



REMARKS ON THE PROPERTIES OF WASSERSTEIN MEDIAN ON SYMMETRIC CONES

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Abstract. The author studied a one-parameter family of divergences and the related median minimization problem of finite points over these divergences in a symmetric cone [14]. The unique solution of the minimization problem with a weight ω is called the ω -weighted Wasserstein median. Recently, in the special symmetric cone of the positive definite matrices, Hwang and Kim [8] explored several properties of the Wasserstein mean and found bounds for the Wasserstein mean with respect to Löwner order. Also Kim and Lee [10] presented some relations between the Wasserstein mean and other well-known matrix means such as the power mean, harmonic mean and Karcher mean. Motivated by these results, as an application of the previous work [14], we investigate several properties of the ω -weighted Wasserstein median which mainly extend the corresponding ones in [8, 10] into a general symmetric cone Ω with a purely Jordan-algebraic technique.

1. INTRODUCTION

A divergence, which measures discrepancy between two points, plays a crucial role in many problems such as information theory, statistics, optimization, computational vision, and neural networks [1, 2, 3]. For the definition of divergence, readers may refer to [14]. As is known, a divergence is almost a distance function except the symmetry with respect to its arguments and the triangle inequality. For instance, the square of a distance function is a (symmetric) divergence. Thus a divergence Φ gives rise to an important optimization problem

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like a least squares problem on a Riemannian manifold M :

$$\arg \min_{x \in M} \sum_{j=1}^m w_j \Phi(a_j, x), \tag{1.1}$$

where $a_1, \dots, a_m \in M$ and $\omega = (w_1, \dots, w_m) \in \mathbb{R}^m$ is a positive probability vector. So a minimizer whenever it exists provides alternatively a barycenter or averaging on M , which is called the ω -weighted Φ -median of a_1, \dots, a_m .

In a recent work [14], this median optimization problem on a special Riemannian manifold called symmetric cones is studied. The main result in [14] is briefly summarized as follow: Let V be a Euclidean Jordan algebra and let Ω be the symmetric cone (see section 2 for basic facts regarding Euclidean Jordan algebras and symmetric cones). Consider the function $\Phi_t : \Omega \times \Omega \rightarrow \mathbb{R}$ defined by

$$\Phi_t(a, b) = \text{tr}((1-t)a + tb) - \text{tr}\left(P\left(a^{\frac{1-t}{2t}}\right)b\right)^t, \quad 0 < t < 1, \tag{1.2}$$

where tr is the trace functional and P is the quadratic representation of V .

Theorem 1.1. ([14]) *For every $0 < t < 1$, Φ_t is a divergence on Ω . Moreover, the minimization problem*

$$\arg \min_{x \in \Omega} \sum_{j=1}^m w_j \Phi_t(a_j, x) \tag{1.3}$$

has a unique minimizer.

A meaningful reason to take the divergence (1.2) into account stems from the followings: The term $F_t(a, b) = \text{tr}\left(P\left(a^{\frac{1-t}{2t}}\right)b\right)^t$ in (1.2) is known as *sandwiched quasi-relative entropy* in the theory of quantum information; for positive (semi)definite matrices A and B ,

$$F_t(A, B) = \text{tr}\left(A^{\frac{1-t}{2t}} B A^{\frac{1-t}{2t}}\right)^t, \quad t \in (0, 1). \tag{1.4}$$

This is a parameterized version of the *fidelity* $F_{\frac{1}{2}}(A, B) = \text{tr}\left(A^{\frac{1}{2}} B A^{\frac{1}{2}}\right)^{\frac{1}{2}}$. Fidelity and sandwiched quasi-relative entropies play an essential role in quantum information theory and quantum computation [7, 20, 21, 22]. In addition, the extended version d_W on the set of positive definite matrices of the *Bures distance* in quantum information is defined by

$$d_W(A, B) = \left[\text{tr}\left(\frac{A+B}{2}\right) - \text{tr}\left(A^{\frac{1}{2}} B A^{\frac{1}{2}}\right)^{\frac{1}{2}} \right]^{\frac{1}{2}},$$

which is also known as the *Wasserstein distance* in statistics and the theory of optimal transport [5, 12, 19]. Clearly, $d_W^2(A, B) = \Phi_{\frac{1}{2}}(A, B)$. This implies that the divergence (1.2) may have a rich background in various areas mentioned above even though its square root is not a distance in general [14]. From now on, we call the unique minimizer of (1.3) the ω -weighted Wasserstein median of a_1, \dots, a_m .

