



ULAM STABILITIES FOR IMPULSIVE INTEGRO-DIFFERENTIAL EQUATIONS

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Abstract. In the present paper, we establish Ulam-Hyres and Ulam-Hyers-Rassias stabilities for nonlinear impulsive integro-differential equations with non-local condition in Banach space. The generalization of Grownwall type inequality is used to obtain our results.

1. INTRODUCTION

A question raised by Ulam [20] in 1940, is answered by Hyers [7] in case of Banach space. Furthermore, Rassias [19] generalised the concept of Ulam-Hyers stability in 1978. Rassias introduced new function variables. Therefore the new concept of stability named with Ulam-Hyers-Rassias stability. The

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Ulam type stability problems attracted many researchers ([12, 14, 15, 18–23]). Kucche and Shikare [12] studied Ulam type stabilities of the following problem:

$$\begin{cases} x'(t) = Ax(t) + f(t, x_t, \int_0^t g_1(t, s, x_s) ds, \int_0^b g_2(t, s, x_s) ds), t \in (0, b], 0 < b < \infty, \\ x(t) = \phi(t), t \in [-r, 0]. \end{cases}$$

In [18], Parthasarathy studied the Ulam problem for impulsive differential equation of the type:

$$\begin{cases} x'(t) = f(t, x(t)), & t \in J' := J \setminus \{t_1, t_2, \dots, t_m\}, \quad J = [0, T], \\ x(t_k^+) = x(t_k^-) + I_k(x(t_k^-)), & k = 1, 2, \dots, m. \end{cases}$$

As per best of our knowledge, Ulam type stabilities for impulsive integro-differential equation with nonlocal condition is not investigated yet. In the present paper we consider impulsive integro-differential equation of first order of the type:

$$\begin{cases} u'(t) = Au(t) + f(t, u_t, \int_0^t k(t, s)h(s, u_s) ds), \\ \quad t \in (0, T], \quad t \neq \tau_k, \quad k = 1, 2, \dots, m, \\ u(t) + (g(u_{t_1}, \dots, u_{t_p}))(t) = \phi(t), \quad -r \leq t \leq 0, \\ \Delta u(\tau_k) = I_k u(\tau_k), \quad k = 1, 2, \dots, m, \end{cases} \quad (1.1)$$

where $0 < t_1 < t_2 < \dots < t_p \leq T$, $p \in \mathbb{N}$, A is the infinitesimal generator of strongly continuous semigroup of bounded linear operators $\{T(t)\}_{t \geq 0}$ and $I_k (k = 1, 2, \dots, m)$ are the linear operators acting in a Banach space X .

Let $k : [0, T] \times [0, T] \rightarrow \mathbb{R}$ be a continuous function and the functions f, h, ϕ and g are given functions satisfying some assumptions. The impulsive moments τ_k are such that $0 \leq \tau_0 < \tau_1 < \tau_2 < \dots < \tau_m < \tau_{m+1} \leq T$, $m \in \mathbb{N}$, $\Delta u(\tau_k) = u(\tau_k + 0) - u(\tau_k - 0)$, where $u(\tau_k + 0)$ and $u(\tau_k - 0)$ are the right and the left limits of u at τ_k , respectively.

Many authors studied existence, uniqueness and other qualitative properties of equations (1.1) and their special forms, see ([1, 3, 6, 8–11]) and the references therein. For more details on impulsive differential equations, see ([3, 13, 16]). The aim of the present paper is to investigate Ulam-Hyres and Ulam-Hyers-Rassias stabilities of mild solution of the problem (1.1). We use generalization of Grownwall type inequality to derive the result.

The paper is organized as follows: In Section 2, we present the preliminaries, hypotheses. In Section 3, we give proof of Ulam-Hyers stability results and Section 4, contains Ulam-Hyers-Rassias stability results.

