U \in \mathcal{U}$ , there exists a  $\Phi$ -map  $H : X \rightarrow E$  such that  $Gr(H) \subseteq U$ . Since  $H : X \rightarrow E$  is a  $\Phi$ -map there exists a map  $G : X \rightarrow E$  such that for each  $x \in X$ ,  $A \in \langle G(x) \rangle$  implies  $\Gamma(A) \subseteq H(x)$ , and  $X = \bigcup \{Int G^-(y) : y \in E\}$ . As a result, for each  $x \in Y \subseteq X$ ,  $A \in \langle G|_Y(x) \rangle$  implies  $\Gamma(A) \subseteq H(x) = H|_Y(x)$  and

$$\begin{aligned} Y &= Y \cap X = Y \cap \bigcup \{Int G^-(y) : y \in E\} \\ &= \bigcup \{Y \cap Int G^-(y) : y \in E\} = \bigcup \{Int G|_Y^-(y) : y \in E\}. \end{aligned}$$

Thus,  $H|_Y : Y \rightarrow E$  is a  $\Phi$ -map and  $Gr(H|_Y) \subseteq Gr(H) \subseteq U$ .  $\square$

**Theorem 1.9.** ([6,8]) *Let  $(E, D; \Gamma; \mathcal{U})$  be an abstract convex uniform space, and  $F \in KKM(E, E)$  be a closed compact map. If  $\overline{F(E)}$  is a  $\Phi$ -set, then  $F$  has a fixed point.*

**Examples 1.10.** (i) Any locally convex subset of a topological vector space  $E$  is a  $\Phi$ -set in  $E$ .

(ii) Any subset of the Zima type in a  $G$ -convex uniform space  $(E \supseteq D; \Gamma; \mathcal{U})$  such that every singleton is  $\Gamma$ -convex is a  $\Phi$ -set.

(iii) For a locally  $G$ -convex space  $(E \supseteq D; \Gamma; \mathcal{U})$ , any nonempty subset  $X$  of  $E$  is a  $\Phi$ -set. A locally  $G$ -convex space  $(E \supseteq D; \Gamma; \mathcal{U})$  is a  $\Phi$ -set.

(iv) A metric  $G$ -convex space  $(E \supseteq D; \Gamma)$  is a  $\Phi$ -space whenever  $D$  is dense in  $X$  and every open ball is  $\Gamma$ -convex.

## 2. FIXED POINT THEORY

A slight modifications of the proof of Lemma 3.4 in [5], yields the following lemma.

**Lemma 2.1.** *Let  $X$  be a nonempty closed,  $\Gamma$ -convex subset of an abstract convex uniform space  $(E, \Gamma; \mathcal{U})$  and  $F : X \rightarrow X$ . If  $\emptyset \neq Q \subseteq X$ , then there exists a closed,  $\Gamma$ -convex set  $K = K(F, Q)$  with  $Q \subseteq K \subseteq X$  and  $K = \overline{co_\Gamma(F(K) \cup Q)}$ .*

*Proof.* Let

$$\mathcal{F} = \{A \subseteq E : A \text{ is closed, } \Gamma\text{-convex and } \overline{c\omega}_\Gamma(F(X \cap A) \cup Q) \subseteq A\}.$$

Since  $E \in \mathcal{F}$ ,  $\mathcal{F} \neq \emptyset$ . Define a partial order by inverse inclusion, that is, for  $A, B \in \mathcal{F}$ ,  $A \leq B \Leftrightarrow B \subseteq A$ . Let  $\mathcal{C}$  be any chain in  $\mathcal{F}$ . Put  $M = \bigcap_{A \in \mathcal{C}} A$ . Since each  $A \in \mathcal{C}$  is closed,  $\Gamma$ -convex and contain  $Q$ , we infer that  $M$  is closed,  $\Gamma$ -convex and contain  $Q$ , for all  $A \in \mathcal{C}$ , it follows from

$$F(M \cap X) \cup Q \subseteq F(A \cap X) \cup Q$$

that  $\overline{c\omega}_\Gamma(F(M \cap X) \cup Q) \subseteq \overline{c\omega}_\Gamma(F(A \cap X) \cup Q) \subseteq A$  and so

$$\overline{c\omega}_\Gamma(F(M \cap X) \cup Q) \subseteq \bigcap_{A \in \mathcal{C}} A = M.$$