A motivation of this paper is as follows. Recently, in the special symmetric cone of the positive definite matrices, Hwang and Kim [8] explored several properties of the Wasserstein mean and found bounds for the Wasserstein mean with respect to Löwner order. Also Kim and Lee [10] presented some relations between the Wasserstein mean and other well-known matrix means such as the power mean, harmonic mean and Karcher mean. Motivated by these results, as a continuation or an application of the previous work [14], in the present paper, we investigate several important properties of the ω -weighted Wasserstein median of a_1, \dots, a_m which mainly extend the corresponding ones in [8, 10] into the setting of a general symmetric cone Ω with a purely Jordan-algebraic technique.

2. EUCLIDEAN JORDAN ALGEBRAS AND SYMMETRIC CONES

Before stating the motivation of this work, first we briefly describe (following mostly [6, 14]) some Jordan-algebraic concepts relevant to our purpose. A Jordan algebra V over \mathbb{R} is a *non-associative* commutative algebra satisfying $x^2(xy) = x(x^2y)$ for all $x, y \in V$. For $x \in V$, let L_x be the linear operator defined by $L_x y = xy$, and let $P(x) = 2L_x^2 - L_{x^2}$. The map P is called the quadratic representation of V . An element $x \in V$ is said to be invertible if there exists an element y (denoted by $y = x^{-1}$) in the subalgebra generated by x and e (the Jordan identity) such that $xy = e$.

The following appears at [6, Propositions II.3.1, II.3.2].

Proposition 2.1. *Let V be a Jordan algebra.*

- (i) *An element x in V is invertible if and only if $P(x)$ is invertible. In this case: $P(x)^{-1} = P(x^{-1})$.*
- (2) *If x and y are invertible, then $P(x)y$ is invertible and $(P(x)y)^{-1} = P(x^{-1})y^{-1}$.*
- (iii) *For any elements x and y , $P(P(x)y) = P(x)P(y)P(x)$. In particular, $P^m(x) = P(x^m)$, $m \geq 1$.*

An element $c \in V$ is called an idempotent if $c^2 = c$. We say that c_1, \dots, c_k is a complete system of orthogonal idempotents if $c_i^2 = c_i$, $c_i c_j = 0$, $i \neq j$ and $c_1 + \dots + c_k = e$. An idempotent is said to be primitive if it is non-zero and

cannot be written as the sum of two non-zero idempotents. A Jordan frame is a complete system of orthogonal primitive idempotents.

A finite-dimensional Jordan algebra V with an identity element e is said to be *Euclidean* if there exists an inner product $\langle \cdot, \cdot \rangle$ such that $\langle xy, z \rangle = \langle y, xz \rangle$ for all $x, y, z \in V$.

Theorem 2.2. (Spectral theorem, first version [6, Theorem III.1.1]) *Let V be a Euclidean Jordan algebra. Then for $x \in V$, there exist real numbers $\lambda_1, \dots, \lambda_k$ all distinct and a unique complete system of orthogonal idempotents c_1, \dots, c_k such that*

$$x = \sum_{i=1}^k \lambda_i c_i. \quad (2.1)$$

The numbers λ_i are called the eigenvalues and (2.1) is called the spectral decomposition of x .

Theorem 2.3. (Spectral theorem, second version [6, Theorem III.1.2]) *Any two Jordan frames in a Euclidean Jordan algebra V have the same number of elements (called the rank of V , denoted by $\text{rank}(V)$). Given $x \in V$, there exists a Jordan frame c_1, \dots, c_r and real numbers $\lambda_1, \dots, \lambda_r$, where r is the rank of V , such that $x = \sum_{i=1}^r \lambda_i c_i$. The numbers λ_i (with their multiplicities) are uniquely determined by x .*

Definition 2.4. Let V be a Euclidean Jordan algebra of $\text{rank}(V) = r$. The spectral mapping $\lambda : V \rightarrow \mathbb{R}^r$ is defined by $\lambda(x) = (\lambda_1(x), \dots, \lambda_r(x))$, where $\lambda_i(x)$'s are eigenvalues of x (with multiplicities) as in Theorem 2.3 in non-increasing order $\lambda_{\max}(x) = \lambda_1(x) \geq \lambda_2(x) \geq \dots \geq \lambda_r(x) = \lambda_{\min}(x)$. Furthermore, $\det(x) = \prod_{i=1}^r \lambda_i(x)$ and $\text{tr}(x) = \sum_{i=1}^r \lambda_i(x)$.