2. PRELIMINARIES AND HYPOTHESES

Let X be a Banach space with the norm $\|\cdot\|$. Let $C = \mathcal{C}([-r, 0], X)$, $0 < r < \infty$ be the Banach space of all continuous functions $\psi : [-r, 0] \rightarrow X$ endowed with supremum norm $\|\psi\|_C = \sup\{\|\psi(t)\| : -r \leq t \leq 0\}$. $PC([-r, T], X) = \{u : [-r, T] \rightarrow X \mid u(t) \text{ is piecewise continuous at } t \neq \tau_k, \text{ left continuous at } t = \tau_k, \text{ and the right limit } u(\tau_k+0) \text{ exists for } k = 1, 2, \dots, m\}$. Then $PC([-r, T], X)$ is a Banach space with the supremum norm

$$\|u\|_{PC} = \sup\{\|u(t)\| : t \in [-r, T] \setminus \{\tau_1, \tau_2, \dots, \tau_m\}\}.$$

For any $u \in PC([-r, T], X)$ and $t \in [0, T] \setminus \{\tau_1, \tau_2, \dots, \tau_m\}$, we denote u_t the element of C given by $u_t(\theta) = u(t + \theta)$ for $\theta \in [-r, 0]$ and ϕ is a given element of C .

Definition 2.1. A function $u \in PC([-r, T], X)$ satisfied the equations:

$$\begin{aligned} u(t) &= T(t)\phi(0) - T(t)(g(u_{t_1}, \dots, u_{t_p}))(0) \\ &+ \int_0^t T(t-s)f(s, u_s, \int_0^s k(s, \tau)h(\tau, u_\tau)d\tau)ds \\ &+ \sum_{0 < \tau_k < t} T(t - \tau_k)I_k u(\tau_k), \quad t \in (0, T], \\ u(t) + (g(u_{t_1}, \dots, u_{t_p}))(t) &= \phi(t), \quad -r \leq t \leq 0 \end{aligned}$$

is said to be the mild solution of the initial value problem (1.1).

Theorem 2.2. ([17]) *Let $\{T(t)\}_{t \geq 0}$ be a C_0 semigroup. Then there exist constants $\omega \geq 0$ and $M \geq 1$ such that $\|T(t)\| \leq Me^{\omega t}$, $0 < t < \infty$.*

Lemma 2.3. ([2]) *Let for $t \geq t_0$, the following inequality hold:*

$$u(t) \leq a(t) + \int_{t_0}^t b(t, s)u(s)ds + \int_{t_0}^t \left(\int_{t_0}^s k(t, s, \tau)u(\tau)d\tau \right) ds + \sum_{t_0 < \tau_k < t} \beta_k(t)u(t_k),$$

where, $u, a \in PC([t_0, \infty), \mathbb{R}_+)$, a is nondecreasing, $b(t, s)$ and $k(t, s, \tau)$ are continuous and non-negative functions for $t, s, \tau \geq t_0$ and are nondecreasing with respect to t , $\beta_k(t) (k \in \mathbb{N})$ are nondecreasing for $t \geq t_0$. Then for $t \geq t_0$ the following inequality hold :

$$u(t) \leq a(t) \prod_{t_0 < \tau_k < t} (1 + \beta_k(t)) \exp\left(\int_{t_0}^t b(t, s)ds \right) + \int_{t_0}^t \int_{t_0}^s k(t, s, \tau)d\tau ds.$$

Definition 2.4. We say that equation (1.1) has the Ulam-Hyers stability, if there exists a non-negative constant c_1 such that for each $\epsilon > 0$ and u in $PC([-r, T], X)$ satisfies:

$$\begin{cases} \|u'(t) - Au(t) - f(t, u_t, \int_0^t k(t, s)h(s, u_s)ds)\| \leq \epsilon, \\ t \in (0, T], \quad t \neq \tau_k, \quad k = 1, 2, \dots, m, \\ \|u(t) + (g(u_{t_1}, \dots, u_{t_p}))(t) - \phi(t)\| \leq \epsilon, \quad -r \leq t \leq 0, \\ \|\Delta u(\tau_k) - I_k u(\tau_k)\| \leq \epsilon, \quad k = 1, 2, \dots, m, \end{cases} \quad (2.1)$$