Thus  $M \in \mathcal{F}$  and  $M$  is an upper bound of  $\mathcal{C}$ . By Zorn's lemma,  $\mathcal{F}$  has a maximal element, say  $K$ . We claim that  $\overline{c\omega}_\Gamma(F(K \cap X) \cup Q) = K$ . In fact, put  $K_0 = \overline{c\omega}_\Gamma(F(K \cap X) \cup Q)$ . It is obvious that  $K_0$  is closed,  $\Gamma$ -convex and contain  $Q$ . Furthermore, since  $\overline{c\omega}_\Gamma(F(K_0 \cap X) \cup Q) \subseteq \overline{c\omega}_\Gamma(F(K \cap X) \cup Q) = K_0$ , we have  $K_0 \in \mathcal{F}$  and  $K_0 \geq K$ . By the maximality of  $K$ , we conclude that  $K = K_0$ , that is

$$\overline{c\omega}_\Gamma(F(K \cap X) \cup Q) = K.$$

Finally, since  $F(X) \subseteq X$ , it follows since  $X$  is closed that  $K \subseteq X$  and  $\overline{c\omega}_\Gamma(F(K) \cup Q) = K$ .  $\square$

**Theorem 2.2.** *Let  $X$  be a nonempty closed,  $\Gamma$ -convex subset of an abstract convex uniform  $\Phi$ -space  $(E, \Gamma; \mathcal{U})$ . Let  $F \in KKM(X, X)$  be a closed map, then  $F$  has a fixed point provided the following condition hold:*

$$\begin{aligned} & \text{for any } x_0 \in X, \text{ and } A \subseteq X \text{ with } A = \overline{c\omega}_\Gamma(\{x_0\} \cup F(A)) \\ & \text{we have that } A \text{ is compact.} \end{aligned} \quad (2.1)$$

*Proof.* Putting  $Q = \{x_0\}$  in Lemma 2.1, we obtain that there exists a closed,  $\Gamma$ -convex set  $K \subseteq X$  with  $K = \overline{c\omega}_\Gamma(F(K) \cup \{x_0\})$ . Since (2.1) holds, then  $K$  is compact. Now  $F : K \rightarrow K$  is closed and compact and  $F|_K \in KKM(K, K)$  by Lemma 1.5. Since  $E$  is a  $\Phi$ -space, then  $F(K)$  is a  $\Phi$ -set and so by Theorem 1.9,  $F$  has a fixed point.  $\square$

**Theorem 2.3.** *Let  $X$  be a nonempty complete,  $\Gamma$ -convex subset of an abstract convex uniform  $\Phi$ -space  $(E, \Gamma; \mathcal{U})$ . Let  $F \in KKM(X, X)$  be a closed map, then  $F$  has a fixed point provided that the following condition hold:*

$$\begin{aligned} & \text{whenever } x_0 \in X, \ A \subseteq X, \ F(A) \subseteq A \text{ and } A \setminus \overline{c\omega}_\Gamma(F(A)) \subseteq \{x_0\} \\ & \text{we have that } A \text{ is a precompact subset of } X. \end{aligned} \quad (2.2)$$

*Proof.* Choose  $x_0 \in X$  and let  $A = \bigcup_{i \geq 0} F^i(x_0)$  where  $F^0(x_0) = \{x_0\}$ . Then  $F(A) \subseteq A$  and  $A \setminus \overline{\text{co}}_\Gamma(F(A)) \subseteq \{x_0\}$ , so  $A$  is precompact, and hence  $\overline{A}$  is compact since it is a precompact and closed subset of the complete set  $X$ . Define  $G : \overline{A} \rightarrow \overline{A}$  by  $G(x) = F(x) \cap \overline{A}$ . Since  $F$  is closed and  $\overline{A}$  is compact, it is easy to see that  $G(x) \neq \emptyset, \forall x \in \overline{A}$ . Put

$$\mathcal{A} = \{Y : Y \text{ is a nonempty closed subset of } \overline{A} \text{ and } G(Y) \subseteq Y\}.$$