Let Q be the set of all square elements of V . Then Q is a closed convex cone of V with $Q \cap -Q = \{0\}$, and is the set of elements $x \in V$ such that $L(x)$ is positive semi-definite. It turns out that Q has non-empty interior $\Omega := \text{int}(Q)$, and Ω is a symmetric cone, that is, the group $G(\Omega) = \{g \in \text{GL}(V) \mid g(\Omega) = \Omega\}$ acts transitively on it and Ω is a self-dual cone with respect to the inner product $\langle \cdot, \cdot \rangle$ (see [6]). We say that $g \in \text{GL}(V)$ is a Jordan automorphism if $g(xy) = g(x)g(y)$ for all $x, y \in V$. For an element $g \in G(\Omega)$, g is a Jordan automorphism if and only if $g(e) = e$ [6, Propositions VIII.2.4, 2.8] or [11]).

Note that $\bar{\Omega} = \{x \in V \mid \lambda_i(x) \geq 0, i = 1, \dots, r\}$. For $x, y \in V$, we define the Löwner order by

$$x \leq y \quad \text{if} \quad y - x \in \bar{\Omega}$$

and $x < y$ if $y - x \in \Omega$. Clearly $\bar{\Omega} = \{x \in V \mid x \geq 0\}$ and $\Omega = \{x \in V \mid x > 0\}$. Furthermore, for any $a \in \Omega$, $P(a) \in G(\Omega)$ so that $P(a)$ is an order preserving linear operator.

On the other hand, the symmetric cone Ω in V admits a $G(\Omega)$ -invariant Riemannian metric defined by

$$\langle u, v \rangle_x = \langle P(x)^{-1}u, v \rangle, \quad x \in \Omega, \quad u, v \in V. \tag{2.2}$$

So Ω is a Riemannian manifold [6]. It is shown in [16, Proposition 2.6] that the unique geodesic joining a and b is

$$t \mapsto a \#_t b := P(a^{1/2})(P(a^{-1/2})b)^t, \tag{2.3}$$

where $a^t = \sum_{j=1}^r \lambda_j(a)^t c_j$ for the spectral decomposition $a = \sum_{j=1}^r \lambda_j(a) c_j$ in Theorem 2.3. The geometric mean of a and b is defined to be $a \# b := a \#_{1/2} b$, which is a unique geodesic middle between a and b . It is well-known that $a \# b$ is the unique solution on Ω of the following quadratic equation, called the Riccati equation:

$$P(x)a^{-1} = b. \tag{2.4}$$

3. MAIN RESULTS

For simplicity, in what follows, we restrict our attention only to the case $t = 1/2$. In this case, we denote by $W(\omega; a_1, \dots, a_m)$ the unique minimizer of (1.3), that is, the ω -weighted Wasserstein median of a_1, \dots, a_m ,

$$\begin{aligned} W(\omega; a_1, \dots, a_m) &= \arg \min_{x \in \Omega} \sum_{j=1}^m w_j \Phi_{\frac{1}{2}}(a_j, x) \\ &= \arg \min_{x \in \Omega} \sum_{j=1}^m w_j \left(\operatorname{tr} \left(\frac{a_j + x}{2} \right) - \operatorname{tr} \left(P(a_j^{\frac{1}{2}})x \right)^{\frac{1}{2}} \right). \end{aligned} \tag{3.1}$$

