# FIXED POINT THEOREMS FOR SIX MAPS IN G-METRIC SPACES 

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#### Abstract

In this paper we obtain a unique common fixed point theorem for six mappings in $G$-metric spaces.


## 1. Introduction

In 1992 Dhage introduced a new class of generalized metric spaces called $D$-metric spaces $[1-4]$ as a generalization of ordinary metric function $(X, d)$ and went on to present several fixed point results for single and multivalued mappings. Mustafa and Sims [11] and Naidu et al. [7-9] demonstrated that most of the claims concerning the fundamental topological structure of $D$ metric space are incorrect, alternatively, Mustafa and Sims [12] introduce more appropriate notion of generalized metric space which called $G$-metric spaces, and obtained some topological properties. Later several authors like $[5,6,10$, 13-17] obtained some fixed point theorems for a single map in $G$-metric spaces.

In this paper, we obtain a unique common fixed point theorem for six mappings in $G$-metric spaces and obtain some theorems of [10] and [18] as corollaries to our theorem.

[^0]First, we present some known definitions and propositions in $G$-metric spaces.

Definition 1.1. ([12]) Let $X$ be a nonempty set and let $G: X \times X \times X \rightarrow \mathbb{R}^{+}$ be a function satisfying the following properties :
$\left(G_{1}\right) G(x, y, z)=0$ if $x=y=z$,
$\left(G_{2}\right) 0<G(x, x, y)$ for all $x, y \in X$ with $x \neq y$,
$\left(G_{3}\right) G(x, x, y) \leq G(x, y, z)$ for all $x, y, z \in X$ with $y \neq z$,
$\left(G_{4}\right) G(x, y, z)=G(x, z, y)=G(y, z, x)=\cdots$, symmetry in all three variables, $\left(G_{5}\right) G(x, y, z) \leq G(x, a, a)+G(a, y, z)$ for all $x, y, z, a \in X$.
Then the function $G$ is called a generalized metric or a $G$-metric on $X$ and the pair $(X, G)$ is called a $G$-metric space.

Definition 1.2. ([12]) Let $(X, G)$ be a $G$-metric space and $\left\{x_{n}\right\}$ be a sequence in $X$. A point $x \in X$ is said to be limit of $\left\{x_{n}\right\}$ if $\lim _{n, m \rightarrow \infty} G\left(x, x_{n}, x_{m}\right)=0$. In this case, the sequence $\left\{x_{n}\right\}$ is said to be $G$-convergent to $x$.

Definition 1.3. ([12]) Let $(X, G)$ be a $G$-metric space and $\left\{x_{n}\right\}$ be a sequence in $X .\left\{x_{n}\right\}$ is called $G$-Cauchy if $\lim _{n, m, l \rightarrow \infty} G\left(x_{l}, x_{n}, x_{m}\right)=0$. And $(X, G)$ is called $G$-complete if every $G$-Cauchy sequence in $(X, G)$ is $G$-convergent in $(X, G)$.

Proposition 1.4. ([12]) In a $G$-metric space $(X, G)$, the following are equivalent.
(1) The sequence $\left\{x_{n}\right\}$ is $G$-Cauchy.
(2) For every $\varepsilon>0$, there exists $N \in \mathbf{N}$ such that $G\left(x_{n}, x_{m}, x_{m}\right)<\varepsilon$, for all $n, m \geq N$.

Proposition 1.5. ([12]) Let $(X, G)$ be a $G$-metric space. Then the function $G(x, y, z)$ is jointly continuous in all three of its variables.

Proposition 1.6. ([12]) Let $(X, G)$ be a $G$-metric space. Then for any $x, y, z$, $a \in X$, it follows that
(i) if $G(x, y, z)=0$ then $x=y=z$,
(ii) $G(x, y, z) \leq G(x, x, y)+G(x, x, z)$,
(iii) $G(x, y, y) \leq 2 G(x, x, y)$,
(iv) $G(x, y, z) \leq G(x, a, z)+G(a, y, z)$,
(v) $G(x, y, z) \leq \frac{2}{3}[G(x, a, a)+G(y, a, a)+G(z, a, a)]$.

Proposition 1.7. ([12]) Let $(X, G)$ be a $G$-metric space. Then for a sequence $\left\{x_{n}\right\} \subseteq X$ and a point $x \in X$, the following are equivalent
(i) $\left\{x_{n}\right\}$ is $G$-convergent to $x$,
(ii) $G\left(x_{n}, x_{n}, x\right) \rightarrow 0$ as $n \rightarrow \infty$,
(iii) $G\left(x_{n}, x, x\right) \rightarrow 0$ as $n \rightarrow \infty$,
(iv) $G\left(x_{m}, x_{n}, x\right) \rightarrow 0$ as $m, n \rightarrow \infty$.