Since  $\overline{A} \in \mathcal{A}$ ,  $\mathcal{A} \neq \emptyset$ . Define a partial order  $\leq$  on  $\mathcal{A}$  by  $A \leq B \Leftrightarrow B \subseteq A$ . Let  $\mathcal{C}$  be any chain in  $\mathcal{A}$  and put  $M = \bigcap_{L \in \mathcal{C}} L$ . Now  $M$  is an upper bound of  $\mathcal{C}$  and so, by Zorn's Lemma,  $\mathcal{A}$  has a maximal element, say  $Q$ . Since  $F$  is closed, so is  $G$ , and this with the compactness of  $\overline{A}$  guarantees that  $G$  is upper semicontinuous. Therefore,  $G(Q)$  is compact. Putting  $Y = G(Q)$  and noting that  $G(Y) = G(G(Q)) \subseteq G(Q) = Y$ , the maximality of  $Q$  gives us that  $Q = Y$ . Thus

$$Q = G(Q) = F(Q) \cap \overline{A} \subseteq F(Q).$$

Let  $K = K(F, Q)$  be the subset of  $X$  described in Lemma 2.1, so  $K = \overline{\text{co}}_\Gamma(F(K) \cup Q)$ . Since  $Q \subseteq F(Q) \subseteq K$ , we have  $K = \overline{\text{co}}_\Gamma(F(K))$  and so we have shown that there exists a closed,  $\Gamma$ -convex subset  $K \subseteq X$  such that  $K = \overline{\text{co}}_\Gamma(F(K))$ . Now (2.2) implies that  $K$  is precompact subset of  $X$  and note in fact that it is compact. Thus by Theorem 1.9,  $F : K \rightarrow K$  has a fixed point.  $\square$

Now, we present a Mönch type result for KKM multimaps.

**Theorem 2.4.** *Let  $X$  be a nonempty complete,  $\Gamma$ -convex subset of an abstract convex uniform  $\Phi$ -space  $(E, \Gamma; \mathcal{U})$ . Suppose  $F \in \text{KKM}(X, X)$  is closed, and satisfies the following properties:*

$$F \text{ maps compact sets into relatively compact sets;} \quad (2.3)$$

$$A = \text{co}_\Gamma(\{x_0\} \cup F(A)) \text{ with } \overline{A} = \overline{C} \text{ and } C \subseteq A \text{ countable,} \\ \text{implies } \overline{A} \text{ is compact;} \quad (2.4)$$

$$\text{for any relatively compact subset } A \text{ of } X \\ \text{there exists a countable subset } B \subseteq A \text{ with } \overline{B} = \overline{A}; \quad (2.5)$$

$$F(\overline{A}) \subseteq \overline{F(A)} \text{ for any relatively compact subset } A \text{ of } X. \quad (2.6)$$

Then  $F$  has a fixed point.

*Proof.* We follow the proof of Theorem 2.5 in [2]. Let  $D_0 = \text{co}_\Gamma(\{x_0\})$ ,  $D_{n+1} = \text{co}_\Gamma(\{x_0\} \cup F(D_n))$ ,  $n = 0, 1, 2, \dots$  and

$$D_\infty = \bigcup_{n=0}^{\infty} D_n.$$

Now for  $n = 0, 1, 2, \dots$  notice  $D_n$  is  $\Gamma$ -convex. Also by induction, we see that

$$D_0 \subseteq D_1 \subseteq \dots \subseteq D_{n-1} \subseteq D_n \subseteq \dots$$

Consequently,  $D_\infty$  is  $\Gamma$ -convex. Since for each  $n$ ,

$$co_\Gamma(\{x_0\} \cup F(D_n)) \subseteq co_\Gamma(\{x_0\} \cup F(D_\infty)),$$

so

$$D_\infty = \bigcup_{n=0}^{\infty} co_\Gamma(\{x_0\} \cup F(D_n)) \subseteq co_\Gamma(\{x_0\} \cup F(D_\infty)).$$