Let $\mathbb{A} = (a_1, \dots, a_m) \in \Omega^m$ and let σ be a permutation on $\{1, \dots, m\}$. We need the following notations:

$$\begin{aligned} W(\omega; \mathbb{A}) &= W(\omega; a_1, \dots, a_m), \\ \mathbb{A}_\sigma &= (a_{\sigma(1)}, \dots, a_{\sigma(m)}), \\ \mathbb{A}^k &= (\underbrace{a_1, \dots, a_m}_{k \text{ times}}, \dots, \underbrace{a_1, \dots, a_m}_{k \text{ times}}) \in \Omega^{km}, \\ \omega_\sigma &= (w_{\sigma(1)}, \dots, w_{\sigma(m)}), \\ \omega^k &= \frac{1}{k}(\underbrace{w_1, \dots, w_m}_{k \text{ times}}, \dots, \underbrace{w_1, \dots, w_m}_{k \text{ times}}) \in \mathbb{R}^{km}, \end{aligned}$$

where the number of blocks of the above expressions is a positive integer k , and $\omega = (w_1, \dots, w_m) \in \mathbb{R}^m$ is a positive probability vector as before. We begin with simple observations.

Theorem 3.1. *The following properties of the ω -weighted Wasserstein median of a_1, \dots, a_m are satisfied.*

- (i) $W(\omega; \alpha\mathbb{A}) = \alpha W(\omega; \mathbb{A})$ for any $\alpha > 0$ (Positive homogeneity).
- (ii) $W(\omega_\sigma; \mathbb{A}_\sigma) = W(\omega; \mathbb{A})$ for any permutation σ on $\{1, \dots, m\}$ (Permutation invariance).
- (iii) $W(\omega^k; \mathbb{A}^k) = W(\omega; \mathbb{A})$ for any $k \in \mathbb{N}$ (Repetition invariance).

Proof. First observe that according to [14, (5.3)], the ω -weighted Wasserstein median $x_0 = W(\omega; \mathbb{A})$ is characterized by the equivalence:

$$x_0 = \sum_{j=1}^m w_j \left(P(x_0^{1/2}) a_j \right)^{\frac{1}{2}}. \quad (3.2)$$

This tells us that $x_0 = W(\omega; \mathbb{A})$ is the unique solution on Ω of the nonlinear equation

$$x = \sum_{j=1}^m w_j \left(P(x^{1/2}) a_j \right)^{\frac{1}{2}}. \quad (3.3)$$

(i) By (3.2), we have

$$\begin{aligned} \alpha x_0 &= \sum_{j=1}^m w_j \left(\alpha^2 P(x_0^{1/2}) a_j \right)^{\frac{1}{2}} \\ &= \sum_{j=1}^m w_j \left(P(\alpha^{1/2} x_0^{1/2}) (\alpha a_j) \right)^{\frac{1}{2}} \\ &= \sum_{j=1}^m w_j \left(P(\alpha x_0)^{1/2} (\alpha a_j) \right)^{\frac{1}{2}}. \end{aligned}$$

This implies that αx_0 satisfies (3.3) for $\alpha a_1, \dots, \alpha a_m$. Hence, $W(\omega; \alpha\mathbb{A}) = \alpha W(\omega; \mathbb{A})$.

(ii) This is clear from the definition of $W(\omega; \mathbb{A})$ by (3.1).

(iii) Put $x_* = W(\omega^k; \mathbb{A}^k)$. From (3.2), we obtain that

$$\begin{aligned} x_* &= \left[\sum_{j=1}^m \frac{w_j}{k} \left(P(x_*^{1/2}) a_j \right)^{\frac{1}{2}} \right] + \dots + \left[\sum_{j=1}^m \frac{w_j}{k} \left(P(x_*^{1/2}) a_j \right)^{\frac{1}{2}} \right] \\ &= k \cdot \frac{1}{k} \left[\sum_{j=1}^m w_j \left(P(x_*^{1/2}) a_j \right)^{\frac{1}{2}} \right] \\ &= \sum_{j=1}^m w_j \left(P(x_*^{1/2}) a_j \right)^{\frac{1}{2}}, \end{aligned}$$

which implies that $x_* = W(\omega; \mathbb{A})$ by (3.2). □

Theorem 1.1 tells us the existence of $W(\omega; \mathbb{A})$. However, there does not exist a closed form of $W(\omega; \mathbb{A})$ in general. Only in two variable case, the exact formula of $W(\omega; \mathbb{A})$ is calculated in [14, Theorem 8.1] on Ω . Nonetheless, as in the case of positive definite matrices when the matrices A_j 's commute (see [4]), an analogous result can be derived in the symmetric cone Ω . To this end, we recall that elements x and y are said to operator commute if L_x and L_y commute, that is, $L_x L_y = L_y L_x$. It is known that x and y operator commute if and only if x and y have their spectral decompositions with respect to a common Jordan frame [6, Lemma X.2.2]. Equivalently, we say that x and y are simultaneously diagonalizable. In this case, x and y lie in an associative subalgebra of V . With this property, we obtain the following.