Definition 1.8. ([12]) Let $(X, G)$ and $\left(X^{\prime}, G^{\prime}\right)$ be two $G$-metric spaces, and let $f:(X, G) \rightarrow\left(X^{\prime}, G^{\prime}\right)$ be a function. Then $f$ is said to be $G$-continuous at a point $a \in X$ if and only if, given $\varepsilon>0$, there exists $\delta>0$ such that $x, y \in X$; and $G(a, x, y)<\delta$ implies $G^{\prime}(f(a), f(x), f(y))<\varepsilon$. A function $f$ is $G$-continuous at $X$ if and only if it is $G$-continuous at all $a \in X$.

Proposition 1.9. ([12]) Let $(X, G)$, and $\left(X^{\prime}, G^{\prime}\right)$ be two $G$-metric spaces. Then a function $f: X \longrightarrow X^{\prime}$ is $G$-continuous at a point $x \in X$ if and only if it is $G$-sequentially continuous at $x$; that is, whenever $\left\{x_{n}\right\}$ is $G$-convergent to $x$ we have $\left\{f\left(x_{n}\right)\right\}$ is $G$-convergent to $f(x)$.

We recall that two maps $f$ and $g$ are said to be weak compatible if they commute at their coincidence point, that is, $f x=g x$ implies that $f g x=g f x$.

The main aim of this paper is to present a generalization of Theorem 2.1 in [18].

## 2. Main Result

Let $\Phi$ denote the class of all functions $\phi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$such that $\phi$ is non decreasing, continuous and $\sum_{n=1}^{\infty} \phi^{n}(t)<\infty$ for all $t>0$. It is clear that $\phi^{n}(t) \rightarrow$ 0 as $n \rightarrow \infty$ for all $t>0$ and hence, we have $\phi(t)<t$, for all $t>0$.

Theorem 2.1. Let $(X, G)$ be a $G$-Complete metric space and $A, B, C, S, T, R$ : $X \rightarrow X$ be satisfying:
(i) $A(X) \subseteq T(X), B(X) \subseteq R(X), C(X) \subseteq S(X)$ and either one of $T(X)$, $R(X)$ or $S(X)$ is a closed subset of $X$,
(ii) the pair $(A, S),(B, T)$ and $(C, R)$ are weakly compatible,
(iii)

$$
G(A x, B y, C z) \leq \phi\left(\max \left\{\begin{array}{c}
G(S x, T y, R z), \frac{1}{2} G(S x, A x, B y),  \tag{2.1}\\
\frac{1}{2} G(T y, B y, C z), \frac{1}{2} G(R z, C z, A x)
\end{array}\right\}\right)
$$

for all $x, y, z \in X$, where $\phi \in \Phi$. Then the maps $A, B, C, T, R$ and $S$ have $a$ unique common fixed point, say $p \in X$ and if $T, R$ and $S$ are $G$-continuous at $p$ then $A, B$ and $C$ are $G$-continuous at $p$.

Proof. Choose $x_{0} \in X$. Define the sequence $y_{3 n}=A x_{3 n}=T x_{3 n+1}, y_{3 n+1}=$ $B x_{3 n+1}=R x_{3 n+2}, y_{3 n+2}=C x_{3 n+2}=S x_{3 n+3}, n=0,1,2, \cdots$. Denote $d_{n+1}=$ $G\left(y_{n}, y_{n+1}, y_{n+2}\right)$. Then in general we have

$$
\begin{aligned}
& d_{3 n+1}=G\left(y_{3 n}, y_{3 n+1}, y_{3 n+2}\right) \\
& =G\left(A x_{3 n}, B x_{3 n+1}, C x_{3 n+2}\right) \\
& \leq \phi\left(\max \left\{\begin{array}{c}
G\left(S x_{3 n}, T x_{3 n+1}, R x_{3 n+2}\right), \frac{1}{2} G\left(S x_{3 n}, A x_{3 n}, B x_{3 n+1}\right), \\
\frac{1}{2} G\left(T x_{3 n+1}, B x_{3 n+1}, C x_{3 n+2}\right), \frac{1}{2} G\left(R x_{3 n+2}, C x_{3 n+2}, A x_{3 n}\right)
\end{array}\right\}\right) \\
& =\phi\left(\max \left\{\begin{array}{l}
G\left(y_{3 n-1}, y_{3 n}, y_{3 n+1}\right), \frac{1}{2} G\left(y_{3 n-1}, y_{3 n}, y_{3 n+1}\right), \\
\frac{1}{2} G\left(y_{3 n}, y_{3 n+1}, y_{3 n+2}\right), \frac{1}{2} G\left(y_{3 n+1}, y_{3 n+2}, y_{3 n}\right)
\end{array}\right\}\right) \\
& \leq \phi\left(\operatorname { m a x } \left\{\begin{array}{l}
\left.\left.d_{3 n}, \frac{1}{2} d_{3 n}, \frac{1}{2} d_{3 n+1}, \frac{1}{2} d_{3 n+1}\right\}\right) .
\end{array}\right.\right.
\end{aligned}
$$