On the other hand,  $D_\infty$  is a  $\Gamma$ -convex set which contains  $\bigcup_{n=0}^{\infty} F(D_n) = F(D_\infty)$ , consequently  $co_\Gamma(\{x_0\} \cup F(D_\infty)) \subseteq D_\infty$ . Thus

$$D_\infty = co_\Gamma(\{x_0\} \cup F(D_\infty)). \tag{2.7}$$

It is easy to see (use induction with (1.2), note  $X$  is complete, and (2.3)) that  $D_n$  is relatively compact for  $n = 0, 1, 2, \dots$ . Now (2.5) implies that for each  $n = 0, 1, 2, \dots$  there exists  $C_n$  with  $C_n$  countable,  $C_n \subseteq D_n$ , and  $\overline{C_n} = \overline{D_n}$ . Let  $C_\infty = \bigcup_{n=0}^{\infty} C_n$ . Now since

$$\bigcup_{n=0}^{\infty} D_n \subseteq \bigcup_{n=0}^{\infty} \overline{D_n} \subseteq \overline{\bigcup_{n=0}^{\infty} D_n},$$

we have

$$\overline{\bigcup_{n=0}^{\infty} D_n} = \overline{\bigcup_{n=0}^{\infty} D_n} = \overline{D_\infty} \text{ and } \overline{\bigcup_{n=0}^{\infty} D_n} = \overline{\bigcup_{n=0}^{\infty} C_n} = \overline{\bigcup_{n=0}^{\infty} C_n} = \overline{C_\infty}.$$

Thus  $\overline{D_\infty} = \overline{C_\infty}$ . This together with (2.4) and (2.7) implies that  $\overline{D_\infty}$  is compact. From (2.7) we have  $F(D_\infty) \subseteq D_\infty$ , and this together with (2.6) yields

$$F(\overline{D_\infty}) \subseteq \overline{F(D_\infty)} \subseteq \overline{D_\infty}.$$

Also notice  $F|_{\overline{D_\infty}} \in KKM(\overline{D_\infty}, \overline{D_\infty})$  is closed. Now apply Theorem 1.9.  $\square$

**Corollary 2.5.** *Let  $X$  a nonempty complete,  $\Gamma$ -convex subset of a metrizable abstract convex uniform space  $(E, \Gamma)$  such that every open ball is convex and  $1_X \in KKM(X, X)$ . Suppose that  $F : X \rightarrow X$  is a continuous map with the property (2.4). Then  $F$  has a fixed point.*

*Proof.* Since every open ball is convex, then  $(E, \Gamma)$  is an abstract convex uniform space from part (iv) of Examples 1.10. Since  $1_X \in KKM(X, X)$  and  $F : X \rightarrow X$  is continuous, then  $F \in KKM(X, X)$  and (2.3) holds. Also (2.5) follows, since compact metric spaces are separable. Apply Theorem 2.4.  $\square$

Now we extend the concept of measure of noncompactness and condensing multimaps on locally  $G$ -convex in Huang et al. [5] to abstract convex uniform spaces.

**Definition 2.6.** For a subset  $A$  of abstract convex uniform spaces  $(E, \Gamma; \mathcal{U})$ , define

$$\Psi(A) = \{V \in \mathcal{B} : A \subseteq V[S], \text{ for some precompact subset } S \text{ of } E\}.$$

We call the set  $\Psi(A)$  a measure of noncompactness of  $A$ .

Essentially the same reasoning as in [5, Proposition 3.2] guarantees the following result.

**Theorem 2.7.** *Let  $A$  and  $B$  be subsets of  $(E, \Gamma; \mathcal{U})$ . Then,*

- (i)  $A$  is precompact if and only if  $\Psi(A) = \mathcal{B}$ ;
- (ii)  $\Psi(A) \supseteq \Psi(B)$  if  $A \subseteq B$ ;
- (iii)  $\Psi(\text{co}_\Gamma(A)) = \Psi(A)$ ;
- (iv)  $\Psi(A \cup B) = \Psi(A) \cap \Psi(B)$ .

**Definition 2.8.** Suppose that  $X$  be a nonempty subset of an abstract convex uniform space  $(E, \Gamma; \mathcal{U})$  and  $\Psi$  is the measure of noncompactness in Definition 2.6. A multimap  $F : X \multimap E$  is called *condensing* provided that if  $A \subseteq X$  and  $\Psi(F(A)) \subseteq \Psi(A)$ , then  $A$  is precompact.  $F$  is called *generalized condensing* if, whenever  $A \subseteq X$ ,  $F(A) \subseteq A$  and  $A \setminus \overline{\text{co}_\Gamma(F(A))}$  is precompact, Then  $A$  is precompact.