Theorem 3.2. (Consistency with scalars) *Assume that a_j 's operator commute. Then we have*

$$W(\omega; \mathbb{A}) = \left(\sum_{j=1}^m w_j a_j^{1/2} \right)^2.$$

Proof. Due to (3.2), it suffices to show that

$$\left(\sum_{j=1}^m w_j a_j^{1/2} \right)^2 = \sum_{j=1}^m w_j \left(P \left(\sum_{i=1}^m w_i a_i^{1/2} \right) a_j \right)^{\frac{1}{2}}. \tag{3.4}$$

Indeed, by the definition of the quadratic representation P , we have

$$\begin{aligned} P \left(\sum_{i=1}^m w_i a_i^{1/2} \right) a_j &= \left(2L_{\sum_{i=1}^m w_i a_i^{1/2}} L_{\sum_{i=1}^m w_i a_i^{1/2}} - L_{(\sum_{i=1}^m w_i a_i^{1/2})^2} \right) (a_j) \\ &= 2 \left(\sum_{i=1}^m w_i a_i^{1/2} \right) \left(\left(\sum_{i=1}^m w_i a_i^{1/2} \right) a_j \right) - \left(\sum_{i=1}^m w_i a_i^{1/2} \right)^2 a_j \\ &= 2 \left(\sum_{i=1}^m w_i a_i^{1/2} \right)^2 a_j - \left(\sum_{i=1}^m w_i a_i^{1/2} \right)^2 a_j \\ &= \left(\sum_{i=1}^m w_i a_i^{1/2} \right)^2 a_j, \end{aligned}$$

where third equality comes from the assumption that a_j 's operator commute so that they have a common Jordan frame and lie in an associative subalgebra of V as mentioned before. Thus, we get

$$\left(P \left(\sum_{i=1}^m w_i a_i^{1/2} \right) a_j \right)^{\frac{1}{2}} = \left(\left(\sum_{i=1}^m w_i a_i^{1/2} \right)^2 a_j \right)^{\frac{1}{2}} = \left(\sum_{i=1}^m w_i a_i^{1/2} \right) a_j^{1/2}. \tag{3.5}$$

The second equality is repeatedly obtained from the fact that a_j 's have a common Jordan frame. Summing up (3.5) on both sides yields that

$$\sum_{j=1}^m w_j \left(P \left(\sum_{i=1}^m w_i a_i^{1/2} \right) a_j \right)^{\frac{1}{2}} = \sum_{j=1}^m w_j \left(\left(\sum_{i=1}^m w_i a_i^{1/2} \right) a_j^{1/2} \right) = \left(\sum_{i=1}^m w_i a_i^{1/2} \right)^2,$$

which entails the claim (3.4), as desired. This completes the proof. □

Remark 3.3. In [4, 10] the authors just mentioned and quoted the consistency with scalars for the case of positive definite matrices which is a special case of the symmetric cone Ω . We provided a basic and elegant proof of Theorem 3.2 in Ω . So Theorem 3.2 extends the corresponding one in [4, 10] into the general setting of Ω .

In [8, Proposition 2.3], the unitary congruence invariancy of $W(\omega; \mathbb{A})$, $W(\omega; U\mathbb{A}U^*) = UW(\omega; \mathbb{A})U^*$ holds true when U is an unitary matrix and $\mathbb{A} = (A_1, \dots, A_m)$ is an m -tuple of positive definite matrices A_j 's. This can be generalized in Ω as follows:

Theorem 3.4. (Automorphism invariancy) $W(\omega; g(\mathbb{A})) = g(W(\omega; \mathbb{A}))$ for any Jordan automorphism g , where $g(\mathbb{A}) = (g(a_1), \dots, g(a_m))$.