Hence, we must have $d_{3 n+1} \leq \phi\left(d_{3 n}\right)$. Similarly, we will have $d_{3 n+2} \leq \phi\left(d_{3 n+1}\right)$ and $d_{3 n+3} \leq \phi\left(d_{3 n+2}\right)$. Thus $d_{n+1} \leq \phi\left(d_{n}\right), n=1,2,3, \cdots$, so,

$$
\begin{align*}
G\left(y_{n}, y_{n+1}, y_{n+2}\right) & \leq \phi\left(G\left(y_{n-1}, y_{n}, y_{n+1}\right)\right) \\
& \leq \phi^{2}\left(G\left(y_{n-2}, y_{n-1}, y_{n}\right)\right) \\
& \cdot  \tag{2.2}\\
& \cdot \\
& \cdot \\
& \leq \phi^{n}\left(G\left(y_{0}, y_{1}, y_{2}\right)\right)
\end{align*}
$$

From $\left(G_{3}\right)$ and (2.2), we have

$$
\begin{equation*}
G\left(y_{n}, y_{n}, y_{n+1}\right) \leq G\left(y_{n}, y_{n+1}, y_{n+2}\right) \leq \phi^{n}\left(G\left(y_{0}, y_{1}, y_{2}\right)\right) \tag{2.3}
\end{equation*}
$$

For $m>n$, since $\sum_{n=1}^{\infty} \phi^{n}(t)<\infty$ for all $t>0$, we have

$$
\begin{aligned}
& G\left(y_{n}, y_{n}, y_{m}\right) \\
& \leq \sum_{i=n}^{m-1} G\left(y_{i}, y_{i}, y_{i+1}\right) \\
& \leq \phi^{n}\left(G\left(y_{0}, y_{1}, y_{2}\right)\right)+\phi^{n+1}\left(G\left(y_{0}, y_{1}, y_{2}\right)\right)+\ldots+\phi^{m-1}\left(G\left(y_{0}, y_{1}, y_{2}\right)\right) \\
& \leq \sum_{i=n}^{\infty} \phi^{i}\left(G\left(y_{0}, y_{1}, y_{2}\right)\right) \\
& \rightarrow 0 \text { as } n \rightarrow \infty
\end{aligned}
$$

Hence, $\left\{y_{n}\right\}$ is a $G$-Cauchy sequence from Proposition 1.4. Since $X$ is $G$ complete, there exists $p \in X$ such that $y_{n} \rightarrow p(n \rightarrow \infty)$, that is, $\lim _{n \rightarrow \infty} y_{n}=$ $p$,

$$
\begin{aligned}
\lim _{n \rightarrow \infty} y_{n} & =\lim _{n \rightarrow \infty} A x_{3 n}=\lim _{n \rightarrow \infty} B x_{3 n+1}=\lim _{n \rightarrow \infty} C x_{3 n+2} \\
& =\lim _{n \rightarrow \infty} T x_{3 n+1}=\lim _{n \rightarrow \infty} R x_{3 n+2}=\lim _{n \rightarrow \infty} S x_{3 n+3}=p
\end{aligned}
$$