It is obvious that every compact map or every map defined on a compact set is condensing. Also, every condensing map is generalized condensing.

**Remark 2.9.** Every condensing (respectively generalized condensing) map  $F : X \multimap X$  satisfies condition (2.1) (respectively (2.2)). Thus, by Theorems 2.2 and 2.3, we get the following.

**Corollary 2.10.** *Let  $X$  be a nonempty complete,  $\Gamma$ -convex subset of an abstract convex uniform  $\Phi$ -space  $(E, \Gamma; \mathcal{U})$ . If  $F \in KKM(X, X)$  is either condensing or generalized condensing and closed, then  $F$  has a fixed point.*

### 3. ESSENTIALTY FOR MÖNCH TYPE MAPPINGS

Let  $(E, \Gamma; \mathcal{U})$  be an abstract convex uniform space,  $U$  an open subset of  $E$  and  $x_0 \in U$ .

**Definition 3.1.** We let  $M(\overline{U}, E)$  denotes the set of all continuous maps  $F : \overline{U} \rightarrow E$  which satisfy Mönch's condition (i.e., if  $C \subseteq \text{co}_\Gamma(\{x_0\} \cup F(C))$  and  $C \subseteq \overline{U}$  is countable, then  $\overline{C}$  is compact).



**Definition 3.2.** We let  $F \in M_{\partial U}(\overline{U}, E)$  if  $F \in M(\overline{U}, E)$  with  $x \neq F(x)$  for  $x \in \partial U$ ; here  $\partial U$  denotes the boundary of  $U$  in  $E$ .

**Definition 3.3.** A map  $F \in M_{\partial U}(\overline{U}, E)$  is essential in  $M_{\partial U}(\overline{U}, E)$  if for every  $G \in M_{\partial U}(\overline{U}, E)$  with  $G|_{\partial U} = F|_{\partial U}$  there exists  $x \in U$  with  $x = G(x)$

**Definition 3.4.** Let  $(E, \Gamma; \mathcal{U})$  be an abstract convex uniform space. Throughout this section, we will assume that the convex structure  $\Gamma$  satisfies the following conditions:

$$\text{for each } a \in E, \text{ the multimap } x \mapsto co_{\Gamma}\{a, x\} \text{ is closed.} \quad (3.1)$$

$$\begin{aligned} &\text{for each } a \in E, \text{ there exists a continuous map} \\ &\omega(t, x) : [0, 1] \times E \rightarrow co_{\Gamma}\{a, x\} \text{ such that } \omega(0, x) = a \text{ and } \omega(1, x) = x. \end{aligned} \quad (3.2)$$

Let  $E$  be a topological vector space,  $A \subseteq E$ ,  $a \in E$ , and  $\Gamma(A) = \text{conv}(A)$ . Let  $\omega(t, x) = (1-t)a + tx$ , and it is easy to show that  $(E, \Gamma)$  satisfies (3.1) and (3.2).

**Definition 3.5.** A metric space  $(M, d)$  is said to be a hyperconvex metric space if for any collection of points  $x_{\alpha}$  of  $M$  and any collection  $r_{\alpha}$  of non-negative real numbers with  $d(x_{\alpha}, x_{\beta}) \leq r_{\alpha} + r_{\beta}$ , we have

$$\bigcap_{\alpha} B(x_{\alpha}, r_{\alpha}) \neq \emptyset.$$

For each  $A \subseteq M$ , Set

$$\Gamma(A) = co(A) = \bigcap \{B \subseteq M : B \text{ is a closed ball in } M \text{ such that } A \subset B\}.$$

It is well known that for any hyperconvex metric space  $M$  there exist an index set  $I$  and a natural isometric embedding from  $M$  into  $l_{\infty}(I)$ , and a nonexpansive retraction  $r : l_{\infty}(I) \rightarrow M$ . For each  $a, b \in M$  we have

$$\begin{aligned} &r(\text{conv}(a, b)) \\ &\subseteq r\left(\bigcap \{B \subseteq l_{\infty} : B \text{ is a closed ball in } l_{\infty} \text{ such that } \text{conv}(a, b) \subset B\}\right) \\ &= \bigcap \{B \subseteq M : B \text{ is a closed ball in } M \text{ such that } \{a, b\} \subset B\} = co(a, b). \end{aligned}$$

Thus,

$$r(\text{conv}(a, b)) \subseteq co(a, b).$$

Let  $\omega(t, x) = r((1-t)a + tx)$ . Then  $\omega$  is continuous and  $\omega(0, x) = a$  and  $\omega(1, x) = x$ . Also, it is easy to see that the map  $x \mapsto co(a, x)$  is closed. Thus,  $(M, \Gamma)$  satisfies (3.1) and (3.2).