then there exists a solution v of the equation (1.1) with

$$\|u - v\|_{PC} \leq c_1 \epsilon.$$

Definition 2.5. We say that equation (1.1) has the generalized Ulam-Hyers stability, if there exists a piecewise continuous function ξ (depend upon f) with $\xi(0) = 0$ such that for each solution v in $PC([-r, T], X)$ of the equation (1.1) with

$$\|u - v\|_{PC} \leq \xi(\epsilon).$$

Definition 2.6. We say that equation (1.1) has the Ulam-Hyers-Rassias stability, if there exists a positive piecewise continuous function $\bar{\psi}(t) : [-r, T] \rightarrow R$ such that for each $\epsilon > 0$ and u in $PC([-r, T], X)$, there exists $c_2 \geq 0$ (depending upon f and $\bar{\psi}(t)$) such that for every $\epsilon > 0$, $\bar{\psi} \geq 0$, if $u \in PC([-r, T], X)$ satisfies:

$$\begin{cases} \|u'(t) - Au(t) - f(t, u_t, \int_0^t k(t, s)h(s, u_s)ds)\| \leq \epsilon \bar{\psi}(t), \\ t \in (0, T], \quad t \neq \tau_k, \quad k = 1, 2, \dots, m, \\ \|u(t) + (g(u_{t_1}, \dots, u_{t_p}))(t) - \phi(t)\| \leq \epsilon \bar{\psi}, \quad -r \leq t \leq 0, \\ \|\Delta u(\tau_k) - I_k u(\tau_k)\| \leq \epsilon \bar{\psi}, \quad k = 1, 2, \dots, m, \end{cases} \quad (2.2)$$

then there exists a solution $v : [-r, T] \rightarrow X$ of the equation (1.1) with

$$\|u - v\|_{PC} \leq \epsilon c_2 (\bar{\psi}(t) + \bar{\psi}(k+1)).$$

Definition 2.7. We say that equation (1.1) has the generalized Ulam-Hyers-Rassias stability, if there exists a positive piecewise continuous function $\bar{\psi}(t) : [-r, T] \rightarrow R$ such that for each $\epsilon > 0$ and u in $PC([-r, T], X)$, there exists $c_2 \geq 0$ (depending upon f and $\bar{\psi}(t)$) such that for every $\epsilon > 0$, $\bar{\psi} \geq 0$ if $u \in PC([-r, T], X)$ satisfies :

$$\begin{cases} \|u'(t) - Au(t) - f(t, u_t, \int_0^t k(t, s)h(s, u_s)ds)\| \leq \bar{\psi}(t), \\ t \in (0, T], \quad t \neq \tau_k, \quad k = 1, 2, \dots, m, \\ \|u(t) + (g(u_{t_1}, \dots, u_{t_p}))(t) - \phi(t)\| \leq \bar{\psi}, \quad -r \leq t \leq 0, \\ \|\Delta u(\tau_k) - I_k u(\tau_k)\| \leq \bar{\psi}, \quad k = 1, 2, \dots, m, \end{cases} \quad (2.3)$$

then there exists a solution $v : [-r, T] \rightarrow X$ of the equation (1.1) with

$$\|u - v\|_{PC} \leq c_2(\bar{\psi}(t) + \bar{\psi}(k + 1))$$

Remark 2.8. A function $u \in PC([-r, T], X)$ is solution of the inequality (2.1). If there exists $b_u \in PC([-r, T], X)$ and a sequence $b_k, k = 1, 2, \dots, m$ (which depend on u) such that