Let $T(X)$ be a closed subset of $X$. Then there exists $v \in X$ such that $T v=p$. We prove that $B v=p$. For

$$
\begin{aligned}
& G\left(A x_{3 n}, B v, C x_{3 n+2}\right) \\
& \leq \phi\left(\max \left\{\begin{array}{c}
G\left(S x_{3 n}, T v, R x_{3 n+2}\right), \frac{1}{2} G\left(S x_{3 n}, A x_{3 n}, B v\right), \\
\frac{1}{2} G\left(T v, B v, C x_{3 n+2}\right), \frac{1}{2} G\left(R x_{3 n+2}, C x_{3 n+2}, A x_{3 n}\right)
\end{array}\right\}\right) \\
& =\phi\left(\max \left\{\begin{array}{l}
G\left(y_{3 n-1}, p, y_{3 n+1}\right), \frac{1}{2} G\left(y_{3 n-1}, y_{3 n}, B v\right), \\
\frac{1}{2} G\left(p, B v, y_{3 n+2}\right), \frac{1}{2} G\left(y_{3 n+1}, y_{3 n+2}, y_{3 n}\right)
\end{array}\right\}\right) .
\end{aligned}
$$

Letting $n \rightarrow \infty$, we get

$$
G(p, B v, p) \leq \phi\left(\max \left\{0, \frac{1}{2} G(p, p, B v), \frac{1}{2} G(p, B v, p), 0\right\}\right),
$$

and we have $B v=T v=p$, since $\phi(t)<t$ for all $t>0$. Since $p=B v \in$ $B(X) \subseteq R(X)$, there exists $z \in X$ such that $R z=p$. Similarly, putting $x=x_{3 n}, y=x_{3 n+1}, z=p$ in (1) and letting $n \rightarrow \infty$, we get $C z=p$. Since $p=C z \in C(X) \subseteq S(X)$, there exists $u \in X$ such that $S u=p$.

Similarly, putting $x=p, y=x_{3 n+1}, z=x_{3 n+2}$ in (1) and letting $n \rightarrow \infty$, we get $A u=p$. By weak compatible the pair $(A, S)$, we have $A S u=S A u$, and $A p=S p$. Also, $B p=T p$ and $R p=C p$. We prove that $A p=p$. If $A p \neq p$, then

$$
\left.\left.\begin{array}{l}
G\left(A p, B x_{3 n+1}, C x_{3 n+2}\right) \\
\leq \phi\left(\max \left\{\begin{array}{c}
G\left(S p, T x_{3 n+1}, R x_{3 n+2}\right), \frac{1}{2} G\left(S p, A p, B x_{3 n+1}\right), \\
\frac{1}{2} G\left(T x_{3 n+1}, B x_{3 n+1}, C x_{3 n+2}\right), \frac{1}{2} G\left(R x_{3 n+2}, C x_{3 n+2}, A p\right)
\end{array}\right\}\right) \\
G\left(A p, y_{3 n}, y_{3 n+1}\right), \frac{1}{2} G\left(A p, A p, y_{3 n+1}\right), \\
\frac{1}{2} G\left(y_{3 n}, y_{3 n+1}, y_{3 n+1}\right), \frac{1}{2} G\left(y_{3 n+1}, y_{3 n+2}, A p\right)
\end{array}\right\}\right) .
$$

Letting $n \rightarrow \infty$, we get

$$
\begin{aligned}
G(A p, p, p) & \leq \phi\left(\max \left\{G(A p, p, p), \frac{1}{2} G(A p, A p, p), 0, \frac{1}{2} G(p, p, A p)\right\}\right) \\
& \leq \phi\left(\max \left\{G(A p, p, p), G(A p, p, p), 0, \frac{1}{2} G(p, p, A p)\right\}\right)
\end{aligned}
$$

and we have $A p=p$, since $\phi(t)<t$ for all $t>0$. Similarly, putting $x=$ $x_{3 n}, y=p, z=x_{3 n+2}$ and $x=x_{3 n}, y=x_{3 n+1}, z=p$ in (1) and letting $n \rightarrow \infty$, we get $B p=p$ and $C p=p$, respectively. Thus $p$ is a common fixed point of $A, B, C, T, R$ and $S$.

Suppose $p^{\prime}$ is another common fixed point of $A, B, C, T, R$ and $S$. Then from (1), we have

$$
G\left(A p, B p, C p^{\prime}\right) \leq \phi\left(\max \left\{G\left(p, p, p^{\prime}\right), 0, \frac{1}{2} G\left(p, p, p^{\prime}\right), \frac{1}{2} G\left(p^{\prime}, p^{\prime}, p\right)\right\}\right) .
$$