The proof of the following theorem follows the lines of Theorem 2.1 in [1].

**Theorem 3.6.** *Let  $(E, \Gamma; \mathcal{U})$  be an abstract convex uniform space which satisfies (3.1) and (3.2),  $U$  an open subset of  $E$  and  $x_0 \in U$ . Suppose  $F \in M(\bar{U}, E)$  with*

$$\text{the constant map } x_0 \text{ is essential in } M_{\partial U}(\bar{U}, E) \quad (3.3)$$

and

$$x \notin \text{co}_\Gamma(\{x_0\} \cup F(x)) \text{ for any } x \in \partial U \quad (3.4)$$

holding. Also assume that

$$\begin{aligned} E \text{ is such that any closed subset is compact} \\ \text{iff it is sequentially compact.} \end{aligned} \quad (3.5)$$

Then  $F$  is essential in  $M_{\partial U}(\bar{U}, E)$ .

*Proof.* Let  $H \in M_{\partial U}(\bar{U}, E)$  with  $H|_{\partial U} = F|_{\partial U}$ . We must show  $H$  has a fixed point in  $U$ . Consider

$$B = \{x \in \bar{U} : x \in \text{co}_\Gamma(\{x_0\} \cup H(x))\}.$$

Now  $B \neq \emptyset$  since  $x_0 \in U$ . Let  $x_\alpha \in B$  be a convergent net with  $x_\alpha \rightarrow x \in \bar{U}$ . Since  $H$  is continuous, so the multimap  $x \mapsto \text{co}_\Gamma\{a, H(x)\}$  is closed from (3.1). This together with  $x_\alpha \in \text{co}_\Gamma(\{x_0\} \cup H(x_\alpha))$  implies that  $x \in \text{co}_\Gamma(\{x_0\} \cup H(x))$ , which shows that  $B$  is closed. In addition,  $B \cap \partial U = \emptyset$  since (3.4) holds and  $H|_{\partial U} = F|_{\partial U}$ . We now claim that there exists a continuous  $\mu : \bar{U} \rightarrow [0, 1]$  with  $\mu(\partial U) = 0$  and  $\mu(B) = 1$ . Since uniform topological spaces are completely regular, the claim will be true if we show  $B$  is compact. To see this let  $C = \{x_n\}_{n=1}^\infty$  be any sequence in  $B$ . We have  $C \subseteq \text{co}_\Gamma(\{x_0\} \cup H(C))$ . Since  $H \in M_{\partial U}(\bar{U}, E)$ , we have that  $\bar{C}$  is compact and so is sequentially compact by (3.5). Without loss of generality, we may assume  $x_n \rightarrow x \in \bar{C}$ . Now since  $B$  is closed, we get  $x \in B = \bar{B}$ . Consequently  $B = \bar{B}$  is sequentially compact, so is compact from (3.5). By (3.2), there exists a continuous map  $\omega(t, x) : [0, 1] \times E \rightarrow \text{co}_\Gamma\{x_0, x\}$  such that  $\omega(0, x) = x_0$  and  $\omega(1, x) = x$ . Define a map  $R_\mu : \bar{U} \rightarrow E$  by

$$R_\mu(x) = \omega(\mu(x), H(x)).$$

We first show  $R_\mu$  satisfies the Mönch condition. Let  $C \subseteq \bar{U}$  be countable and

$$C \subseteq \text{co}_\Gamma(\{x_0\} \cup R_\mu(C)).$$

Now since  $R_\mu(x) = \omega(\mu(x), H(x)) \subseteq \text{co}_\Gamma(\{x_0\} \cup H(x))$  we have  $R_\mu(C) \subseteq \text{co}_\Gamma(\{x_0\} \cup H(C))$ . Thus

$$C \subseteq \text{co}_\Gamma(\{x_0\} \cup R_\mu(C)) \subseteq \text{co}_\Gamma(\{x_0\} \cup H(C)).$$