- (1) $\|b_u(t)\| \leq \epsilon, t \in [-r, T]$ and $\|b_k(\tau_k)\| \leq \epsilon, k = 1, 2, \dots, m,$
- (2) $u'(t) = Au(t) + f(t, u_t, \int_0^t k(t, s)h(s, u_s)ds) + b_u(t), t \in (0, T], t \neq \tau_k,$
- (3) $u(t) + (g(u_{t_1}, \dots, u_{t_p}))(t) + b_u(t) = \phi(t), -r \leq t \leq 0,$
- (4) $\Delta u(\tau_k) = I_k u(\tau_k) + b_k(\tau_k), k = 1, 2, \dots, m.$

Proposition 2.9. If $u \in PC([-r, T], X)$ satisfies the set of inequalities (2.1), then u is the solution of following integro-differential equations:

$$\begin{aligned} & \|u(t) - T(t)\phi(0) + T(t)(g(u_{t_1}, \dots, u_{t_p}))(0) \\ & - \int_0^t T(t-s)f(s, u_s, \int_0^s k(s, \tau)h(\tau, u_\tau)d\tau)ds - \sum_{0 < \tau_k < t} T(t - \tau_k)I_k u(\tau_k)\| \\ & \leq \epsilon \left(\int_0^t \|T(t-s)\|ds + \|T(t)\| + \sum_{0 < \tau_k < t} \|T(t - \tau_k)\| \right). \end{aligned}$$

Proof. With Remark 2.8, we have

$$\begin{cases} u'(t) = Au(t) + f(t, u_t, \int_0^t k(t, s)h(s, u_s)ds) + b_u(t), \\ t \in (0, T], t \neq \tau_k, \\ u(t) + (g(u_{t_1}, \dots, u_{t_p}))(t) + b_u(t) = \phi(t), -r \leq t \leq 0, \\ \Delta u(\tau_k) = I_k u(\tau_k) + b_k(\tau_k), k = 1, 2, \dots, m. \end{cases} \tag{2.4}$$

Clearly, the solution of system of equations (2.4) is given by

$$\begin{aligned} u(t) &= T(t)\phi(0) - T(t)(g(u_{t_1}, \dots, u_{t_p}))(0) - T(t)b_u(t) \\ &+ \int_0^t T(t-s)f(s, u_s, \int_0^s k(s, \tau)h(\tau, u_\tau)d\tau)ds + \int_0^t T(t-s)b_u(t)ds \\ &+ \sum_{0 < \tau_k < t} T(t - \tau_k)I_k u(\tau_k) + \sum_{0 < \tau_k < t} T(t - \tau_k)b_k(u(\tau_k)). \end{aligned}$$

It follows that,

$$\begin{aligned}
& \|u(t) - T(t)\phi(0) + T(t)(g(u_{t_1}, \dots, u_{t_p}))(0) \\
& \quad - \int_0^t T(t-s)f(s, u_s, \int_0^s k(s, \tau)h(\tau, u_\tau)d\tau)ds - \sum_{0 < \tau_k < t} T(t - \tau_k)I_k u(\tau_k)\| \\
& \leq \int_0^t \|T(t-s)\| \|b_u(t)\| ds + \|T(t)\| \|b_u(t)\| + \sum_{0 < \tau_k < t} \|T(t - \tau_k)\| \|b_k(u(\tau_k))\| \\
& \leq \epsilon \left(\int_0^t \|T(t-s)\| ds + \|T(t)\| + \sum_{0 < \tau_k < t} \|T(t - \tau_k)\| \right).
\end{aligned}$$

□

Let us introduce the following hypotheses which are assumed thereafter for our convenience.

- (H₁) Let $f : [0, T] \times C \times X \rightarrow X$ and $h : [0, T] \times C \rightarrow X$ be continuous functions such that there exists a continuous nondecreasing function $p : [0, T] \rightarrow \mathbb{R}_+ = [0, \infty)$ and $q : [0, T] \rightarrow \mathbb{R}_+$ such that

$$\begin{aligned}
\|f(t, \psi, u) - f(t, \phi, v)\| & \leq p(t)(\|\psi - \phi\|_C + \|u - v\|), \\
\|h(t, \psi) - h(t, \phi)\| & \leq q(t)\|\psi - \phi\|_C
\end{aligned}$$

for every $t \in [0, T]$, $\psi \in C$ and $u, v \in X$.