Proof. Claim 1. $P(g(x)) = gP(x)g^{-1}$ for $x \in V$.
 First observe that $gL_xg^{-1} = L_{g(x)}$. Indeed, for $y \in V$, we have

$$(gL_xg^{-1})(y) = g(xg^{-1}(y)) = g(x)g(g^{-1}(y)) = g(x)y = L_{g(x)}(y).$$

Thus, we get

$$\begin{aligned} gP(x)g^{-1} &= g(2L_x^2 - L_{x^2})g^{-1} = 2gL_xL_xg^{-1} - gL_{x^2}g^{-1} \\ &= 2(gL_xg^{-1})(gL_xg^{-1}) - L_{g(x^2)} \\ &= 2L_{g(x)}^2 - L_{g(x)^2} = P(g(x)). \end{aligned}$$

Claim 2. $P(a\#b)a^{-1} = b$ for $a, b \in \Omega$.

In fact, a proof of this claim is presented implicitly in [17, Proposition 6 (i)]. For reader's convenience, we provide a detailed one.

$$\begin{aligned} P(a\#b)a^{-1} &= P(a\#b)P(a^{-1/2})e \\ &= (P(a)\#P(b))P(a^{-1/2})e \\ &= (P(a^{1/2})[P(a^{-1/2})P(b)P(a^{-1/2})]^{1/2}P(a^{1/2}))P(a^{-1/2})e \\ &= P(a^{1/2})[P(P(a^{-1/2})b)]^{1/2}e \\ &= P(a^{1/2})P([P(a^{-1/2})b]^{1/2})e \\ &= P(a^{1/2})P(a^{-1/2})b = b, \end{aligned}$$

where the second equality is from [16, Proposition 2.5], and the third, fourth and fifth ones come from Proposition 2.1.

Claim 3. $g(a\#b) = g(a)\#g(b)$ for $a, b \in \Omega$.

Clearly $g \in G(\Omega)$. Then we adopt the technique in [17, Proposition 6 (vi)]. By the Riccati equation (2.4), we have

$$P(g(a)\#g(b))g(a)^{-1} = g(b).$$

On the other hand, by Claims 1 and 2, we also obtain that

$$\begin{aligned} P(g(a\#b))g(a)^{-1} &= gP(a\#b)g^{-1}g(a^{-1}) \\ &= gP(a\#b)a^{-1} \\ &= g(b). \end{aligned}$$

As $g(a\#b)$ belongs to Ω , this implies that $g(a\#b)$ is a solution of the same Riccati equation $P(x)g(a)^{-1} = g(b)$. Hence, we get $g(a\#b) = g(a)\#g(b)$.

Claim 4. $W(\omega; g(\mathbb{A})) = g(W(\omega; \mathbb{A}))$.

Let $x_0 = W(\omega; \mathbb{A})$. Note that from [14, (5.2)] we have

$$x_0 = W(\omega; \mathbb{A}) \Leftrightarrow e = \sum_{j=1}^m w_j (a_j\#x_0^{-1}). \tag{3.6}$$

Since g is a Jordan automorphism, it follows from Claim 3 that

$$\begin{aligned} e = g(e) &= g\left(\sum_{j=1}^m w_j (a_j\#x_0^{-1})\right) = \sum_{j=1}^m w_j g(a_j\#x_0^{-1}) \\ &= \sum_{j=1}^m w_j (g(a_j)\#g(x_0^{-1})) \\ &= \sum_{j=1}^m w_j (g(a_j)\#g(x_0)^{-1}). \end{aligned}$$

This means that $g(x_0) = W(\omega; g(\mathbb{A}))$ by (3.6). Therefore, we conclude that

$$g(W(\omega; \mathbb{A})) = g(x_0) = W(\omega; g(\mathbb{A})).$$

This finishes the proof. □

Also we get two basic inequalities as below.