Since  $H \in M_{\partial U}(\bar{U}, E)$  we have that  $\bar{C}$  is compact. Thus  $R_\mu \in M_{\partial U}(\bar{U}, E)$  with  $(R_\mu)|_{\partial U} = x_0$ . Now since the constant map  $x_0$  is essential in  $M_{\partial U}(\bar{U}, E)$

there exists  $x \in U$  with  $x = R_\mu(x)$ . Consequently,  $x \in B$  and so  $\mu(x) = 1$  and  $R_\mu(x) = \omega(1, H(x)) = H(x)$ . Thus  $x = H(x)$ .  $\square$

We give now an example of a constant essential map in  $M_{\partial U}(\overline{U}, E)$ .

**Theorem 3.7.** *Let  $(E, \Gamma; \mathcal{U})$  be a complete metrizable, abstract convex uniform space such that every open ball is  $\Gamma$ -convex,  $1_E \in KKM(E, E)$ , and as in section 2 we assume (1.1), (1.2) hold. Let  $U$  be an open subset of  $E$  with  $x_0 \in U$ . Then the constant map  $x_0$  is essential in  $M_{\partial U}(\overline{U}, E)$ .*

*Proof.* We follow the proof of Theorem 2.5 in [1]. Let  $\theta \in M_{\partial U}(\overline{U}, E)$  with  $\theta|_{\partial U} = x_0$ . We must show that there exists  $x \in U$  with  $\theta(x) = x$ . Let  $Q = \overline{co}_\Gamma(\theta(\overline{U}))$  and let  $F : Q \rightarrow Q$  be given by

$$F(x) = \begin{cases} \theta(x) & x \in \overline{U}, \\ x_0 & \text{otherwise.} \end{cases}$$

Now  $x_0 \in Q$ ,  $F : Q \rightarrow Q$  is continuous and satisfies the Mönch condition. To see this let  $C \subseteq Q$  be countable with  $C \subseteq co_\Gamma(\{x_0\} \cup F(C))$ . Then

$$C \subseteq co_\Gamma(\{x_0\} \cup \theta(\overline{U} \cap C)).$$

Notice  $C \cap \overline{U} \subseteq Q$  is countable and  $C \cap \overline{U} \subseteq co_\Gamma(\{x_0\} \cup \theta(\overline{U} \cap C))$ . Now since  $\theta \in M_{\partial U}(\overline{U}, E)$  we have  $\overline{C \cap \overline{U}}$  is compact. Then since  $\theta$  is continuous,  $\theta(\overline{C \cap \overline{U}})$  is compact, and now since  $(E, \Gamma; \mathcal{U})$  satisfies (1.2) and is complete,  $\overline{co}_\Gamma(\{x_0\} \cup \theta(\overline{U} \cap C))$  is compact. Thus since

$$C \subseteq \overline{co}_\Gamma(\{x_0\} \cup \theta(\overline{U} \cap C))$$

we have that  $\overline{C}$  is compact. Corollary 2.5 guarantees that there exists  $x \in Q$  with  $F(x) = x$ . Now if  $x \notin U$  we have  $x_0 = F(x) = x$ , which is a contradiction since  $x_0 \in U$ . Thus  $x \in U$  so  $x = F(x) = \theta(x)$ .  $\square$

Combining Theorem 3.6 and Theorem 3.7 gives the following nonlinear alternative of Leray-Schauder type for Mönch type maps.

**Theorem 3.8.** *Let  $(E, \Gamma; \mathcal{U})$  be a complete metrizable abstract convex uniform space such that every open ball is  $\Gamma$ -convex,  $1_E \in KKM(E, E)$ , and as in section 2 we assume (1.1), (1.2) hold. Let  $U$  be an open subset of  $E$  with  $x_0 \in U$ . Suppose  $F \in M_{\partial U}(\overline{U}, E)$  satisfies (3.4). Then  $F$  is essential in  $M_{\partial U}(\overline{U}, E)$  (in particular  $F$  has a fixed point in  $U$ ).*

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