- (H₂) Let $g : C^p \rightarrow C$ such that there exists a constant $G \geq 0$ such that

$$\|g(u_{t_1}, u_{t_2}, \dots, u_{t_p}) - g(v_{t_1}, v_{t_2}, \dots, v_{t_p})\| \leq G\|u - v\|.$$

- (H₃) Let $I_k : X \rightarrow X$ are functions such that there exists constants L_k satisfying

$$\|I_k(u) - I_k(v)\| \leq L_k\|u - v\|, u, v \in X, k = 1, 2, \dots, m.$$

3. ULAM-HYRES STABILITY

Theorem 3.1. *Suppose that the hypotheses (H₁)-(H₃) hold. Then the impulsive initial-value problem (1.1) is Ulam-Hyres stable on $[-r, T]$, whenever $1 - MGe^{\omega T} > 0$.*

Proof. Let $u \in PC([-r, T], X)$ satisfies inequalities (2.2), $v \in PC([-r, T], X)$ be the mild solution of equations (1.1).

$$\begin{aligned}
v(t) & = T(t)\phi(0) - T(t)(g(v_{t_1}, \dots, v_{t_p}))(0) \\
& \quad + \int_0^t T(t-s)f(s, v_s, \int_0^s k(s, \tau)h(\tau, v_\tau)d\tau)ds + \sum_{0 < \tau_k < t} T(t - \tau_k)I_k v(\tau_k).
\end{aligned}$$

Using Proposition 2.9 and Theorem 2.2, we obtain,

$$\begin{aligned}
& \|u(t) - T(t)\phi(0) + T(t)(g(u_{t_1}, \dots, u_{t_p}))(0) \\
& \quad - \int_0^t T(t-s)f(s, u_s, \int_0^s k(s, \tau)h(\tau, u_\tau)d\tau)ds - \sum_{0 < \tau_k < t} T(t - \tau_k)I_k u(\tau_k)\| \\
& \leq \epsilon \left(\int_0^t \|T(t-s)\|ds + \|T(t)\| + \sum_{0 < \tau_k < t} \|T(t - \tau_k)\| \right) \\
& \leq \epsilon \left(\int_0^t M e^{\omega(t-s)} ds + M e^{\omega t} + \sum_{0 < \tau_k < t} M e^{\omega(t-\tau_k)} \right) \\
& \leq \epsilon \left(\frac{M}{\omega} e^{\omega t-1} + M e^{\omega t} + k M e^{\omega(t-\tau_k)} \right) \\
& \leq \epsilon \left(\frac{M}{\omega} e^{\omega T-1} + M e^{\omega T} + k M e^{\omega T} \right) \\
& \leq \epsilon \left(\frac{M}{\omega} e^{\omega T-1} + M e^{\omega T} (k+1) \right).
\end{aligned}$$

Now, we have

$$\begin{aligned}
\|u(t) - v(t)\| &= \|u(t) - T(t)\phi(0) + T(t)(g(v_{t_1}, \dots, v_{t_p}))(0) \\
& \quad - \int_0^t T(t-s)f(s, v_s, \int_0^s k(s, \tau)h(\tau, v_\tau)d\tau)ds \\
& \quad - \sum_{0 < \tau_k < t} T(t - \tau_k)I_k v(\tau_k)\| \\
& \leq \|u(t) - T(t)\phi(0) + T(t)(g(u_{t_1}, \dots, u_{t_p}))(0) \\
& \quad - \int_0^t T(t-s)f(s, u_s, \int_0^s k(s, \tau)h(\tau, u_\tau)d\tau)ds \\
& \quad - \sum_{0 < \tau_k < t} T(t - \tau_k)I_k u(\tau_k)\| \\
& \quad + \|T(t)\| \| (g(v_{t_1}, \dots, v_{t_p}))(0) - (g(u_{t_1}, \dots, u_{t_p}))(0) \| \\
& \quad + \int_0^t \|T(t-s)\| \| f(s, u_s, \int_0^s k(s, \tau)h(\tau, u_\tau)d\tau) \\
& \quad - f(s, v_s, \int_0^s k(s, \tau)h(\tau, v_\tau)d\tau) \| ds \\
& \quad + \sum_{0 < \tau_k < t} \|T(t - \tau_k)\| \| I_k u(\tau_k) - I_k v(\tau_k) \|.
\end{aligned}$$