Thus, $G\left(p, p, p^{\prime}\right) \leq \phi\left(G\left(p, p, p^{\prime}\right)\right.$ so that $p=p^{\prime}$. Thus, $p$ is the unique common fixed point of $A, B, C, T, R$ and $S$. Let $\left\{y_{n}\right\}$ be any sequence in $X$
such that $\left\{y_{n}\right\}$ is $G$-convergent to $p$. Then we have

$$
\begin{aligned}
& G\left(A y_{n}, A p, A p\right)=G\left(A y_{n}, B p, C p\right) \\
& \leq \phi\left(\max \left\{\begin{array}{c}
G\left(S y_{n}, p, p\right), \frac{1}{2} G\left(S y_{n}, A y_{n}, p\right), \\
0, \frac{1}{2} G\left(p, p, A y_{n}\right)
\end{array}\right\}\right) \\
& \leq \phi\left(\max \left\{\begin{array}{c}
G\left(S y_{n}, p, p\right), \frac{1}{2} G\left(S y_{n}, p, p\right)+\frac{1}{2} G\left(p, A y_{n}, p\right), \\
0, \frac{1}{2} G\left(p, p, A y_{n}\right)
\end{array}\right\}\right) .
\end{aligned}
$$

Letting $n \rightarrow \infty$, then since $S$ is $G$-continuous at $p$ we get, $\alpha \leq \phi\left(\frac{1}{2} \alpha\right)$, where

$$
\alpha=\lim _{n \rightarrow \infty} G\left(A y_{n}, A p, A p\right) .
$$

This implies that $\alpha=0$. Then from Proposition 1.9, we deduce that $A$ is $G$ continuous at $p$. Similarly, we can show that $B$ and $C$ are also $G$-continuous at $p$.

Corollary 2.2. (Corollary 2.1 of [18]) Let $(X, G)$ be a $G$-Complete metric space and $A, B, C: X \rightarrow X$ be satisfying:

$$
G(A x, B y, C z) \leq \phi\left(\max \left\{\begin{array}{c}
G(x, y, z), \frac{1}{2} G(x, A x, B y),  \tag{2.4}\\
\frac{1}{2} G(y, B y, C z), \frac{1}{2} G(z, C z, A x)
\end{array}\right\}\right)
$$

for all $x, y, z \in X$, where $\phi \in \Phi$. Then the maps $A, B, C$ have a unique common fixed point, say $p \in X$ and $A, B$ and $C$ are $G$-continuous at $p$.

Proof. Take $T=R=S=I$ identity map in Theorem 2.1.

Corollary 2.3. Let $(X, G)$ be a $G$-Complete metric space and $A, B: X \rightarrow X$ be satisfying:
(i) $A(X) \subseteq B(X), B(X)$ is a closed subset of $X$ and the pair $(A, B)$ is weakly compatible,
(ii)

$$
G(A x, A y, A z) \leq \phi\left(\max \left\{\begin{array}{c}
G(B x, B y, B z), \frac{1}{2} G(B x, A x, A y),  \tag{2.5}\\
\frac{1}{2} G(B y, A y, A z), \frac{1}{2} G(B z, A z, A x)
\end{array}\right\}\right)
$$

for all $x, y, z \in X$, where $\phi \in \Phi$. Then the maps $A, B$ have a unique common fixed point, say $p \in X$ and if $B$ is $G$-continuous at $p$ then $A$ is $G$-continuous at $p$.

Proof. Take $B=C=A$ and $T=R=S=B$ in Theorem 2.1.
The following example illustrates Theorem 2.1 with $\phi(t)=\frac{t}{2}$.

Example 2.4. Let $X=[0,1]$ and $G(x, y, z)=|x-y|+|y-z|+|z-x|$ for all $x, y, z \in X$. Define $A, B, C, T, R, S: X \rightarrow X$ as $A x=C x=1, B x=\frac{3+x}{4}$, $T x=x, S x=\frac{x^{2}+x}{2}, R x=\frac{2+x^{2}}{3}$ for all $x \in X$.
$G(A x, B y, C z)$
$=\frac{1-y}{2}$
$=\frac{1}{4} 2(1-y)$
$=\frac{1}{4} G(y, B y, C z)=\frac{1}{2}\left(\frac{1}{2} G(T y, B y, C z)\right)$
$\leq \frac{1}{2} \max \left\{G(S x, T y, C z), \frac{1}{2} G(S x, A x, B y), \frac{1}{2} G(T y, B y, C z), \frac{1}{2} G(R z, C z, A x)\right\}$.
Also, it is easy to see that $A(X) \subseteq T(X), B(X) \subseteq R(X), C(X) \subseteq S(X)$ and $T(X)=X$ is a closed subset of $X$. Moreover, the pair $(A, S),(B, T)$ and $(C, R)$ are weakly compatible. Hence the all of conditions of Theorem 2.1 are hold and 1 is the unique common fixed point of $A, B, C, T, R$ and $S$.

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