Theorem 3.5. (Arithmetic-Wasserstein median inequality)

$$W(\omega; \mathbb{A}) \leq \sum_{j=1}^m w_j a_j.$$

Proof. First, the map $f(x) = x^2$ on V is operator-convex in the sense that

$$f((1-t)a + tb) \leq (1-t)f(a) + tf(b) \text{ for all } t \in [0, 1], a, b \in V.$$

In fact,

$$\begin{aligned} (1-t)f(a) + tf(b) - f((1-t)a + tb) &= (1-t)a^2 + tb^2 - ((1-t)a + tb)^2 \\ &= t(1-t)(a-b)^2 \\ &\geq 0. \end{aligned}$$

Put $x_0 = W(\omega; \mathbb{A})$. Then by (3.2) and the operator-convexity of f , we get

$$\begin{aligned} x_0^2 &= \left(\sum_{j=1}^m w_j \left(P(x_0^{1/2}) a_j \right)^{\frac{1}{2}} \right)^2 \\ &\leq \sum_{j=1}^m w_j \left(P(x_0^{1/2}) a_j \right) \\ &= P(x_0^{1/2}) \left(\sum_{j=1}^m w_j a_j \right). \end{aligned}$$

Taking the order preserving linear operator $P(x_0^{-1/2})$ on the both sides yields that

$$\begin{aligned} x_0 &= P(x_0^{-1/2}) x_0^2 \\ &\leq P(x_0^{-1/2}) P(x_0^{1/2}) \left(\sum_{j=1}^m w_j a_j \right) \\ &= \sum_{j=1}^m w_j a_j, \end{aligned}$$

as desired. □

Remark 3.6. Theorem 3.5 is an extension of corresponding result in [4, 8] into the symmetric cone Ω .

Theorem 3.7. (Determinantal inequality)

$$\det W(\omega; \mathbb{A}) \geq \prod_{j=1}^m (\det a_j)^{w_j}.$$

Proof. Put $x_0 = W(\omega; \mathbb{A})$. As is well known, the function $g(x) = -\log \det x$ is strictly convex on Ω because the Hessian $\nabla^2 g(x) = P(x^{-1})$ is positive definite

[15]. Thus

$$\log \det \left(\sum_{j=1}^m w_j a_j \right) \geq \sum_{j=1}^m w_j \log \det a_j.$$

Appealing to [14, (5.2)] and the argument in [9], we get

$$\begin{aligned} 0 &= \log \det e \\ &= \log \det \left(\sum_{j=1}^m w_j (a_j \# x_0^{-1}) \right) \\ &\geq \sum_{j=1}^m w_j \log \det (a_j \# x_0^{-1}) \\ &= \frac{1}{2} \sum_{j=1}^m w_j \log(\det a_j)(\det x_0^{-1}) \\ &= \frac{1}{2} \sum_{j=1}^m \log(\det a_j)^{w_j} - \frac{1}{2} \log \det x_0 \\ &= \frac{1}{2} \log \left(\prod_{j=1}^m (\det a_j)^{w_j} \right) - \frac{1}{2} \log \det x_0, \end{aligned}$$

which entails the desired inequality. □

Remark 3.8. Theorem 3.7 is a generalization of [8, Proposition 2.3 (5)] under the circumstances of symmetric cone Ω .

The following theorem in [14] is concerned with the location of $W(\omega; \mathbb{A})$, which is sort of a sharpened extension of [10, Lemma 2.4] on Ω . For the sake of readers, we give a proof.

Theorem 3.9. *Let $\alpha := \min\{\lambda_{\min}(a_j) \mid j = 1, \dots, m\}$, $\beta := \max\{\lambda_{\max}(a_j) \mid j = 1, \dots, m\}$, where $\lambda_{\min}(a_j)$ and $\lambda_{\max}(a_j)$ denote the minimum and maximum eigenvalues of a_j , respectively. Then*

$$W(\omega; \mathbb{A}) \in [\alpha e, \beta e] = \{x \mid \alpha e \leq x \leq \beta e\}.$$

Proof. First note that $a_j \in [\alpha e, \beta e]$, $j = 1, \dots, m$. Define a mapping $F : [\alpha e, \beta e] \rightarrow [\alpha e, \beta e]$ by

$$F(x) = \sum_{i=1}^m w_j \left(P(x^{1/2}) a_j \right)^{\frac{1}{2}}.$$

To see that F is a self-map, let $x \in [\alpha e, \beta e]$. By the order preserving property of $P(x^{1/2})$, we have

$$\begin{aligned} \alpha^2 e &= \alpha(\alpha e) \\ &\leq \alpha x = \alpha P(x^{1/2})e = P(x^{1/2})(\alpha e) \\ &\leq P(x^{1/2})a_j \leq P(x^{1/2})(\beta e) = \beta P(x^{1/2})e = \beta x \\ &\leq \beta(\beta e) = \beta^2 e. \end{aligned}$$