$$\begin{aligned}
&\leq \epsilon \left(\frac{M}{\omega} e^{\omega T-1} ds + M e^{\omega T} (k+1) \right) + M G e^{\omega t} \|v - u\| \\
&\quad + \int_0^t M e^{\omega(t-s)} p(s) [\|u_s - v_s\|_C + \int_0^s Lq(\tau) (\|u_\tau - v_\tau\|_C) d\tau] ds \\
&\quad + \sum_{0 < \tau_k < t} M e^{\omega(t-\tau_k)} L_k \|u(\tau_k) - v(\tau_k)\|.
\end{aligned}$$

Let $R(t) = \sup\{p(t), Lq(t)\}$ and $R^* = \sup\{R(t) : t \in [-r, T]\}$. Define the function $z : [-r, T] \rightarrow \mathbb{R}$ by $z(t) = \sup\{\|u(s) - v(s)\| : -r \leq s \leq t\}, t \in [0, T]$. Let $t^* \in [-r, t]$ be such that $z(t) = \|u(t^*) - v(t^*)\|$. If $t^* \in [0, t]$, then

$$\begin{aligned}
z(t) &\leq \epsilon \left(\frac{M}{\omega} e^{\omega T-1} ds + M e^{\omega T} (k+1) \right) + M e^{\omega t} G z(t) \\
&\quad + \int_0^{t^*} M e^{\omega(t-s)} p(s) [z(s) + \int_0^s Lq(\tau) (z(\tau) d\tau)] ds \\
&\quad + \sum_{0 < \tau_k < t} M e^{\omega(t-\tau_k)} L_k z(\tau_k), \\
(1 - M G e^{\omega t}) z(t) &\leq \epsilon \left(\frac{M}{\omega} e^{\omega T-1} + M e^{\omega T} (k+1) \right) + \int_0^t M e^{\omega T} p(s) z(s) ds \\
&\quad + \int_0^t M e^{\omega T} \int_0^s Lq(\tau) (z(\tau) d\tau) ds + \sum_{0 < \tau_k < t} M e^{\omega T} L_k z(\tau_k) \\
&\leq \frac{\epsilon}{(1 - M G e^{\omega T})} \left(\frac{M}{\omega} e^{\omega T-1} + M e^{\omega T} (k+1) \right) \\
&\quad + \int_0^t \frac{M e^{\omega T}}{(1 - M G e^{\omega T})} p(s) z(s) ds \\
&\quad + \int_0^t \frac{M L e^{\omega T}}{(1 - M G e^{\omega T})} \int_0^s q(\tau) (z(\tau) d\tau) ds \\
&\quad + \sum_{0 < \tau_k < t} \frac{L_k M e^{\omega T}}{(1 - M G e^{\omega T})} z(\tau_k). \tag{3.1}
\end{aligned}$$

If $t^* \in [-r, 0]$, then

$$\begin{aligned}
z(t) &\leq \|(g(v_{t_1}, \dots, v_{t_p}))(0) - (g(u_{t_1}, \dots, u_{t_p}))(0)\| + \|b_v(t) - b_u(t)\| \\
&\leq G \|u - v\| + 2\epsilon. \tag{3.2}
\end{aligned}$$

In the view of inequality (3.1) and (3.2), the inequality (3.1) holds good for $t \in [-r, T]$. Now applying impulsive Lemma 2.3 to (3.1), we get

$$\begin{aligned} z(t) &\leq \frac{\epsilon}{(1 - MG e^{\omega T})} \left(\frac{M}{\omega} e^{\omega T - 1} + M e^{\omega T} (k + 1) \right) \prod_{0 < \tau_k < t} \left(1 + \frac{L_k M e^{\omega T}}{(1 - MG e^{\omega T})} \right) \\ &\quad \times \exp \left\{ \int_0^t \frac{M e^{\omega T}}{(1 - MG e^{\omega T})} R(s) ds + \int_0^t \int_0^s \left[\frac{M L e^{\omega T}}{(1 - MG e^{\omega T})} R(s) R(\tau) d\tau \right] ds \right\} \\ &\leq \frac{\epsilon}{(1 - MG e^{\omega T})} \left(\frac{M}{\omega} e^{\omega T - 1} + M e^{\omega T} (k + 1) \right) \\ &\quad \times \prod_{0 < \tau_k < t} \left(1 + \frac{L_k M e^{\omega T}}{(1 - MG e^{\omega T})} \right) \exp \left\{ \frac{M e^{\omega T}}{(1 - MG e^{\omega T})} \cdot R^* T \left(1 + LR * \frac{T}{2} \right) \right\}. \end{aligned}$$

Therefore, $\|u(t) - v(t)\|_{PC} \leq \epsilon c_1$, where \hat{c} is depend upon f only.

$$\begin{aligned} c_1 &= \frac{\epsilon}{(1 - MG e^{\omega T})} \left(\frac{M}{\omega} e^{\omega T - 1} + M e^{\omega T} (k + 1) \right) \\ &\quad \times \prod_{0 < \tau_k < t} \left(1 + \frac{L_k M e^{\omega T}}{(1 - MG e^{\omega T})} \right) \exp \left\{ \frac{M e^{\omega T}}{(1 - MG e^{\omega T})} R^* T \left(1 + LR * \frac{T}{2} \right) \right\} \end{aligned}$$

for $1 - MG e^{\omega T} > 0$. □

Corollary 3.2. *Assume that the hypotheses (H_1) - (H_3) hold. Then the impulsive initial-value problem (1.1) is generalized Ulam-Hyres stable on $[-r, T]$ for $1 - MG e^{\omega T} > 0$.*

Proof. Define,

$$\begin{aligned} \xi(\epsilon) &\leq \frac{\epsilon}{(1 - MG e^{\omega T})} \left(\frac{M}{\omega} e^{\omega T - 1} ds + M e^{\omega T} (k + 1) \right) \\ &\quad \times \prod_{0 < \tau_k < t} \left(1 + \frac{L_k M e^{\omega T}}{(1 - MG e^{\omega T})} \right) \exp \left\{ \frac{M e^{\omega T}}{(1 - MG e^{\omega T})} R^* T \left(1 + LR * \frac{T}{2} \right) \right\}. \end{aligned}$$

Then $\xi(\epsilon)$ is piecewise continuous and $\xi(0) = 0$. Therefore,

$$\|u(t) - v(t)\|_{PC} \leq \xi(\epsilon). \quad \square$$

4. ULAM-HYRES-RASSIAS STABILITY

Theorem 4.1. *Assume that the hypotheses (H_1) - (H_3) hold. Consider $\bar{\psi} : [-r, T] \rightarrow \mathbb{R}_+$ is positive nondecreasing continuous function and there exists $\lambda > 0$ such that*

$$\int_0^t \bar{\psi}(s) ds \leq \lambda \bar{\psi}(t), \quad t \in [-r, T].$$

Then the impulsive initial-value problem (1.1) is Ulam-Hyers-Rassias stable with respect to $\bar{\psi}(t)$, $\bar{\psi}$ provided that $1 - MGe^{\omega T} > 0$.