Therefore,

$$\begin{aligned} \alpha e &= \sum_{j=1}^m w_j \alpha e = \sum_{j=1}^m w_j (\alpha^2 e)^{\frac{1}{2}} \\ &\leq \sum_{j=1}^m w_j \left(P(x^{1/2})a_j \right)^{\frac{1}{2}} (= F(x)) \\ &\leq \sum_{j=1}^m w_j (\beta^2 e)^{\frac{1}{2}} = \sum_{j=1}^m w_j \beta e = \beta e. \end{aligned}$$

By Brouwer’s fixed point theorem, there exists a point $x_0 \in [\alpha e, \beta e]$ such that $x_0 = F(x_0)$. It follows from (3.3) that x_0 is the unique solution of (3.3), that is, $x_0 = W(\omega; \mathbb{A})$. This completes the proof. \square

As noted in [4], the Wasserstein-harmonic mean inequality does not hold. However, a lower and an upper bound for $W(\omega; \mathbb{A})$ is derived in [8]. Using the same argument, we get an extension of [8, Theorem 3.4] in the symmetric cone Ω .

Theorem 3.10. *$W(\omega; \mathbb{A})$ satisfies the following order relation.*

$$2e - \sum_{j=1}^m w_j a_j^{-1} \leq W(\omega; \mathbb{A}) \leq \left(2e - \sum_{j=1}^m w_j a_j \right)^{-1}$$

as long as $2e - \sum_{j=1}^m w_j a_j$ has an inverse.

Proof. Let $x_0 = W(\omega; \mathbb{A})$. According to the arithmetic-geometric-harmonic mean inequalities [16, Theorem 2.8] in Ω , we have, for $j = 1, \dots, m$,

$$\left(\frac{a_j^{-1} + x_0}{2} \right)^{-1} \leq a_j \# x_0^{-1} \leq \frac{a_j + x_0^{-1}}{2}.$$

Hence, we obtain

$$\sum_{j=1}^m w_j \left(\frac{a_j^{-1} + x_0}{2} \right)^{-1} \leq e = \sum_{j=1}^m w_j (a_j \# x_0^{-1}) \leq \frac{1}{2} \sum_{j=1}^m w_j a_j + \frac{1}{2} x_0^{-1},$$

where the equality $e = \sum_{j=1}^m w_j(a_j \# x_0^{-1})$ comes from (3.6). From the second inequality, we get easily the upper bound for $x_0 = W(\omega; \mathbb{A})$. By the order-reversing property of the inversion [18, Lemma 11], taking inverse on the both sides of the first inequality together with the arithmetic-harmonic mean inequalities [16, Theorem 2.8] yields the following inequalities:

$$\begin{aligned} e &\leq \left[\sum_{j=1}^m w_j \left(\frac{a_j^{-1} + x_0}{2} \right)^{-1} \right]^{-1} \\ &\leq \sum_{j=1}^m w_j \left(\frac{a_j^{-1} + x_0}{2} \right) \\ &= \frac{1}{2} \sum_{j=1}^m w_j a_j^{-1} + \frac{1}{2} x_0. \end{aligned}$$

Solving this for $x_0 = W(\omega; \mathbb{A})$, we obtain the desired lower bound. This completes the proof. □

4. FINAL REMARK

As mentioned in the introduction, $\Phi_{\frac{1}{2}}(a, b)^{\frac{1}{2}}$ is not a metric on Ω [14]. Nonetheless, it shares many interesting properties with usual means as seen in the current work. In the theory of matrix mean, Karcher mean or multivariate geometric mean is the most significant one [10]. However, its symmetric cone version has not been investigated up to now except only in [13]. In [10], an order relation between the Wasserstein mean and Karcher mean by way of the power mean is presented. But, the power mean is not defined on Ω , yet. So with the theory development of Karcher mean and power mean on the symmetric cone Ω , a comparison study of the Wasserstein median with Karcher mean and power mean becomes an interesting future research.

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