Proof. Let $u \in PC([-r, T], X)$ satisfies the inequalities (2.3), $v \in PC([-r, T], X)$ be the mild solution of equations (1.1).

$$\begin{aligned} v(t) &= T(t)\phi(0) - T(t)(g(v_{t_1}, \dots, v_{t_p}))(0) \\ &\quad + \int_0^t T(t-s)f(s, v_s, \int_0^s k(s, \tau)h(\tau, v_\tau)d\tau)ds + \sum_{0 < \tau_k < t} T(t - \tau_k)I_k v(\tau_k). \end{aligned}$$

Using inequalities (2.3) and Theorem 2.2, we obtain,

$$\begin{aligned} &\|u(t) - T(t)\phi(0) + T(t)(g(u_{t_1}, \dots, u_{t_p}))(0) \\ &\quad - \int_0^t T(t-s)f(s, u_s, \int_0^s k(s, \tau)h(\tau, u_\tau)d\tau)ds \\ &\quad - \sum_{0 < \tau_k < t} T(t - \tau_k)I_k u(\tau_k)\| \\ &\leq \left(\int_0^t \|T(t-s)\|ds + \|T(t)\| + \sum_{0 < \tau_k < t} \|T(t - \tau_k)\| \right) \\ &\leq \left(\int_0^t Me^{\omega(t-s)}\epsilon\bar{\psi}(s)ds + Me^{\omega t}\epsilon\bar{\psi} + \sum_{0 < \tau_k < t} Me^{\omega(t-\tau_k)}\epsilon\bar{\psi} \right) \\ &\leq \epsilon\lambda\bar{\psi}(t)Me^{\omega T} + Me^{\omega T}\epsilon\bar{\psi} + \sum_{0 < \tau_k < t} Me^{\omega T}\epsilon\bar{\psi} \\ &\leq \epsilon Me^{\omega T}(\lambda\bar{\psi}(t) + \bar{\psi}(k+1)). \end{aligned}$$

Proceeding in same way as in Theorem 3.1 we obtain,

$$\begin{aligned} z(t) &\leq \frac{\epsilon}{(1 - MGe^{\omega T})}(\lambda\bar{\psi}(t) + \bar{\psi}(k+1)) \prod_{0 < \tau_k < t} \left(1 + \frac{L_k Me^{\omega T}}{(1 - MGe^{\omega T})}\right) \\ &\quad \times \exp\left\{\int_0^t \frac{Me^{\omega T}}{(1 - MGe^{\omega T})}R(s)ds + \int_0^t \int_0^s \left[\frac{MLe^{\omega T}}{(1 - MGe^{\omega T})}R(s)R(\tau)d\tau\right]ds\right\} \\ &\leq \frac{\epsilon}{(1 - MGe^{\omega T})}(\lambda\bar{\psi}(t) + \bar{\psi}(k+1)) \\ &\quad \times \prod_{0 < \tau_k < t} \left(1 + \frac{L_k Me^{\omega T}}{(1 - MGe^{\omega T})}\right) \exp\left\{\frac{Me^{\omega T}}{(1 - MGe^{\omega T})}R^*T\left(1 + LR * \frac{T}{2}\right)\right\}, \end{aligned}$$

$$\|u(t) - v(t)\|_{PC} \leq \epsilon(\lambda\bar{\psi}(t) + \bar{\psi}(k+1))c_2,$$

where, c_2 is depend upon f and $\bar{\psi}(t)$ and

$$c_2 = \frac{1}{(1 - MGe^{\omega T})} \prod_{0 < \tau_k < t} \left(1 + \frac{L_k M e^{\omega T}}{(1 - MGe^{\omega T})}\right) \\ \times \exp \left\{ \frac{M e^{\omega T}}{(1 - MGe^{\omega T})} R^* T \left(1 + LR * \frac{T}{2}\right) \right\}$$

for $1 - MGe^{\omega T} > 0$. □

Corollary 4.2. *Assume that the hypotheses (H_1) - (H_3) hold. Then the impulsive initial-value problem (1.1) is generalized Ulam-Hyres-Rassias stable with respect to $\bar{\psi}(t)$, $\bar{\psi}$ on $[-r, T]$ for $1 - MGe^{\omega T} > 0$.*

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